

On Eliciting Syntax from Language Models via Hashing

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Abstract

Unsupervised parsing, also known as grammar induction, aims to infer syntactic structure from raw text. Recently, binary representation has exhibited remarkable information-preserving capabilities at both lexicon and syntax levels. In this paper, we explore the possibility of leveraging this capability to deduce parsing trees from raw text, relying solely on the implicitly induced grammars within models. To achieve this, we upgrade the bit-level CKY from zero-order to first-order to encode the lexicon and syntax in a unified binary representation space, switch training from supervised to unsupervised under the contrastive hashing framework, and introduce a novel loss function to impose stronger yet balanced alignment signals. Our model¹ shows competitive performance on various datasets, therefore, we claim that our method is effective and efficient enough to acquire high-quality parsing trees from pre-trained language models at a low cost.

1 Introduction

Grammars form the backbone of languages, providing the essential framework that dictates how lexicons are arranged to convey meaning. Understanding and generating language heavily relies on grasping these latent structures. Unsupervised parsing, which aims to deduce sentence structure without relying on costly manually annotated treebanks, has been widely studied in academia. However, despite its importance, advancements have been slow due to the intrinsic complexity of this task. Nowadays, addressing these challenges becomes even more crucial for further exploring the capabilities of large language models.

Word embedding and language model techniques (Mikolov et al., 2013a,b; Radford, 2018; Devlin et al., 2019) have shown that training models to predict tokens in specific contexts is remark-

¹<https://github.com/speedcell14/parserker>

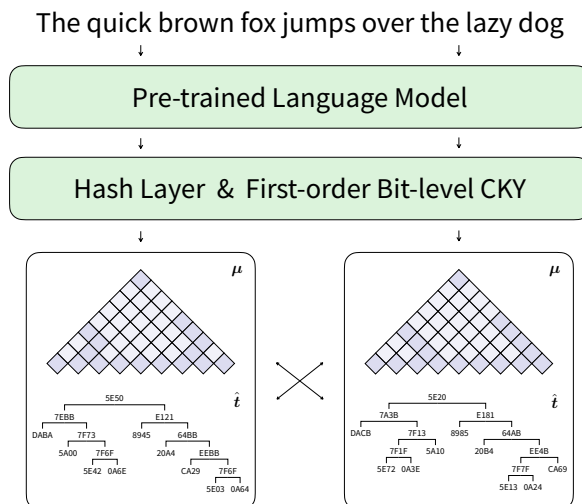


Figure 1: The model architecture. The hash layer produces scores of all spans, and the following first-order bit-level CKY (§3.1) returns marginal probabilities μ and predicts the most probable trees \hat{t} . Sentences are fed into the network twice. We select span marginal probabilities from one pass according to the predicted trees from the other pass, and perform contrastive hashing (§3.2, §3.3) on their corresponding score and code vectors. The purple cells represent the marginal probabilities, and the dark purple indicate the selected ones.

ably effective in implicitly capturing lexical features. A well-known example is the captured lexical relationship of *king - man + woman = queen*. As one of the most widely accepted explanations for this phenomenon, the distributional hypothesis (Harris, 1954; Mikolov et al., 2013a,b) suggests this is because tokens appearing in similar contexts tend to be assigned similar meanings. Specifically, similar contexts achieve this by placing tokens in analogous syntactic structures. This phenomenon naturally prompts us to consider whether there is a representation learning method that can explicitly encode both lexical and syntactic information in a unified format, making it possible to capture syntactic structures as well as lexical relationships by training language models solely with conventional

conditional token prediction procedures.

Fortunately, the recently proposed binary representation meets these requirements perfectly. Wang et al. (2023) proposed a binary representation that bridges the gap between the continuous nature of deep learning and the discrete intrinsic property of natural languages. Instead of directly applying contrastive learning on the high-dimensional continuous hidden states of pre-trained language models, Wang et al. (2023) project them as K -dimensional score vectors. These scores can easily be binarized into K -bit codes, and token-level contrastive learning is applied among these scores and their binarized codes. They demonstrate that lexical information can be properly preserved within only 24 bits. Following this, Wang and Utiyama (2024) additionally take spans on the target parsing trees into consideration. They use marginal probabilities to construct a novel similarity function that reflects not only lexical information but also the boundary of each span, and then perform contrastive hashing across spans rather than tokens. In their supervised parsing experiments, they show the effectiveness of the structured binary representation by achieving comparable performance to conventional parsers.

Although in the supervised settings, Wang and Utiyama (2024) achieves satisfactory results, we found that for unsupervised settings, their model is insufficient to induce meaningful parsing trees. In this paper, we aim to elicit constituency parsers from pre-trained language models without training them on annotated treebanks. We analyze the existing issues of their structured binary representation and explore the possibility of further enhancing the unified information-preserving capability. To achieve this, we upgrade the bit-level CKY module from zero-order (§2.1) to first-order (§3.1) to integrate lexicon and syntax in a unified format, convert parsing from supervised (§2.2) to unsupervised (§3.2), and propose a novel objective function (§3.3) to impose stronger yet balanced alignment signals. Besides, we also discuss how the learning objective of contrastive hashing aligns with the target of parsing. This provides an explanation (§3.2) different from the distributional hypothesis and explains why our training leads to syntactic structures rather than other structures. Experiments show that our models achieve competitive performance and indicate that acquiring high-quality syntactic annotations at a low cost is becoming practicable. We refer to our parser as Parserker2, following the original Parserker (Wang and Utiyama, 2024).

2 Background

2.1 Zero-order Constituency Parsing

Given sequence w_1, \dots, w_n , constituency parser returns the most probable binary-branching parsing tree $\mathbf{t} = \{\langle l_i, r_i, y_i \rangle\}_{i=1}^{2n-1}$, which is represented as a list of labeled spans indicating constituents at different hierarchies. Where l_i and r_i refer to the left and right boundaries of the i -th constituent, and $y_i \in \mathcal{Y}$ stands for its assigned label. Previous models (Kitaev and Klein, 2018; Yu et al., 2020; Zhang et al., 2020) commonly employ encoders to transform inputs into hidden states $\mathbf{h}_1, \dots, \mathbf{h}_n$ first, use classifiers to predict span scores $g(l, r, y)$ and tree scores $g(\mathbf{t})$, and then normalize them among all valid trees to obtain tree probability $p(\mathbf{t})$. Training and inference stages aim at maximizing the probabilities of target trees and searching trees with the maximal probabilities $\hat{\mathbf{t}}$, respectively.

$$g(\mathbf{t}) = \sum_{\langle l, r, y \rangle \in \mathbf{t}} g(l, r, y) \quad (1)$$

$$p(\mathbf{t}) = \frac{\exp g(\mathbf{t})}{Z \equiv \sum_{\mathbf{t}' \in \mathcal{T}} \exp g(\mathbf{t}')} \quad (2)$$

$$\hat{\mathbf{t}} = \{\langle l_i, r_i, y_i \rangle\}_{i=1}^{2n-1} \leftarrow \arg \max_{\mathbf{t} \in \mathcal{T}} p(\mathbf{t}) \quad (3)$$

Apart from being used to normalize probabilities of trees, the log partition term Z , which stands for the total scores of all valid constituency trees, can also be used to compute span marginal probabilities. As Eisner (2016) mentioned, computing the partial derivative of the log partition with respect to span scores yields marginal probabilities efficiently.

$$\mu(l, r, y) = \frac{\partial \log Z}{\partial g(l, r, y)} \quad (4)$$

Intuitively speaking, marginal probability reflects the joint probability of selecting tokens w_l, \dots, w_r as a constituent with label y assigned to it. If a span is not likely to be selected, its marginal probability will not be high regardless of its label. Therefore, similar to hidden states, marginal probabilities are considered a format containing not only lexical but also syntactic features. Unlike hidden states, these marginal probabilities explicitly correspond to the specific boundaries and labels of spans in parsing trees globally normalized under the CKY framework, whereas hidden states implicitly preserve this information in a high-dimensional, human-unreadable format.

Recently, Wang and Utiyama (2024) extended constituency parsers by replacing discrete labels $y \in \mathcal{Y}$ with binary codes $\mathbf{c} \in \{-1, +1\}^K$. In their approach, the code-level scores $g(l, r, \mathbf{c})$ are obtained by summing up bit-level scores $g_k(l, r, c^k)$.

$$g(\mathbf{t}) = \sum_{\langle l, r, \mathbf{c} \rangle \in \mathbf{t}} g(l, r, \mathbf{c}) \quad (5)$$

$$g(l, r, \mathbf{c}) = \sum_{k=1}^K g_k(l, r, c^k) \quad (6)$$

Moreover, to compute these bit-level scores, they retained the one-head-one-bit design of Wang et al. (2023) and employed a multi-head attention module to predict the score of being assigned +1.

$$g_k(l, r, +1) = \frac{(\mathbf{W}_k^Q \mathbf{h}_l)^\top (\mathbf{W}_k^K \mathbf{h}_r)}{\sqrt{d_k}} \quad (7)$$

$$g_k(l, r, -1) = 0 \quad (8)$$

Where $\mathbf{W}_k^Q, \mathbf{W}_k^K \in \mathbb{R}^{\lceil \frac{d}{K} \rceil \times d}$ are the query and key matrices used to produce the k -th bit. They assign a score of 0 for the -1 case and extend the marginal probability and decoding to the bit level.

$$\mu_k(l, r, c^k) = \frac{\partial \log Z}{\partial g_k(l, r, c^k)} \quad (9)$$

$$\hat{\mathbf{t}} = \{\langle l_i, r_i, \mathbf{c}_i \rangle\}_{i=1}^{2n-1} \leftarrow \arg \max_{\mathbf{t} \in \mathcal{T}} p(\mathbf{t}) \quad (10)$$

2.2 Supervised Contrastive Hashing

To perform contrastive learning, Wang et al. (2023) and Wang and Utiyama (2024) define their similarity functions in a similar manner, both first binarize one input and then calculate the similarity between the continuous one and the binarized one. However, the former binarizes scores via taking their signs, while the latter leans bits towards the sides with larger marginal probabilities.

$$\mathbf{c} = [c^1, \dots, c^K] \in \{-1, +1\}^K \quad (11)$$

$$c^k = \begin{cases} +1 & \mu_k(l, r, +1) > \mu_k(l, r, -1) \\ -1 & \text{otherwise} \end{cases}$$

As mentioned above, marginal probabilities contain both label and structural information. To impose supervision on lexicon and syntax simultaneously by leveraging this property, they proposed defining the novel similarity as the average of bit-level marginal probabilities of the i -th constituent with the binary label of j -th constituent.

$$s(i, j) = \frac{1}{K} \sum_{k=1}^K \mu_k(l_i, r_i, c_j^k) \quad (12)$$

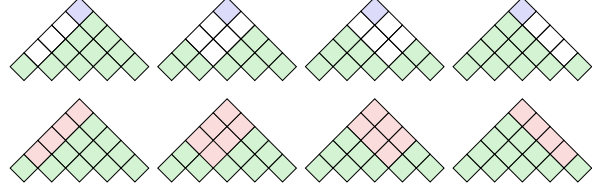


Figure 2: Charts of the zero-order (above §2.1) and the first-order parsing (below §3.1). At this time step, zero-order parsers separately determine the splitting positions on the left and right children and predict labels according to the top-most cell. In contrast, first-order parsers make these two decisions jointly by averaging all the cells that cross the left and right children to unify the representation of lexicon and syntax.

During the training stage, Wang and Utiyama (2024) select spans from target trees to perform contrastive hashing with the similarity function described above. Naively contrasting all spans would increase the time complexity to $\mathcal{O}(n^4)$. To avoid this, they restrict supervision to spans on the target trees, reducing the number of spans to $2n - 1$ and maintaining the time complexity at $\mathcal{O}(n^2)$. In their supervised settings, they only allow the model to determine the binary codes, without predicting the boundaries, thus, the procedure can be reinterpreted as searching in a constrained space.

$$\hat{\mathbf{t}} = \{\langle l_i, r_i, \hat{\mathbf{c}}_i \rangle\}_{i=1}^{2n-1} \leftarrow \arg \max_{\mathbf{t} \in \mathcal{T}[l, r, \cdot]} p(\mathbf{t}) \quad (13)$$

Where l_i and r_i denote the boundaries of the target spans, and $\mathcal{T}[l, r, \cdot]$ means only searching in the constrained space to ensure target are always included. Besides, the positive and negative sets are divided according to the ground-truth labels y_i .

$$\begin{aligned} \mathcal{P} &= \{j \mid y_i = y_j\} \\ \mathcal{N} &= \{j \mid y_i \neq y_j\} \end{aligned} \quad (14)$$

3 Proposed Methods

3.1 First-order Constituency Parsing

Efficient computing requires batchifying the inside pass of the CKY algorithm for parallel dynamic programming on GPUs (Stern et al., 2017; Zhang et al., 2020). Within the CKY framework, Wang and Utiyama (2024) introduce a large tensor as the chart for dynamic programming, where $G(l, r, \mathbf{c})$ refers to the total scores of all trees spanning from l to r with code \mathbf{c} as the top label, while $g(l, r, \mathbf{c})$ stands for a single constituent. The algorithm starts from single-word spans and incrementally com-

puts larger spans by enumerating splitting positions and summing children with the top span.

$$G(l, r, \mathbf{c}) \leftarrow \sum_{m=l}^{r-1} G(l, m, \cdot) + G(m+1, r, \cdot) + g(l, r, \mathbf{c}) \quad (15)$$

This procedure has been widely employed as a practical standard (Zhang et al., 2020; Wang et al., 2023). However, we notice that natively using it for unsupervised parsing is not sufficient. As shown in Figure 2, the crux is that even though Equation 15 enumerates all valid splitting positions, the span score $g(l, r, \mathbf{c})$ does not take the splitting positions into consideration. According to Equation 7, this score depends only on the leftmost and rightmost tokens, regardless of the chosen splitting positions. In other words, different choices of splitting positions do not vary the code scores of top spans. Therefore, performing contrastive hashing by using such scores barely provides any effective information for unsupervised parsing. We refer to this kind of CKY as zero-order CKY.

Naturally, the most intuitive solution is upgrading to first-order CKY by taking the splitting position m into consideration through introducing a novel span score function $g(l, r, m, \mathbf{c})$.

$$G(l, r, \mathbf{c}) = \sum_{m=l}^{r-1} G(l, m, \cdot) + G(m+1, r, \cdot) + g(l, r, m, \mathbf{c}) \quad (16)$$

And instead of relying only on the leftmost and the rightmost hidden states, we use the averaged representation of the left and right children, respectively.

$$g(l, r, m, \mathbf{c}) = \sum_{k=1}^K g_k(l, r, m, \mathbf{c}^k) \quad (17)$$

$$g_k(l, r, m, +1) = \frac{(\mathbf{W}_k^Q \bar{\mathbf{h}}_{l:m})^\top (\mathbf{W}_k^K \bar{\mathbf{h}}_{m+1:r})}{\sqrt{d_k}}$$

$$\bar{\mathbf{h}}_{l:m} = \text{mean}_{l \leq i \leq m} \mathbf{h}_i$$

$$\bar{\mathbf{h}}_{m+1:r} = \text{mean}_{m < j \leq r} \mathbf{h}_j$$

Where $\bar{\mathbf{h}}_{l:m}$ and $\bar{\mathbf{h}}_{m+1:r}$ are the averaged representation of the left and right children, respectively. In this way, the splitting position influences the scores of binary codes through children hidden states.

However, naively computing $g_k(l, r, m, +1)$ requires additional computational resources for aver-

aging vectors and performing dot products in real-time, which heavily slows down training and inference. Fortunately, through simple derivation, we note that the new score can be obtained by merely averaging the old scores. Upgrading CKY from zero-order to first-order then introduces almost no additional delay by applying this trick.

$$g_k(l, r, m, +1) = \text{mean}_{l \leq i \leq m < j \leq r} g_k(i, j, +1) \quad (18)$$

According to this definition, the new scores can be interpreted as being obtained by averaging the left and right children, respectively, and then calculating the scores for construing a span across them. Different choices of splitting positions result in different representations of the left and right children, leading to different bit scores for the top span. Since scores reflect the substructure of spans, aligning and uniformizing these scores in Hamming space using contrastive learning is equivalent to aligning and uniformizing the subtrees in syntactic structure space. Hence, our method can also be considered relevant to syntactic distance (Shen et al., 2018a, 2019). Additionally, we also assign a score of 0 for the -1 case.

$$g_k(l, r, m, -1) = 0 \quad (19)$$

And extend the marginal probabilities as well.

$$\mu_k(l, r, m, \mathbf{c}^k) = \frac{\partial \log Z}{\partial g_k(l, r, m, \mathbf{c}^k)} \quad (20)$$

3.2 Unsupervised Contrastive Hashing

We define our similarity in a manner similar to Wang and Utiyama (2024). As we have upgraded the bit-level CKY module from zero-order to first-order, we also upgrade the binarization procedure.

$$\mathbf{c} = [c^1, \dots, c^K] \in \{-1, +1\}^K \quad (21)$$

$$c^k = \begin{cases} +1 & \mu_k(l, r, m, +1) > \mu_k(l, r, m, -1) \\ -1 & \text{otherwise} \end{cases}$$

and the similarity function as follows.

$$s(i, j) = \frac{1}{K} \sum_{k=1}^K \mu_k(l_i, r_i, m_i, c_j^k) \quad (22)$$

Unlike in the supervised settings of Wang and Utiyama (2024), we aim to obtain constituency parsers without training them on annotated treebanks, i.e., $\{\langle l_i, r_i, y_i \rangle\}_{i=1}^{2n-1}$. Therefore, it is difficult for us to constrain the search space as Equation 13 and to divide spans according to ground-truth labels as Equation 14. Thus, we unlock these

restrictions and let parsers determine constituent boundaries and binary labels jointly through searching in an unconstrained space $\mathcal{T}[\cdot, \cdot, \cdot]$.

$$\hat{\mathbf{t}} = \left\{ \langle \hat{l}_i, \hat{r}_i, \hat{c}_i \rangle \right\}_{i=1}^{2n-1} \leftarrow \arg \max_{\mathbf{t} \in \mathcal{T}[\cdot, \cdot, \cdot]} p(\mathbf{t}) \quad (23)$$

After that, since we neither have access to the ground-truth labels y_i , we turn to use the lexicons in spans $w_{\hat{l}_i}, \dots, w_{\hat{r}_i}$ as the labels to divide these selected spans. In this way, pulling or pushing spans is determined solely on surface textual features. Besides, since a portion of input tokens are masked out during the augmentation stage, our parsers can be considered a masked language model as well, except that they are trained with a contrastive objective at the span level.

$$\begin{aligned} \mathcal{P} &= \left\{ j \mid w_{\hat{l}_i:\hat{r}_i} = w_{\hat{l}_j:\hat{r}_j} \right\} \\ \mathcal{N} &= \left\{ j \mid w_{\hat{l}_i:\hat{r}_i} \neq w_{\hat{l}_j:\hat{r}_j} \right\} \end{aligned} \quad (24)$$

From the perspective of training, as Wang et al. (2023) mentioned, one of the most appealing properties of contrastive learning is that it can convert tasks from *wh-questions* to *yes-no questions*. Conventional classification approaches demand embedding vectors for all spans, but enumerating them all is clearly intractable. According to Appendix A, we note that even disregarding the sparsity, employing an embedding with millions of entries is barely practical due to its huge memory consumption. In contrast, our contrastive hashing only needs to know if spans are identical or not, allowing it to pull or push their representations directly without needing to introduce specific embeddings. This property makes previously intractable training feasible and efficient.

From the perspective of representation learning, contrastive learning aims to maximize the distinguishability between instances. In our model, this corresponds to maximizing the distinguishability between subtrees. For parsing, choosing the splitting positions that minimize the internal differences within subtrees is equivalent to maximizing the differences across subtrees. In other words, parsing can be considered as a procedure of searching the minimum entropy tree formed by repeatedly merging the most similar contiguous subtrees, thus, it aligns with the learning objective of contrastive hashing. We believe this explains why such a contrastive hashing procedure results in syntactic trees rather than other structures, and this provides justification for our use of contrastive learning.

3.3 Instance Selection

Contrastive learning (Gao et al., 2021) learns informative representation through pulling together positive and pushing apart negative instances. Wang and Utiyama (2024) enumerate each instance i and compare it with all instances in the batch $j \in \hat{\mathbf{t}}$ to compute the instance-level loss $\ell(i, \mu, \hat{\mathbf{t}})$, and then aggregate all these losses as the batch-level loss \mathcal{L} . By using $\log \sum \exp$ as a approximation of \max ,

$$\max_{x \in \mathcal{X}} (x) \approx \log \sum_{x \in \mathcal{X}} \exp(x) \quad (25)$$

They tweaked those commonly used contrastive objectives into unified formats as follows, where $\mathcal{S} = \{i\}$ is simply defined as the instance itself.

$$\ell_{\text{self}} \approx \max_{\mathcal{N} \cup \mathcal{P}} s(i, j) - s(i, i) \quad (26)$$

$$\ell_{\text{sup}} \approx \max_{\mathcal{N} \cup \mathcal{P}} s(i, j) - \text{mean}_{\mathcal{P}} s(i, j) \quad (27)$$

$$\ell_{\text{hash}} \approx \max_{\mathcal{N} \cup \mathcal{S}} s(i, j) - s(i, i) \quad (28)$$

$$\ell_{\text{max}} \approx \max_{\mathcal{N} \cup \mathcal{S}} s(i, j) - \max_{\mathcal{P}} s(i, j) \quad (29)$$

$$= \max \left(\max_{\mathcal{N}} s(i, j), s(i, i) \right) - \max_{\mathcal{P}} s(i, j)$$

Objective function ℓ_{self} is commonly utilized in scenarios involving only a single positive instance. Khosla et al. (2020) then extended it as ℓ_{sup} to handle multiple positive instances scenarios, and it was later surpassed by ℓ_{hash} and ℓ_{max} . For more details, we refer readers to their original papers (Wang et al., 2023; Wang and Utiyama, 2024).

Briefly speaking, objective ℓ_{hash} assumes there is only one true positive and excludes potential false negatives and positives from both terms, with \mathcal{P} replaced with \mathcal{S} . Moreover, ℓ_{max} adopts a different approach to handling multiple positive instances. They still assume there is only one true positive instance among \mathcal{P} , but they dynamically select the closest one as the true positive, instead of statically selecting \mathcal{S} . By imposing such a weak alignment signal, they also avoid the geometric center issue of ℓ_{sup} . However, we found that for tasks with large label vocabularies, such as language models, this signal turns out to be too weak. Therefore, instead of pulling only the closest pairs, we propose to mainly focus on the farthest pairs,

$$\ell_{\text{min}} \approx \max_{\mathcal{N} \cup \mathcal{S}} s(i, j) - \min_{\mathcal{P}} s(i, j) \quad (30)$$

$$= \max \left(\max_{\mathcal{N}} s(i, j), s(i, i) \right) - \min_{\mathcal{P}} s(i, j)$$

by introducing a differentiable approximation of min operator in a similar matter to Equation 25.

$$\min_{x \in \mathcal{X}} (x) \approx -\log \sum_{x \in \mathcal{X}} \exp(-x) \quad (31)$$

According to experimental results of previous work, excluding potential false negatives seems to be an effective solution, and it also balances the two terms well. However, since ℓ_{\min} introduces a strong alignment signal in the positive term, this balance is disrupted. We have consistently observed that the ℓ_{\min} model suddenly collapses and starts returning only trivial right-branching trees. We hypothesize the reason is that there is no corresponding uniformity signal in the negative term to balance this strong alignment signal. However, naively adding $\min_{\mathcal{P}}$ to the negative term as the balancing term leads to a new issue,

$$\max \left(\max_{\mathcal{N}} s(i, j), \min_{\mathcal{P}} s(i, j) \right) - \min_{\mathcal{P}} s(i, j)$$

that is when the number of positives is large, positives \mathcal{P} dominate the gradients, leaving insufficient supervision signals to the true negatives \mathcal{N} . Therefore, we propose to limit the total gradients of positives to be the same magnitude as single positive by introducing another approximation of min.

$$\overline{\min}_{x \in \mathcal{X}} (x) \approx -\log \left(\frac{1}{|\mathcal{X}|} \sum_{x \in \mathcal{X}} \exp(-x) \right) \quad (32)$$

In this way, we propose $\ell_{\overline{\min}}$ as a balanced version, with $\min_{\mathcal{P}}$ in the negative term replaced by $\overline{\min}_{\mathcal{P}}$.

$$\begin{aligned} \ell_{\overline{\min}} &\approx \max_{\mathcal{N} \cup \{\overline{\min}_{\mathcal{P}}\}} s(i, j) - \overline{\min}_{\mathcal{P}} s(i, j) \quad (33) \\ &= \max \left(\max_{\mathcal{N}} s(i, j), \overline{\min}_{\mathcal{P}} s(i, j) \right) - \overline{\min}_{\mathcal{P}} s(i, j) \end{aligned}$$

3.4 Architecture

Following Wang and Utiyama (2024), our model also consists of a pre-trained language model, an attention hash layer, and a bit-level CKY module. The only difference is that we upgrade CKY from zero-order to first-order, which enhances its ability to unify the representation of lexicon and syntax.

Although it is also a masked language model, our model does not require introducing a large embedding matrix for calculating token classification in the output layer. Since it relies on the attention hash layer to produce binary codes of spans, the number of parameters in the output layer is reduced from $|\mathcal{Y}| \times d$ to two $K \times \lceil \frac{d}{K} \rceil \times d$.

3.5 Training and Inference

During the training stage, sentences are fed into the model twice to obtain two different views by being augmented with different dropout masks. We calculate the marginal probabilities μ^1 and μ^2 , and then predict constituency trees \hat{t}^1 and \hat{t}^2 on these two versions, respectively. For each view, we select the corresponding span scores from the marginal probabilities of one view, according to the predicted tree of the other view, and then perform span-level contrastive hashing by using the objectives above and average them as the batch loss.

$$\mathcal{L} = \text{mean}_{i \in \hat{t}^2} \ell(i, \mu^1, \hat{t}^2) + \text{mean}_{i \in \hat{t}^1} \ell(i, \mu^2, \hat{t}^1) \quad (34)$$

Since unsupervised constituency parsing only aims at detecting the span boundaries without needing to predict labels, we do not need to build the code vocabulary as Wang and Utiyama (2024) did. During the inference stage, we simply search for the most probable constituency parsing trees in an unconstrained space with the Cocke-Kasami-Younger (CKY) algorithm (Kasami, 1966).

4 Experiments

4.1 Settings

Experiments are conducted on the commonly used datasets Penn Treebank (PTB) (Marcus et al., 1993) and Chinese Treebank 5.1 (CTB) (Xue et al., 2005).

Following previous settings (Shen et al., 2018b, 2019; Zhao and Titov, 2021), we use the same preprocessing pipeline to discard punctuation in all splits. Although this pipeline may not be the best choice for pre-trained language models and might result in some information loss, since language models are commonly trained with punctuated corpora, we follow this setting only to provide comparable results to previous work. Regarding the evaluation metric, we follow Kim et al. (2019a) to remove trivial spans, i.e., single-word and entire-sentence spans, calculate unlabeled sentence-level F1 scores, and take the average across all sentences.

We use the deep learning framework PyTorch (Paszke et al., 2019) to implement our models and download checkpoints of pre-trained languages from huggingface/transformers (Wolf et al., 2020). Different from some recent work (Yang et al., 2022; Liu et al., 2023), which require customizing CUDA kernels with Triton (Tillet et al., 2019), our model can be easily and efficiently implemented with pure PyTorch.

MODEL	PTB			
	MEAN	MAX		
PRPN (Shen et al., 2018b) ^b	37.4	38.1		
URNNG (Kim et al., 2019b) ^b	-	45.4		
ON-LSTM (Shen et al., 2019) ^b	47.7	49.4		
R2D2 (Hu et al., 2021) ^b	48.1	-		
Fast R2D2 (Hu et al., 2022) ^b	48.9	-		
StructFormer (Shen et al., 2021) ^b	54.0	-		
C-PCFG (Kim et al., 2019a) [#]	55.2	60.1		
NL-PCFG (Zhu et al., 2020) [#]	55.3	-		
DIORA (Drozdov et al., 2019b) ^b	55.7	56.2		
GPST (Hu et al., 2024a) ^b	57.5	-		
S-DIORA (Drozdov et al., 2020) ^b	57.6	63.9		
TN-PCFG (Yang et al., 2021b) [#]	57.7	61.4		
NBL-PCFG (Yang et al., 2021a) [#]	60.4	-		
CT (Cao et al., 2020) [†]	62.8	65.9		
Co (Maveli and Cohen, 2022) [†]	63.1	66.8		
Rank-PCFG (Yang et al., 2022) [#]	64.1	-		
ReCAT (Hu et al., 2024b) ^b	<u>65.0</u>	-		
SN-PCFG (Liu et al., 2023) [#]	65.1	-		
FOR REFERENCE				
Ensemble (Shayegh et al., 2024)	70.4	71.9		
Left Branching	8.7	8.7		
Right Branching	39.5	39.5		
Oracle	84.3	84.3		
Ours ^b (BERT _{BASE} - 16 bits)			55.3	58.8
Ours ^b (BERT _{BASE} - 20 bits)			<u>56.7</u>	59.8
Ours ^b (BERT _{BASE} - 24 bits)			57.4	59.6
Ours ^b (BERT _{BASE} - 28 bits)			54.5	60.9
Ours ^b (ROBERTA _{BASE} - 8 bits)			56.5	63.1
Ours ^b (ROBERTA _{BASE} - 12 bits)			58.0	62.9
Ours ^b (ROBERTA _{BASE} - 16 bits)			62.4	64.1
Ours ^b (ROBERTA _{BASE} - 20 bits)			<u>59.6</u>	63.9

Table 1: Experiments of unsupervised constituency parsing on the PTB dataset. The columns MEAN and MAX display the averaged and the maximal unlabeled sentence-level F₁ scores. The **bold numbers** and the underlined numbers indicate the best and the second-best performance. ^b[#][†] stands for implicit grammar, explicit grammar, and probing methods, respectively.

We collect sentences until the total number of spans reaches 1024 to keep the contrastive hashing stable, since it is performed at the span level. We use the Adam optimizer (Kingma and Ba, 2015; Loshchilov and Hutter, 2019) and set the number of warmup and training steps to 4,000 and 20,000, respectively. We randomly select a portion of tokens and replace them with [MASK], following the standard augmentation strategy of masked language models. For PTB experi-

MODEL	CTB			
	MEAN	MAX		
ON-LSTM (Shen et al., 2019) ^b	25.4	25.7		
PRPN (Shen et al., 2018b) ^b	30.4	31.5		
Rank-PCFG (Yang et al., 2022) [#]	32.4	-		
C-PCFG (Kim et al., 2019a) [#]	36.0	39.8		
TN-PCFG (Yang et al., 2021b) [#]	39.2	-		
Co (Maveli and Cohen, 2022) [†]	41.8	43.3		
SC-PCFG (Liu et al., 2023) [#]	42.9	-		
R2D2 (Hu et al., 2021) ^b	<u>44.9</u>	-		
Fast R2D2 (Hu et al., 2022) ^b	45.3	-		
FOR REFERENCE				
Left Branching	9.7	9.7		
Right Branching	20.0	20.0		
Oracle	81.1	81.1		
Ours ^b (BERT _{BASE} - 28 bits)			41.2	49.0
Ours ^b (BERT _{BASE} - 32 bits)			43.1	49.5
Ours ^b (BERT _{BASE} - 36 bits)			47.1	49.6
Ours ^b (BERT _{BASE} - 40 bits)			<u>43.6</u>	49.5
Ours ^b (ROBERTA _{BASE} - 36 bits)			46.4	50.2
Ours ^b (ROBERTA _{BASE} - 40 bits)			45.4	50.0
Ours ^b (ROBERTA _{BASE} - 44 bits)			48.5	49.6
Ours ^b (ROBERTA _{BASE} - 48 bits)			<u>47.0</u>	50.3

Table 2: Experiments of unsupervised constituency parsing on the CTB dataset.

ments, we use checkpoints bert-base-cased (Devlin et al., 2019) and roberta-base (Liu et al., 2019). For CTB experiments, we use checkpoints bert-base-chinese (Devlin et al., 2019) and chinese-roberta-wwm-ext (Cui et al., 2020).

We use a single NVIDIA Tesla V100 graphics card to conduct our experiments. Training takes around 30 minutes, which is much faster than the several days of training required by Cao et al. (2020) and Drozdov et al. (2019a). Since we do not modify the architecture of the language model but simply append a hash layer to it, we can fine-tune existing pre-trained language models without needing to train them from scratch, as done by Hu et al. (2022, 2024a). For each setting, we run it four times with different random seeds and report the averaged scores in the following tables.

4.2 Main Results

On the English dataset PTB, as shown in Table 1, our model reaches its peak performance at 24 bits and 16 bits when using BERT and RoBERTa pre-trained language models, respectively. We consis-

NEG	POS	LOSS	PTB	
			MEAN	MAX
$\max_{\mathcal{N} \cup \mathcal{P}}$	\mathcal{S}	ℓ_{self}	39.9	40.4
	$\max_{\mathcal{P}}$	-	44.0	54.0
	$\min_{\mathcal{P}}$	-	48.8	61.8
$\max_{\mathcal{N} \cup \mathcal{S}}$	\mathcal{S}	ℓ_{hash}	39.9	40.3
	$\max_{\mathcal{P}}$	ℓ_{max}	45.5	50.1
	$\min_{\mathcal{P}}$	ℓ_{min}	<u>58.2</u>	60.6
$\max_{\mathcal{N} \cup \{\overline{\min}_{\mathcal{P}}\}}$	\mathcal{S}	-	35.2	49.1
	$\max_{\mathcal{P}}$	-	47.5	53.9
	$\min_{\mathcal{P}}$	$\ell_{\overline{\min}}$	62.4	64.1

Table 3: Ablation study of instance selection strategies in constituency parsing experiments. Columns NEG and POS display the selection strategies for negatives and positives, respectively. LOSS shows this combination corresponds to which loss definition.

tently surpass all other implicit grammar models. Due to the relatively small size of PTB, the probing methods by Cao et al. (2020) and Maveli and Cohen (2022) utilized additional text data for training. Even without using such extra data, our model still achieves performance very close to theirs.

Our model outperforms all existing models by a large margin on the Chinese dataset CTB, as shown in Table 2. Explicit grammar models that perform well on English datasets (Yang et al., 2022; Liu et al., 2023) do not achieve similar success on the Chinese dataset. Additionally, we notice that our model requires much more bits than on the English dataset, i.e., 36 and 44, to reach their full potential. We hypothesize that this is due to the relatively small size of the Chinese dataset, as shown in Appendix A, which prevents the models from being fully trained to encode lexicon and syntax features within only a few bits.

4.3 Ablation Studies

Table 3 reveals how the different combinations of negative and positive terms affect performance. First of all, we notice that once $\min_{\mathcal{P}}$ is employed, regardless of which negative terms are used along with it, the models consistently result in high scores in the MAX column. On the contrary, without employing $\min_{\mathcal{P}}$, these scores dramatically drop. This confirms our statement that for tasks with large label vocabularies, positive terms require strong alignment signals to learn effective representations. Moreover, when it comes to the MEAN column, whether the term $\max_{\mathcal{N} \cup \{\overline{\min}_{\mathcal{P}}\}}$ is employed de-

termines whether the high scores of $\min_{\mathcal{P}}$ can be maintained. We also notice that $\max_{\mathcal{N} \cup \mathcal{S}}$ consistently outperforms $\max_{\mathcal{N} \cup \mathcal{P}}$. This indicates that simply pushing away all instances of \mathcal{P} indeed introduces the false negatives issue. As Wang et al. (2023); Wang and Utiyama (2024) claims, retaining only \mathcal{S} mitigates this issue, but when \mathcal{P} is introduced back to the positive term under a strong alignment, the lack of uniformity signals brings a new imbalance issue, and our solution $\ell_{\overline{\min}}$ rebalances them by using $\overline{\min}_{\mathcal{P}}$ in both terms.

4.4 Case Studies

Figure 3 shows an example of our parsing results, with more examples available in Appendix B. Relying on the implicitly induced grammar, our model provides remarkably accurate parsing results, with all constituents correctly selected. Additionally, the hashing results also demonstrate the impressive capability in discovering syntactic categories. For instance, both preterminal symbols like adjectives, e.g., *quick* (5A00), *brown* (5E42), and *lazy* (5E03), and nonterminal symbols like noun phrases, e.g., *the quick brown fox* (7EBB) and *the lazy dog* (EEBB), are assigned similar and relevant binary codes to each other. This phenomenon can also be observed in sentences in Appendix B, indicating that our parser can accurately reveal both part-of-speech and constituent features at different hierarchical levels.

5 Related Work

Syntactic language models, as a historical and important field of language models, had been widely studied even before the deep learning era (Chelba and Jelinek, 2000; Charniak, 2001; Roark, 2001; Klein and Manning, 2002, 2004; Bod, 2006a,b). After that, Shen et al. (2018a,b, 2019) added syntactic inductive bias to LSTM by introducing master gates to control the information flow in hierarchical directions, thereby enabling the model to learn syntactic distance. Under this framework, by training recurrent language models in the usual way, they can obtain parsers that implicitly structure sentences according to the learned syntactic distances. They have also successfully applied this method to transformers (Shen et al., 2021).

Implicit grammar models induce grammar during the training process by incrementally constructing larger span representations. Kim et al. (2019b) were the first to extend the recurrent neural network grammar (RNNG) (Dyer et al., 2016) from super-

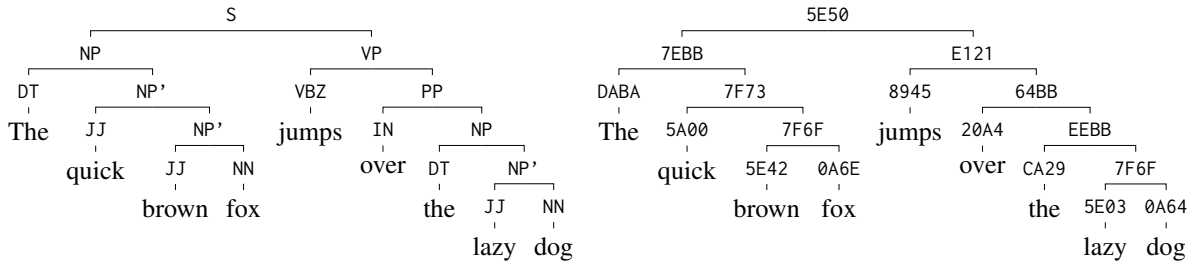


Figure 3: Derivation of the sentence *The quick brown fox jumps over the lazy dog*. The left side is the ground-truth consistency tree, and the right side is our parsing result with binary labels represented in hexadecimal format.

vised to unsupervised settings. They build parsing trees through continuously shifting and reducing, without introducing explicit production rules. Additionally, DIORA (Drozdov et al., 2019b, 2020) construct span representations and update charts in both inside and outside passes, and then encourage consistency between them. Similarly, R2D2 (Hu et al., 2021, 2022) is trained in a similar manner, but with Gumbel-softmax (Jang et al., 2017) introduced during the tree construction.

Apart from implicit grammar models, explicitly inducing probabilistic context-free grammar (PCFG) is also widely focused. Kim et al. (2019a) first brought PCFG approaches back with a neural parameterization technique and trained language models to reconstruct entire input sentences token by token. Zhu et al. (2020) shows that additionally modeling lexical dependencies (Collins, 2003) is effective, and Jiang et al. (2016); Yang et al. (2021a) further confirmed extending to bilexical dependencies is even more beneficial. Besides, Yang et al. (2021b, 2022); Liu et al. (2023) claimed that the limited number of symbols is a bottleneck of PCFG induction, and proposed to introduce more symbols by applying tensor decomposition to overcome the cubic computational complexity.

How much syntactic knowledge is preserved within the ordinary language model is also a question worth considering. Mareček and Rosa (2018, 2019) noticed the value of attention scores first. They defined distance functions similar to our Equation 17 for probing. However, they did not consider splitting positions, and relied only on fixed attention heads without having them fine-tuned. As a result, their methods resulted in limited accuracy. Hewitt and Manning (2019); Wang et al. (2019); Kim et al. (2020); Li et al. (2020); Bai et al. (2021) then introduced parameterized functions to prob syntactic distances on hidden states and attention scores, and then fine-tuned the entire models. Cao

et al. (2020); Maveli and Cohen (2022) fine-tuned pre-trained language models with an additional classifier to distinguish manually generated constituents and distitueuts, and utilized predictions from this classifier to determine splitting positions on parsing trees during the evaluation stage.

In various senses, our approach confirmed the conclusions of many previous works and further pushed their limits. First, by switching the language models from token-level to span-level, we confirmed that modeling lexical dependencies is beneficial and extending this modeling to all tokens in children is more effective. Additionally, by introducing binary representation, we confirmed that employing more symbols is advantageous and further scaling up to 2^K can help parsers do further better. Third, we confirmed that constructing span representations and updating the chart is helpful, and unifying the representation of lexicon and syntax leads to more competitive results. Finally, we confirmed the multi-head attention scores already preserve syntactic information, and fine-tuning them can help probe for more insightful features.

6 Conclusions

In this paper, we confirmed that the information-preserving capability of binary representation is effective at both lexicon and syntax levels, and we demonstrated that it is feasible to elicit parsers from pre-trained language models by leveraging this capability. We achieved this by upgrading bit-level CKY from zero-order to first-order, extending contrastive hashing from supervised to unsupervised, and proposing a novel objective function to impose stronger yet balanced alignment signals. Experiments show our model achieves competitive performance, and also indicate that the technique for acquiring high-quality syntactic annotations at low cost has now reached a practical stage.

Limitations

We successfully obtain parsers in an unsupervised manner. Nonetheless, the number of bits remains a hyperparameter that needs to be tuned by testing them individually. Although, in practice, enumerating from 8 to 48 is sufficient for most cases, the relationship between the required number of bits and the specified task remains unclear. Therefore, we aim to explore this issue in future work. Moreover, we simply define the left and right span representations as the average of their token vectors, as shown in Equation 17. The reason for using such a naive definition is a compromise for the sake of speed. However, it is evident that this simple linear mapping may not efficiently preserve high-order information, and future work could explore more complex mechanisms.

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A Datasets Statistics

DATASET	TRAIN	DEV	TEST	WORD	SPAN
PTB	39,832	1,700	2,416	44,363	8,865,092
CTB	18,104	352	348	36,800	6,510,230

Table 4: Datasets statistics. Columns TRAIN, DEV, and TEST show the number of sentences in each split, while Columns WORD and SPAN indicate the number of words and spans, respectively.

B More Examples

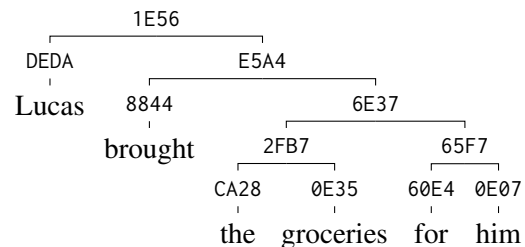


Figure 4: Derivation example.

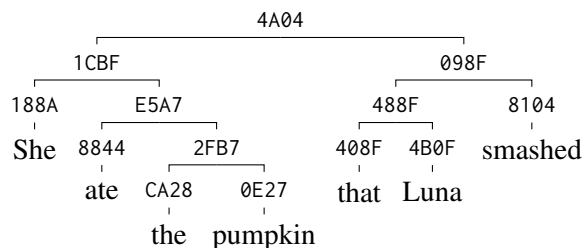


Figure 5: Derivation example.

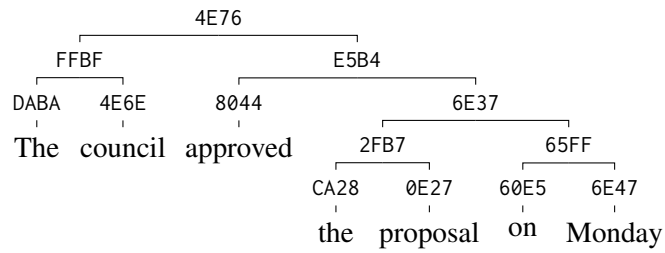


Figure 6: Derivation example.

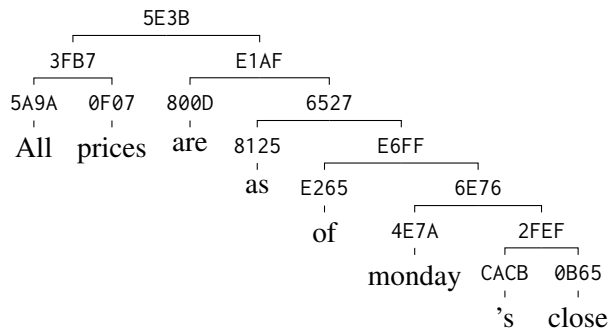


Figure 7: Derivation example.

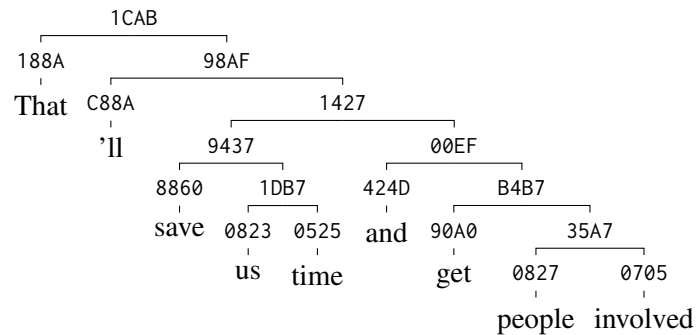


Figure 8: Derivation example.

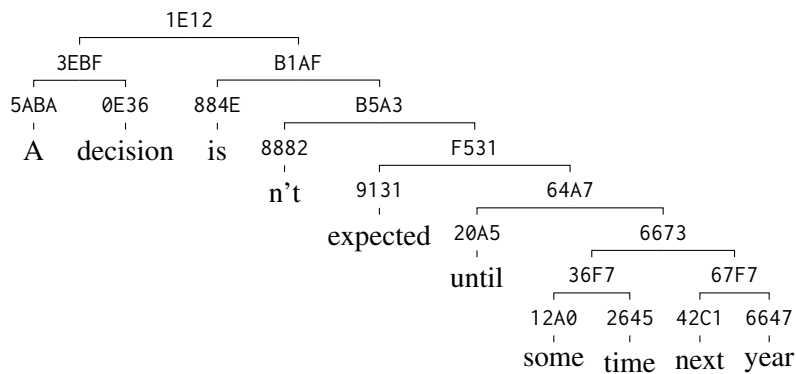


Figure 9: Derivation example.

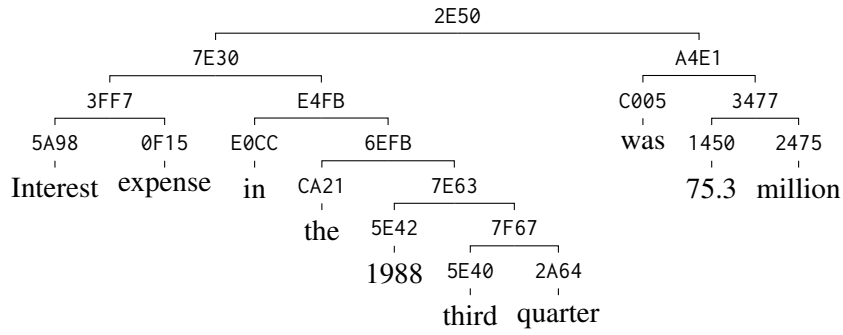


Figure 10: Derivation example.

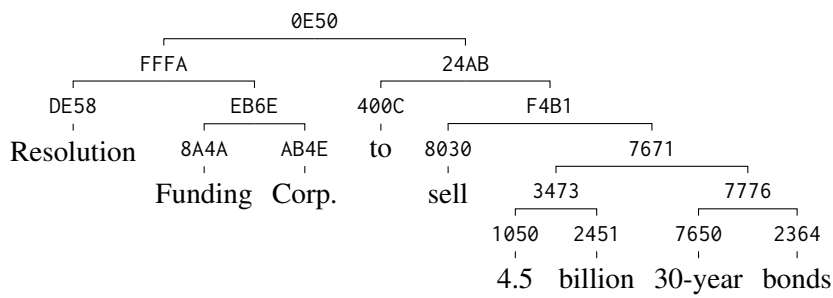


Figure 11: Derivation example.

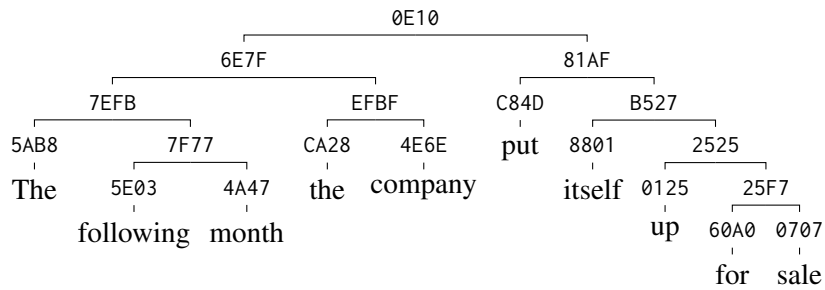


Figure 12: Derivation example.

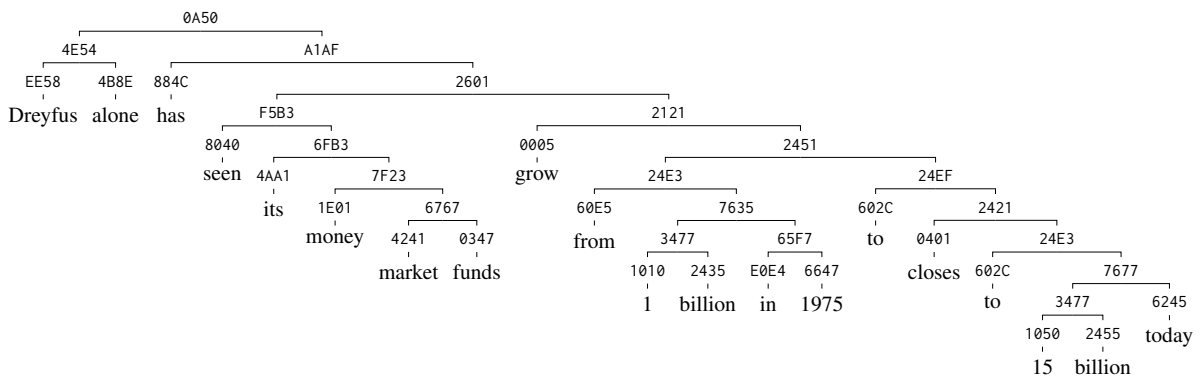


Figure 13: Derivation example.

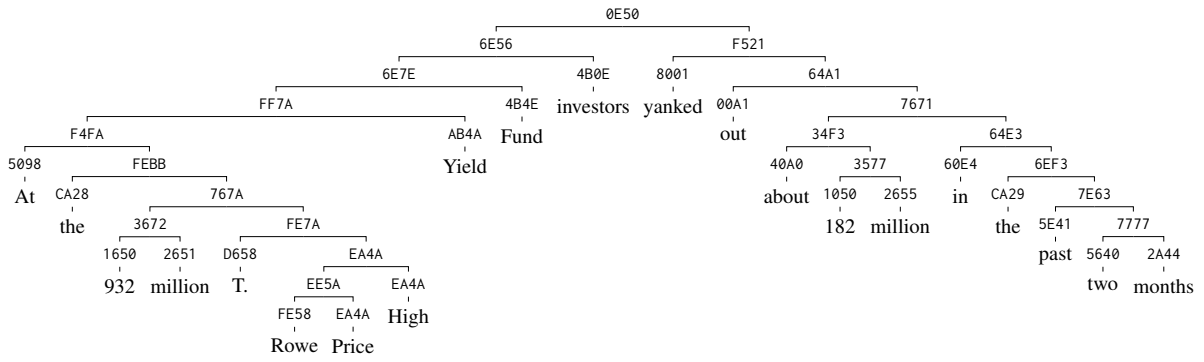


Figure 14: Derivation example.

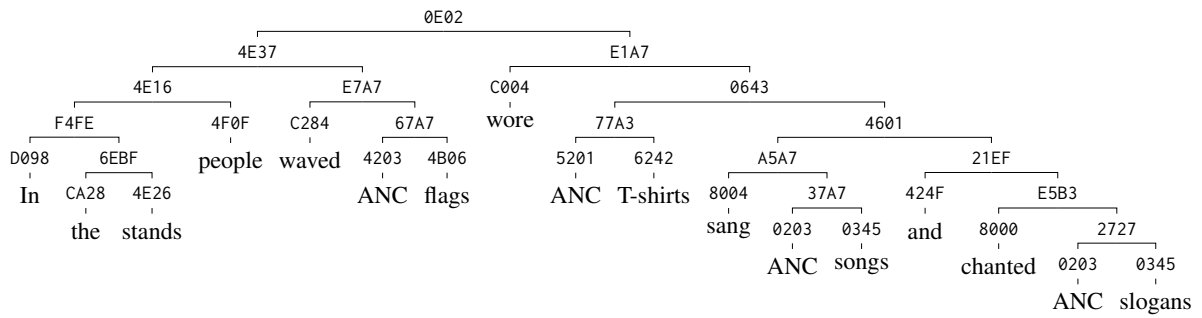


Figure 15: Derivation example.

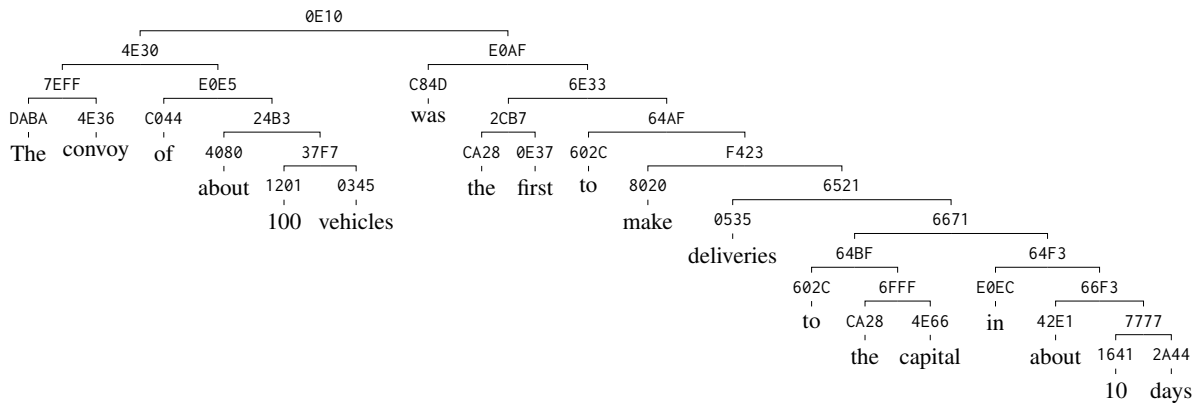


Figure 16: Derivation example.