

Combining (Second-Order) Graph-Based and Headed-Span-Based Projective Dependency Parsing

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Abstract

Graph-based methods, which decompose the score of a dependency tree into scores of dependency arcs, are popular in dependency parsing for decades. Recently, Yang and Tu (2022) propose a headed-span-based method that decomposes the score of a dependency tree into scores of headed spans. They show improvement over first-order graph-based methods. However, their method does not score dependency arcs at all, and dependency arcs are implicitly induced by their cubic-time algorithm, which is possibly sub-optimal since modeling dependency arcs is intuitively useful. In this work, we aim to combine graph-based and headed-span-based methods, incorporating both arc scores and headed span scores into our model. First, we show a direct way to combine with $O(n^4)$ parsing complexity. To decrease complexity, inspired by the classical head-splitting trick, we show two $O(n^3)$ dynamic programming algorithms to combine first- and second-order graph-based and headed-span-based methods. Our experiments on PTB, CTB, and UD show that combining first-order graph-based and headed-span-based methods is effective. We also confirm the effectiveness of second-order graph-based parsing in the deep learning age, however, we observe marginal or no improvement when combining second-order graph-based and headed-span-based methods¹.

1 Introduction

Dependency parsing is an important task in natural language processing. There are many methods to tackle projective dependency parsing. In this paper, we focus on two kinds of *global methods*: graph-based and headed-span-based methods. They both score all parse trees and globally find the highest

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¹Our code is publicly available at <https://github.com/sustcsonglin/span-based-dependency-parsing>

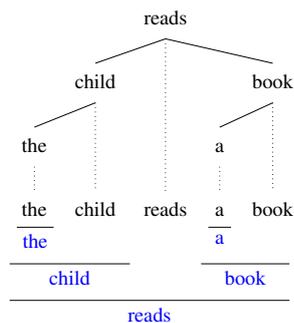


Figure 1: An example projective dependency parse tree with all its headed spans.

scoring tree. The difference between the two is how they score dependency trees. The simplest first-order graph-based methods (McDonald et al., 2005) decompose the score of a dependency tree into the scores of dependency arcs. Second-order graph-based methods (McDonald and Pereira, 2006) additionally score adjacent siblings, i.e., pairs of adjacent arcs with a shared head. There are many other higher-order graph-based methods (Carreras, 2007; Koo and Collins, 2010; Ma and Zhao, 2012). In contrast, the headed-span-based method (Yang and Tu, 2022) decomposes the score of a dependency tree into the scores of *headed spans*: in a projective tree, a headed span is a word-span pair such that the subtree rooted at the word covers the span in the surface order. Fig. 1 shows an example projective parse tree and all its headed spans.

First-order graph-based parsers have difficulties in incorporating sufficient subtree information before the deep learning era. Dozat and Manning (2017) show that first-order graph-based parsers with neural encoders and biaffine scorers can obtain high parsing accuracy. Falenska and Kuhn (2019) argue that powerful neural encoders—such as BiLSTMs (Hochreiter and Schmidhuber, 1997)—can encode rich subtree information implicitly, questioning the utility of high-order features. However, recent works found that high-order graph-based

methods can outperform first-order graph-based methods (Fonseca and Martins, 2020; Zhang et al., 2020; Wang and Tu, 2020) even with powerful neural encoders, indicating the insufficient subtree modeling of first-order graph-based methods. To encode more subtree information, in contrast to the line of work on higher-order parsing, Yang and Tu (2022) choose to model headed spans, which consist of all words within the corresponding subtrees. Thus their model can utilize more subtree information than first-order graph-based methods. However, to retain the cubic parsing complexity, they abandon modeling arcs as the parsing complexity would be $O(n^4)$ otherwise (§3.1). Modeling dependency arcs can capture the direct interactions between two words and is thus useful. Therefore, it is intuitively helpful to combine first-order graph-based and headed-span-based methods.

To decrease the parsing complexity, inspired by the classical head-splitting trick (Eisner, 1997), we propose to decompose the score of a headed span into two terms, assuming that the score of the left span boundary is independent of that of the right span boundary for each headword. This allows us to adapt the Eisner algorithm to parse in cubic time considering both arc and headed span scores (§3.2) at the cost of imposing a stronger independence assumption. More interestingly, we can also combine second-order graph-based and headed-span-based methods and need only cubic time to parse (§3.3), which would be much slower (to the best of our knowledge, $O(n^7)$) if we do not apply the head-splitting trick.

We conduct extensive experiments on PTB, CTB, and UD. We find that combining first-order graph-based and headed-span-based methods is effective, and applying the head-splitting trick or not result in a similar performance, thus it is more advantageous to apply this trick to enjoy a lower parsing complexity. We also confirm the effectiveness of second-order parsing in the deep learning age, however, we observe only marginal improvement or even no improvement when combining second-order graph-based and headed-span-based methods.

2 Scoring and Learning

2.1 Scoring

Given an input sentences x_1, \dots, x_n , we add <bos> (beginning of sentence) and <eos> (end of sentence) as x_0 and x_{n+1} . We apply mean-pooling at the last layer of BERT (Devlin et al., 2019)

(i.e., averaging all subwords embeddings) to obtain the word-level embeddings e_i ². Then we feed e_0, \dots, e_{n+1} into a three-layer BiLSTM network to get c_0, \dots, c_{n+1} , where $c_i = [f_i; b_i]$, f_i and b_i are the forward and backward hidden states of the last BiLSTM layer at position i respectively. We use $h_k = [f_k, b_{k+1}]$ to represent the k th boundary lying between x_k and x_{k+1} , and use $e_{i,j} = h_j - h_{i-1}$ to represent span (i, j) from position i to j inclusive where $1 \leq i \leq j \leq n$. Then we compute:

- $s_{i,j}^{\text{arc}}$ (for arc $x_i \rightarrow x_j$, used in all three models) by feeding c_i, c_j into a deep biaffine function (Dozat and Manning, 2017).
- $s_{i,j,k}^{\text{span}}$ (for headed-span (i, j, k) where x_k is the headword of span (i, j) , used in §3.1) by feeding $e_{i,j}, c_k$ to a deep biaffine function.
- $s_{k,i}^{\text{left}}$ and $s_{k,j}^{\text{right}}$ (for headed-span (i, j, k) , used in §3.2 and §3.3) by feeding c_k, h_{i-1} and c_k, h_j into two different deep biaffine functions.
- $s_{i,j,k}^{\text{sib}}$ (for adjacent siblings $x_i \rightarrow \{x_j, x_k\}$ with $k < j < i$ or $i < j < k$, used in §3.3) by feeding c_i, c_k, c_j into a deep triaffine function (Zhang et al., 2020).

2.2 Learning

We decompose the training loss L into $L_{\text{parse}} + L_{\text{label}}$. For L_{parse} , we use the max-margin loss (Taskar et al., 2004):

$$L_{\text{parse}} = \max(0, \max_{y' \neq y} (s(y') + \Delta(y', y) - s(y))) \quad (1)$$

where Δ measures the difference between the incorrect tree and gold tree y . Here we let Δ to be the Hamming distance (i.e., the total number of mismatches of arcs, sibling pairs, and (split) headed-spans depending on the setting). We use cost-augmented inference (Taskar et al., 2005) to compute Eq. 1, which involves the use of parsing algorithms described in the next section. We use the same label loss L_{label} in Dozat and Manning (2017).

3 Parsing

We use the parsing-as-deduction framework (Pereira and Warren, 1983) to describe the parsing algorithms of our proposed models.

²For some datasets requiring the use of gold POS tags, we additionally concatenate the POS tag embedding to obtain e_i

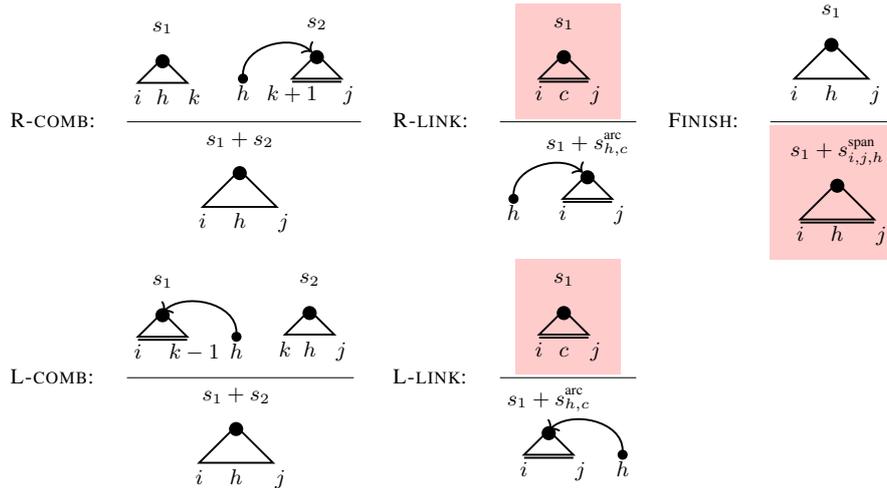


Figure 2: Deduction rules for our modified Eisner-Satta algorithm (Eisner and Satta, 1999). Our modifications are highlighted in red. All deduction items are annotated with their scores. Note that “finished” spans are marked by double underlines, whereas “unfinished” spans take the original triangle notations.

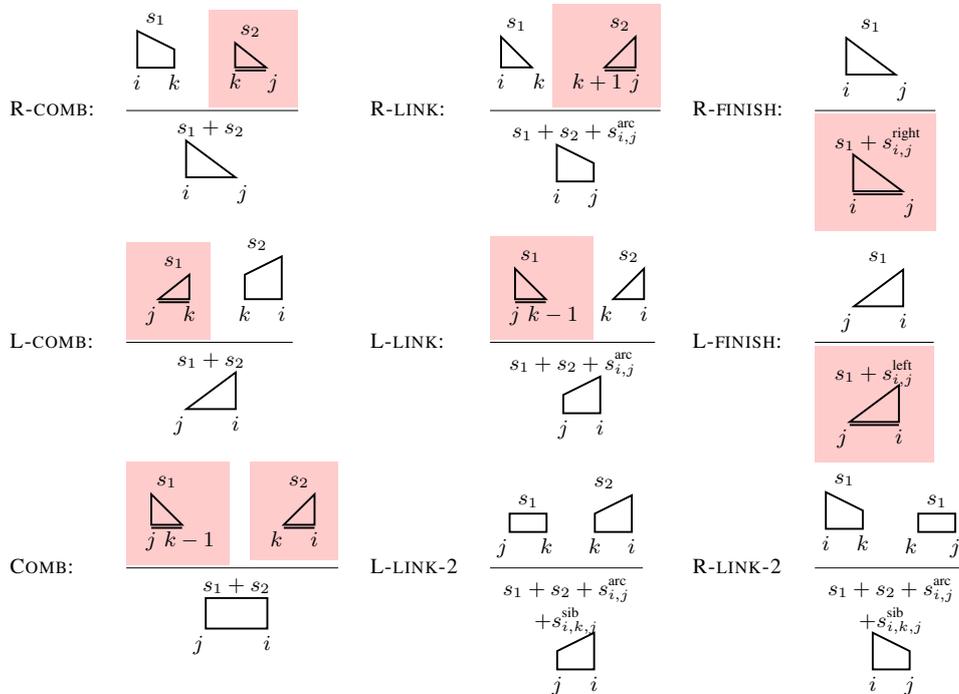


Figure 3: Deduction rules for our modified Eisner algorithm (Eisner, 1997) (first two rows) and its second-order extension (McDonald and Pereira, 2006) (all rows). Our modifications are highlighted in red. All deduction items are annotated with their scores. Note that “finished” (in)complete spans are marked by double underlines.

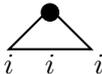
3.1 $O(n^4)$ modified Eisner-Satta algorithm

In this case, we combine first-order graph-based parsing and headed-span-based parsing. The score of a dependency tree y is defined as:

$$s(y) = \sum_{(x_i \rightarrow x_j) \in y} s_{i,j}^{\text{arc}} + \sum_{(l_i, r_i, x_i) \in y} s_{l_i, r_i, i}^{\text{span}}$$

We adapt the Eisner-Satta algorithm for parsing. The $O(n^4)$ Eisner-Satta algorithm (Eisner and

Satta, 1999, Sec. 3) is originally defined with bilocalized PCFGs. Still, we can leverage its dynamic programming substructure to incorporate both arc scores and headed span scores, similar to the relationship between span-based constituency parsing (Stern et al., 2017) and PCFG parsing. The ax-

iom items are  with initial score 0 and

the deduction rules are listed in Fig. 2. Unlike the original Eisner-Satta algorithm, we distinguish between “finished” spans and “unfinished” spans. An “unfinished” span can absorb a child span to form a larger span, while in a “finished” span, the headword has already generated all its children, so it cannot expand anymore and corresponds to a headed-span for the given headword. By explicitly distinguishing between “unfinished” spans and “finished” spans, we can incorporate headed-span scores s^{span} into parsing via the newly introduced rule FINISH. We then modify the rule L-LINK and R-LINK accordingly as only a “finished” span can be attached.

3.2 $O(n^3)$ modified Eisner algorithm

In order to decrease the parsing time complexity from $O(n^4)$ to $O(n^3)$, we decompose $s_{l,r,i}^{\text{span}}$ into two terms:

$$s(y) = \sum_{(x_i \rightarrow x_j) \in y} s_{i,j}^{\text{arc}} + \sum_{(l_i, r_i, x_i) \in y} (s_{i,l_i}^{\text{left}} + s_{i,r_i}^{\text{right}})$$

and modify the Eisner algorithm accordingly. The

axiom items are  and  with initial score 0 and the deduction rules are shown in the first two rows of Fig. 3. Similar to the case in the previous subsection, the original Eisner algorithm does not distinguish between “finished” complete spans and “unfinished” complete spans. An “unfinished” complete span can absorb another complete span to form a larger incomplete span, while a “finished” complete span has no more child in the given direction and thus cannot expand anymore. We introduce new rules L-FINISH and R-FINISH to incorporate the left or right span boundary scores respectively, and adjust other rules accordingly.

3.3 $O(n^3)$ modified second-order Eisner algorithm

We further enhance the model with adjacent sibling information:

$$s(y) = \sum_{(x_i \rightarrow x_j) \in y} s_{i,j}^{\text{arc}} + \sum_{(x_i \rightarrow \{x_j, x_k\}) \in y} s_{i,j,k}^{\text{sib}} + \sum_{(l_i, r_i, x_i) \in y} (s_{i,l_i}^{\text{left}} + s_{i,r_i}^{\text{right}})$$

where for each adjacent sibling part $x_i \rightarrow \{x_j, x_k\}$, x_j and x_k are two adjacent dependents of x_i .

Similarly, we modify the second-order extension of the Eisner algorithm (McDonald and Pereira,

2006) by distinguishing between “unfinished” and “finished” complete spans. The additional deductive rules for second-order parsing are shown in the last row of Fig. 3 and the length of the “unfinished” complete span is forced to be 1 in the rule L-LINK and R-LINK.

4 Experiments

4.1 Setup

We conduct experiments on in Penn Treebank (PTB) 3.0 (Marcus et al., 1993), Chinese Treebank (CTB) 5.1 (Xue et al., 2005) and 12 languages on Universal Dependencies (UD) 2.2. Implementation details are shown in appendix A. The reported results are averaged over three runs with different random seeds.

4.2 Main result

Table 1 and 2 show the results on UD, PTB and CTB respectively. We additionally reimplement Biaffine+20+MM by replacing the TreeCRF loss of Zhang et al. (2020) with the max-margin loss for fair comparison. We refer to our proposed models as 10+Span (§3.1), 10+Span+Headsplit (§3.2), and 20+Span+Headsplit (§3.3) respectively.

We draw the following observations. (1) Second-order information is still helpful even with powerful encoders (i.e., BERT). Biaffine+20+MM outperforms Biaffine+MM in almost all cases. (2) Combining first-order graph-based and headed-span-based methods is effective. Both 10+Span and 10+Span+Headsplit beat Biaffine+MM, Span in almost all cases; have similar performance to Biaffine+20+MM. (3) Decomposing the headed-span scores is useful. 10+Span+Headsplit has similar performance to 10+Span while manages to decrease the parsing complexity from $O(n^4)$ to $O(n^3)$. We speculate that powerful encoders mitigate the issue of independent scoring. (4) Combining second-order graph-based and headed-span-based methods has marginal effects. We speculate that the utility of adjacent sibling information and headed span information is overlapping.

4.3 Error analysis

Following (McDonald and Nivre, 2011), we plot UAS as a function of sentence length; F1 scores as functions of distance to root and dependency length

	bg	ca	cs	de	en	es	fr	it	nl	no	ro	ru	Avg
+BERT _{multilingual}													
<i>Biaffine+MM</i> [†]	90.30	94.49	92.65	85.98	91.13	93.78	91.77	94.72	91.04	94.21	87.24	94.53	91.82
<i>Span</i>	91.10	94.46	92.57	85.87	91.32	93.84	91.69	94.78	91.65	94.28	87.48	94.45	91.96
<i>1O+Span</i>	91.44	94.54	92.68	85.75	91.23	93.84	91.67	94.97	91.81	94.35	87.17	94.49	91.99
<i>1O+Span+HeadSplit</i>	91.46	94.53	92.63	85.78	91.25	93.77	91.91	94.88	91.59	94.18	87.45	94.47	91.99
<i>Biaffine+2O+MM</i>	91.58	94.48	92.69	85.72	91.28	93.80	91.89	94.88	91.30	94.23	87.55	94.55	92.00
<i>2O+Span+HeadSplit</i>	91.82	94.58	92.59	85.65	91.28	93.86	91.80	94.75	91.50	94.40	87.71	94.51	92.04
For reference													
<i>MFVI2O</i>	91.30	93.60	92.09	82.00	90.75	92.62	89.32	93.66	91.21	91.74	86.40	92.61	90.61

Table 1: Labeled Attachment Score (LAS) on twelve languages in UD 2.2. We use ISO 639-1 codes to represent languages. † means reported by Yang and Tu (2022). MFVI2O: Wang and Tu (2020). Span: Yang and Tu (2022).

	PTB		CTB	
	UAS	LAS	UAS	LAS
+BERT _{large}				
<i>Biaffine+MM</i> [†]	97.22	95.71	93.18	92.10
<i>Span</i>	97.24	95.73	93.33	92.30
<i>1O+Span</i>	97.26	95.68	93.56	92.49
<i>1O+Span+HeadSplit</i>	97.30	95.77	93.46	92.42
<i>Biaffine+2O+MM</i>	97.28	95.73	93.42	92.34
<i>2O+Span+HeadSplit</i>	97.23	95.69	93.57	92.47
For reference				
<i>MFVI2O</i>	96.91	95.34	92.55	91.69
<i>HierPtr</i>	97.01	95.48	92.65	91.47
+XLNet _{large}				
<i>HPSG</i> ^b	97.20	95.72	-	-
<i>HPSG+LAL</i> ^b	97.42	96.26	94.56	89.28

Table 2: Results on PTB and CTB. ^b denotes use of additional constituency tree data and thus not comparable to our work. † denotes results reported by Yang and Tu (2022). HPSG: Zhou and Zhao (2019); HPSG+LAL: Mrini et al. (2020); HierPtr: Fernández-González and Gómez-Rodríguez (2021).

on the CTB test set. We also follow (Yang and Tu, 2022) to plot F1 score as a function of span length.

Fig. 4a shows that compared with first-order graph-based method (i.e., Biaffine+MM), headed-span-based method (i.e., Span) has an advantage in predicting long sentences (of length > 30) but has a difficulty in predicting short sentences (of length < 20). By combining first-order graph-based and headed-span-based methods, 1O+Span can predict both short and long sentences correctly. It achieves the best results for all sentence length intervals except for 30-39. Fig. 4b shows that 1O+Span achieves the best performance for almost all cases, indicating its strong ability in predicting complex subtrees with high tree depth. Also, Fig. 4c shows that 1O+Span achieves the best performance for almost all cases, especially for dependency arcs of length ≥ 6 , showing its ability in capturing long-range dependencies. Fig. 4d shows

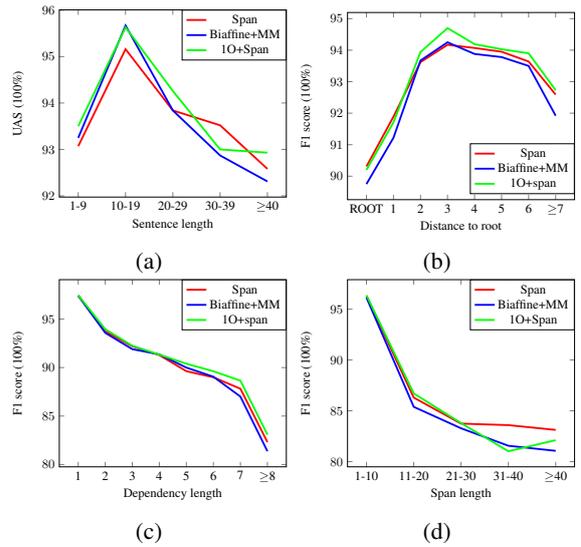


Figure 4: Error analysis on the CTB test set.

that Span has the best performance in identifying the range of a subtree, although it has no direct relation to the final performance.

5 Conclusion

In this paper, we have studied different ways to combine graph-based and headed-span-based methods. We found that applying the head-splitting trick can retain the cubic parsing complexity and meanwhile improve parsing performance when combining first-order graph-based and headed-span-based methods. We also confirmed the effectiveness of second-order parsing, however, we observed marginal or no improvement when combining it with the headed-span-based method.

Acknowledgments

We thank the anonymous reviewers for their constructive comments. This work was supported by the National Natural Science Foundation of China (61976139).

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A Implementation details

We use "bert-large-cased" for PTB, "bert-base-chinese" for CTB, and "bert-multilingual-cased" for UD. We set the hidden size of BiLSTM to 1000. We set the hidden size of biaffine functions to 600/300 for spans,arcs/labels. We set the hidden size of triaffine functions to 400. We add a dropout layer after the embedding layer, LSTM layers, and MLP layers with dropout rate 0.33. We use Adam (Kingma and Ba, 2015) as the optimizer with $\beta_1 = 0.9, \beta_2 = 0.9$ to train our model for 10 epochs with gradient clipping of 5. The maximal learning rate is $lr = 5e - 5$ for BERT and $lr = 25e - 5$ for other components. We linearly warmup the learning rate to their maximal value for the first epoch and gradually decay them to zero for the rest of the epochs. We batch sentences of similar lengths so that the token number is 4000 for each batch.