# **Cutting-Edge Tutorial: Complex Reasoning over Natural Language**

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# **1** Tutorial Overview

Teaching machines to reason over texts has been a long-standing goal of natural language processing (NLP). To this end, researchers have designed a diverse set of complex reasoning tasks that involve compositional reasoning (Geva et al., 2021; Trivedi et al., 2022), knowledge retrieval (Yang et al., 2018; Kwiatkowski et al., 2019), grounding (Budzianowski et al., 2018; Xie et al., 2022; Shi et al., 2021), commonsense reasoning (Talmor et al., 2021a; Lin et al., 2020), etc.

A standard choice for building systems that perform a desired type of reasoning is to fine-tune a pretrained language model (LM) on specific downstream tasks. However, recent research has demonstrated that such a straightforward approach is often brittle. For example, Elazar et al. (2021) and Branco et al. (2021) show that, on questionanswering (QA) tasks, similar performance can be achieved with questions removed from the inputs. Min et al. (2019), Chen and Durrett (2019), and Tang et al. (2021) show that models trained on multi-hop QA do not generalize to answer singlehop questions. The reasoning capabilities of these models thus remain at a surface level, i.e., exploiting data patterns. Consequently, augmenting LMs with techniques that make them robust and effective becomes an active research area.

We will start the tutorial by providing an overview of complex reasoning tasks where the standard application of pretrained language models fails (in Sec 2). This tutorial then reviews recent promising directions for tackling these tasks (in Sec 3). Specifically, we focus on the following groups of approaches that explicitly consider problem structures: (1) knowledgeaugmented methods, where the knowledge is either incorporated during fine-tuning or pretraining; (2) few-shot prompting methods, which effectively guide the models to follow instructions; (3) neuro-symbolic methods, which produce explicit intermediate representations; and, (4) rationalebased methods, one of the most popular forms of the neuro-symbolic methods, which highlight subsets of input as explanations for individual model predictions. The tutorial materials are online at https://wenting-zhao.github. io/complex-reasoning-tutorial.

#### 2 Problem Introduction

We will start with NLP tasks that require reasoning over multiple pieces of information in a provided context, covering various reasoning skills such as fact composition, mathematical reasoning, inferring semantic structures, and reasoning about entities (Yang et al., 2018; Yu et al., 2018; Budzianowski et al., 2018; Dua et al., 2019; Ho et al., 2020; Dasigi et al., 2019; Cobbe et al., 2021; Trivedi et al., 2022). Then, we will discuss benchmarks that combine multiple sources of information (i.e., modalities), e.g., paragraphs, tables, and images (Chen et al., 2020b; Talmor et al., 2021b; Pasupat and Liang, 2015; Chen et al., 2020a).

We will present open-domain setups where external knowledge should be integrated into the reasoning process (Geva et al., 2021; Onoe et al., 2021; Ferguson et al., 2020; Talmor and Berant, 2018). In addition, we will review tasks that require commonsense reasoning (Talmor et al., 2021a; Rudinger et al., 2020; Sap et al., 2019; Saha et al., 2021).

We will conclude this part by highlighting key practices for dataset creation, that increase data diversity and minimize annotation biases and reasoning shortcuts (Bartolo et al., 2020; Khot et al., 2020; Geva et al., 2019; Parmar et al., 2022).

#### **3** Approaches

(1a) Knowledge-Augmented Fine-Tuning Tackling complex reasoning problems that require commonsense knowledge and entity-centric facts can

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benefit from access to external knowledge sources. How to incorporate knowledge during fine-tuning has thus been extensively studied. A general method is to retrieving knowledge facts relevant to given situations (e.g., questions) and fusing them with an LM-based neural module. External knowledge can be categorized into three forms: structured (e.g., knowledge graphs like Concept-Net (Speer et al., 2017)), unstructured (e.g., knowledge corpora such as Wikipedia and GenericsKB (Bhakthavatsalam et al., 2020)), and instancebased (i.e., annotated examples).

In this section, we will cover methods for these three forms of knowledge in a variety of reasoning problems. For structured knowledge, KagNet (Lin et al., 2019) is a typical method that focuses on fusing retrieved subgraphs from ConceptNet for fine-tuning LMs to perform commonsense reasoning. Follow-up works include MHGRN (Feng et al., 2020), QA-GNN (Yasunaga et al., 2021), and GreaseLM (Zhang et al., 2022b). For unstructured knowledge, we will introduce methods that encode a large knowledge corpus as neural memory modules to support knowledge retrieval for reasoning. We will start with DPR (Karpukhin et al., 2020), one of the most popular methods that embed Wikipedia as a dense matrix of fact embeddings. Then, we will cover DrKIT (Dhingra et al., 2020), which improves multi-hop reasoning ability by encoding sparse entity mentions. Additionally, we introduce DrFact (Lin et al., 2021), a fact-level extension for DrKIT that focuses on commonsense reasoning. For instance-based knowledge, a promising direction, we will also introduce methods such as RACo (Yu et al., 2022b), ReCross (Lin et al., 2022), and QEDB (Chen et al., 2022b), which aim to exploit annotated examples to enhance reasoning.

(1b) Knowledge-Augmented Pretraining. Pretraining performs self-supervised learning of representations from large-scale data, which holds the potential to help a broader range of downstream tasks. We will review recent efforts to incorporate knowledge and reasoning abilities into LMs during pretraining. We first discuss retrieval-augmented pretraining (Guu et al., 2020; Lewis et al., 2020a; Borgeaud et al., 2021; Yasunaga et al., 2022b), which retrieves relevant documents from an external memory and feeds them to the model as an additional input. This helps not only knowledgeintensive tasks but also some reasoning-intensive tasks because the models learn to process multiple documents for multi-hop reasoning (Yasunaga et al., 2022b). We then discuss works that integrate structured knowledge bases/graphs. For example, some use knowledge graphs to make additional pretraining objectives for LMs (Xiong et al., 2020; Shen et al., 2020; Wang et al., 2021; Liu et al., 2021; Yu et al., 2022a; Ke et al., 2021); others retrieve and feed entity or knowledge graph information as a direct input to the model (Zhang et al., 2019; Rosset et al., 2020; Liu et al., 2020; Sun et al., 2021; Agarwal et al., 2021; Sun et al., 2020; He et al., 2020; Yasunaga et al., 2022a). Recent works show that these retrieved knowledge graphs can provide LMs with scaffolds for performing complex reasoning over entities, such as logical and multi-hop reasoning (Yasunaga et al., 2022a).

(2) Few-Shot Prompting Approaches. The rise of large pretrained LMs, such as GPT-3 (Brown et al., 2020), OPT (Zhang et al., 2022a), and PaLM (Chowdhery et al., 2022), has unlocked the potential of few-shot prompting methods for a wide range of reasoning tasks. However, despite their strengths, these LMs in the few-shot prompting mode have peculiar failure modes, especially when it comes to complex reasoning tasks (Marcus, 2022). Further, the prompt has to be designed carefully, and it has been shown that seemingly innocuous changes to the prompt (e.g., order of examples or the format of text) can drastically impact the performance (Le Scao and Rush, 2021; Mishra et al., 2021). In response, several techniques have been developed to make few-shot prompting methods to be less susceptible to the exact prompt choice. This section will cover both a high-level overview of few-shot prompting and introduce specific classes of techniques that can further improve the few-shot prompting methods on complex reasoning tasks.

First, we will introduce prompt-design techniques like chain-of-thought prompting (Wei et al., 2022b) and least-to-most prompting (Wei et al., 2022c), which encourage an LM to generate reasoning steps as part of the solution, helping with problem decomposition and enhanced reasoning. Next, we will cover techniques that change the prompt dynamically for each input query. The methods covered in this part include selecting the training examples in the prompt (Liu et al., 2022a) and editing the prompt to incorporate feedback received on a similar-input (Madaan et al., 2022a).

Finally, we will cover techniques that lever-

age code-generation models for complex reasoning tasks. Representative techniques in this part will cover i) the use of code-generation model for structured commonsense reasoning (Madaan et al., 2022b), ii) algorithmic reasoning by expanding detailed instructions in the prompt (Zhou et al., 2022), and iii) generating chain-of-thought styled reasoning chains in Python code to tackle complex symbolic reasoning tasks (Gao et al., 2022).

(3) Neuro-Symbolic Approaches. Although performance on NLP tasks is dominated by neural *endto-end* systems that directly map inputs to outputs (Devlin et al., 2019; Raffel et al., 2020), these approaches lack interpretability and robustness. *Symbolic* approaches, on the other hand, produce explicit intermediate reasoning trajectories such as logical forms, reasoning paths, or program code, which might then be executed to derive a final output (Zettlemoyer and Collins, 2005; Chen et al., 2019b, *i.a.*). Compared to both end-to-end and chain-of-thought methods (Wei et al., 2022a, *i.a.*), the reasoning processes produced by the symbolic methods are interpretable, and the resulting execution makes them more robust to input changes.

Researchers (Andreas et al., 2016; Liang et al., 2017; Gupta et al., 2019; Khot et al., 2021; Zhu et al., 2022; Cheng et al., 2022; Gao et al., 2022; Schick et al., 2023, i.a.) also propose to combine neural modules and symbolic components to leverage advantages of both approaches. More specifically, Neural-Symbolic Machines (Liang et al., 2017) adopt a seq-to-seq model to generate programs and a Lisp interpreter that performs program execution. (Chen et al., 2019b) designs a domainspecific language for question answering over text. BREAK (Wolfson et al., 2020) proposes a meaningful representation, QDMR, that decomposes the question into multiple steps. Thorne et al. (2021) propose a mixed pipeline of logic forms and neural networks, aiming at solving the scale problem and noisy, messy data over a natural language database.

Another stream of works called neural module networks (Andreas et al., 2016; Das et al., 2018; Gupta et al., 2019) propose to generate symbolic programs that are further softly executed by the corresponding neural modules. Khot et al. (2021) propose text module networks to solve complex tasks by decomposing them into simpler ones solvable by existing QA models and a symbolic calculator. However, most prior neural-symbolic methods require the elaborate human design of the symbolic language and the calibration of corresponding neural modules to tackle problems in a specific domain with large training data. Recently, Cheng et al. (2022) propose Binder, a new neural-symbolic system based on GPT-3 Codex (Chen et al., 2021) that supports *flexible* neural module calls that will enable *higher coverage* for the symbolic language, while only requiring *few annotations*. Also, Gao et al. (2022) introduce PAL, a new method based on Codex that generates executable programs as the intermediate reasoning steps and leverages a Python interpreter to derive final answers.

This section will begin by discussing the highlevel comparison among the end-to-end, chain-ofthought, symbolic (e.g., semantic parsing), and neural-symbolic approaches. We will then move to provide a high-level overview of different neuralsymbolic approaches. In this part, we will mainly focus on neural-symbolic approaches with LMs. Finally, we will cover recent techniques incorporating GPT-3 Codex in neural-symbolic approaches.

(4) **Rationale-Based Approaches.** Rationalebased approaches extract parts of input to be *reasoning certificates*, offering end users a way to evaluate the trustworthiness of the predictions. Based on reasoning types, rationales of different granularity are identified – they can be tokens, sentences, or documents (DeYoung et al., 2020; Kwiatkowski et al., 2019). NLP systems can benefit from rationales in several ways. Yang et al. (2018) show that providing rationales as additional supervision improves models' capacity to perform multi-hop reasoning. More recently, Chen et al. (2022a) demonstrate the potential of using such methods to build more robust NLP systems.

Existing methods for extracting rationales often require supervision; they either apply multi-task loss functions (Joshi et al., 2020; Groeneveld et al., 2020), or design specialized network architectures to incorporate inductive biases (Tu et al., 2019; Fang et al., 2020). Because rationale annotations are expensive to collect and not always available, recent effort has been devoted to semi-supervised and unsupervised methods. Chen et al. (2019a) leverage entity taggers to build silver reasoning chains used for rationale supervision. Glockner et al. (2020) and Atanasova et al. (2022) design unsupervised objectives for extracting rationales in multi-hop QA systems. Finally, latent-variable approaches are a natural fit for unsupervised learning (Lei et al., 2016; Zhou et al., 2020; Lewis et al., 2020b). By modeling rationales as a latent variable, it provides a principled way to explicitly impose constraints in the reasoning process.

### 3.1 Schedule

- 1. Introduction & Motivations (15 min.)
- 2. Benchmarks & Evaluation (25 min.)
- 3. Knowledge-augmented Fine-tuning (25 min.)
- 4. Knowledge-augmented Pretraining (25 min.)
- 5. Break (30 minutes)
- 6. Neuro-Symbolic Approaches (25 min.)
- 7. Few-shot Prompting Approaches (25 min.)
- 8. Rationale-Based Approaches (25 min.)
- 9. Concluding discussion (15 min.)

# 4 Instructor information

**Wenting Zhao** is a Ph.D. student in Computer Science at Cornell University. Her research focuses on the intersection of reasoning and NLP. She is especially interested in developing explainable methods for complex reasoning problems.

**Mor Geva** is a postdoctoral researcher, now at Google Research and previously at the Allen Institute for AI. Her research focuses on debugging the inner workings of black-box NLP models, to increase their transparency, control their operation, and improve their reasoning abilities. She is organizing the next edition of the Workshop on Commonsense Reasoning and Representation.

**Bill Yuchen Lin** is a postdoctoral researcher at the Allen Institute for AI. He obtained his Ph.D. at USC advised by Prof. Xiang Ren. His research goal is to teach machines to think, talk, and act with commonsense knowledge and commonsense reasoning ability as humans do. He was a co-author of the tutorial on *Knowledge-Augmented Methods for Natural Language Processing* and the *Workshop on Commonsense Representation and Reasoning* at ACL 2022.

**Michihiro Yasunaga** is a Ph.D. student in Computer Science at Stanford University. His research interest is in developing generalizable models with knowledge, including commonsense, science, and reasoning abilities. He co-organized the Workshop on Structured and Unstructured Knowledge Integration (SUKI) at NAACL 2022.

**Aman Madaan** is a Ph.D. student at the School of Computer Science, Carnegie Mellon University. He is interested in large language models, feedback-driven generation, and the intersection of code generation and natural language reasoning. He helped organize the 1st and 2nd Workshops on Natural Language Generation, Evaluation, and Metrics (GEM) at ACL 2021 and EMNLP 2022.

**Tao Yu** is an assistant professor of computer science at The University of Hong Kong. He completed his Ph.D. at Yale University and was a post-doctoral fellow at the University of Washington. He works on executable language understanding, such as semantic parsing and code generation, and large LMs. Tao is the recipient of an Amazon Research Award. He co-organized multiple workshops in Semantic Parsing and Structured and Unstructured Knowledge Integration at EMNLP and NAACL.

### **5** Other Information

**Reading List** Rogers et al. (2022); Storks et al. (2019); Liu et al. (2022b); Lyu et al. (2022); Wiegreffe and Marasović (2021); Andreas et al. (2016); Cheng et al. (2022); Gao et al. (2022).

**Breadth** We estimate that approximately 30% of the tutorial will center around work done by the presenters. This tutorial categorizes promising approaches for complex reasoning tasks into several groups, and each of this group includes a significant amount of other researchers' works.

**Diversity considerations** The challenges of building robust and generalizable NLP systems exist in every language. The methods covered in this tutorial are language-agnostic and can be extended to non-English context.

For instructors, they all have different affiliations (i.e., Cornell, Google, Stanford, USC, HKU, and CMU). They are three PhD students, two postdoctoral researchers, and one assistant professor; two of the instructors are female.

Prerequisites Following knowledge is assumed:

- Machine Learning: basic probability theory, supervised learning, transformer models
- NLP: Familiarity with pretrained LMs; standard NLP tasks such as question answering, text generation, etc.

# **Estimated number of participants** 150. **Preferable venue** ACL.

**Targeted audience** Researchers and practitioners who seek to develop a background in complex reasoning tasks where standard application of pretrained language models fail. By providing a systematic overview of recent promising approaches for these tasks, this tutorial hopefully reveals new research opportunities to the audience.

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