Multimodal Aspect-Based Sentiment Analysis under Conditional Relation

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Abstract

Multimodal Aspect-Based Sentiment Analysis (MABSA) aims to extract aspect terms from text-image pairs and identify their sentiments. Previous methods are based on the premise that the image contains the objects referred by the aspects within the text. However, this condition cannot always be met, resulting in a suboptimal performance. In this paper, we propose COnditional Relation based Sentiment Analysis framework (CORSA). Specifically, we design a conditional relation detector (CRD) to mitigate the impact of the unmet conditional image. Moreover, we design a visual object localizer (VOL) to locate the exact conditionrelated visual regions associated with the aspects. With CRD and VOL, our CORSA framework takes a multi-task form. In addition, to effectively learn CORSA we conduct two types of annotations. One is the conditional relation using a pretrained referring expression comprehension model; the other is the bounding boxes of visual objects by a pretrained object detection model. Experiments on our built C-MABSA dataset show that CORSA consistently outperforms existing methods. The code and data are available at https://github.com/Liuxj-Anya/CORSA.

1 Introduction

In recent years, fine-grained Multimodal Aspect-Based Sentiment Analysis (MABSA) (Zhao et al., 2024b) has received great attention, due to its significant applications in analyzing social media sentiments. MABSA includes three key subtasks: Multimodal Aspect Term Extraction (MATE), Multimodal Aspect-oriented Sentiment Classification (MASC), and Joint Multimodal Aspects of Sentiment Analysis (JMASA). Given a text-image pair, MATE (Wu et al., 2020a; Li et al., 2023; Guo et al., 2023) aims to extract all the aspect terms mentioned in the text; MASC (Yu and Jiang, 2019; Feng et al., 2024) aims to determine the sentiment

	a)	b)
Image	"Life strongest action ever taken by an American president to tackle clinate change." — The New Yook These Management and the Company And Management and the Company And Company A	gizmorati
Text	So are the actions President Obama is taking to tackle it	LeBron James to Produce NBA Documentary
Conditional Relation	Relevance	Irrelevance
Output	(President Obama, POS)	(LeBron James, NEU)

Figure 1: JMASA aims to extract the aspects and identify their corresponding sentiments from a text-image pair. a) The conditional relation for the aspect (i.e., President Obama) and the image is relevant, and the visual information in the box (in red) could benefit for identifying the sentiment. b) The irrelevant visual information would distract the sentiment prediction.

towards each given aspect term. JMASA (Ju et al., 2021; Yu et al., 2022; Ling et al., 2022; Liu et al., 2024b) aims to jointly predict the aspect terms and the corresponding sentiments. In Figure 1, JMASA produces two aspect-sentiment pairs, i.e., (President Obama, POS) and (LeBron James, NEU).

For fine-grained MABSA task, it mainly involves two challenges. One is the semantic complexity. The given sentences often contain multiple aspects, each referring to different objects in the image. The other is the sentimental complexity. These aspects and image regions could carry different sentiments. To this end, recently proposed methods focus on aligning cross-modal text-image precisely. For example, Ling et al. (2022) propose a task-specific vision-language pretraining framework to solve the cross-modal alignment. Zhou et al. (2023) propose an aspect-oriented method to detect aspect-relevant semantic and sentiment information. Very recently, Xiao et al. (2024) propose to utilize the aesthetic information of the images for textual visual alignment and the sentiment-aware image aesthetic assessment.

However, all of previous methods are designed based on the premise that the image always contains the objects referred by the aspects in the text. Unfortunately, this condition sometimes cannot be met, leading to aligning cross-modal text-image inaccurately. The text and image could be irrelevant, especially in social media domain. As shown in Figure 1b), the image does not contain any information about the aspect, i.e., *LeBron James* which negatively impacts the model's performance. In contrast, the image-text in Figure 1a) satisfies the condition. The visual information contributes to the sentiment analysis.

To mitigate the negative impact of unqualified image-text pairs, in this paper, we propose COnditional Relation based Sentiment Analysis framework (i.e., CORSA) for MABSA. Firstly, we perform two types of annotations. Specifically, we leverage a pretrained Referring Expression Comprehension (REC) (Yan et al., 2023) model to annotate the conditional relation between an image and aspects. Moreover, a pretrained object detection model is employed to annotate visual objects (i.e., bounding boxes and categories) on two popular datasets.

Secondly, we propose two key modules in our CORSA framework. Conditional Relation Detector (CRD) is designed to filter out visual information irrelevant to the aspects considering their compliance with the condition. Furthermore, to precisely locate condition-related regions with the aspects, we propose Visual Object Localizer (VOL). VOL locates visual objects and uses an attention mechanism to align visual objects with aspects.

Thirdly, we design Multimodal Sentiment Analyzer (MSA) based on an encoder-decoder multimodal Bidirectional and Auto-Regressive Transformers (multimodal BART) (Ling et al., 2022) to obtain the aspect-sentiment pairs.

Our contributions are summarized as follows:

- We propose a multi-task framework, CORSA for MABSA task, involving a detector and a localizer. CRD mitigates the impact of the unmet conditional image-text; VOL locates the exact condition-related visual regions referred by the aspects.
- We perform two types of annotations, conditional relation and bounding boxes on two benchmark datasets. Annotations are automatically performed using two pretrained models, respectively.

• We conduct extensive experiments on two benchmark datasets. The experimental results show the effectiveness of our proposed CORSA model.

2 Problem Formulation

We formulate MABSA as a multi-task framework composed of a tuple extraction, a binary classification, and a coordinate regression. Given a tweet containing an image V and a sentence S, we aim to obtain a set for all aspects and the sentimental polarities. These are denoted as $\hat{Y} = \{(a_k, s_k)\}_{k=1}^K$, where a_k is the k-th aspect and s_k is its sentiment. In addition, for each sample, we determine a conditional relation \hat{r} and further detect the location of visual objects, generating the bounding boxes $\{\hat{b}_m\}_{m=1}^B$ and the categories $\{\hat{c}_i\}_{i=1}^C$.

3 Methodology

3.1 Data Generation for C-MABSA

We construct datasets, i.e., C-MABSA with conditional relations for MABSA task. Specifically, we perform two types of annotations automatically on two popular datasets, i.e., TWITTER-15 and TWITTER-17. Firstly, we use a pretrained multi-task universal instance perception model, UNINEXT (Yan et al., 2023) to annotate the conditional relation whether the image contains visual objects referred by the aspects. In UNINEXT, the REC function is adopted. In our settings, UNINEXT takes an aspect and the corresponding image as input and then generates the probability that the image contains the aspect. For samples with more than one aspect, we average the multiple output probabilities. For TWITTER-15, when this probability exceeds a threshold τ_1 of 0.7, we annotate the conditional relation as relevant; otherwise as irrelevant. For TWITTER-17, due to its imageaspect pairs being more relevant, the threshold τ_1 is set as 0.5 to keep more visual information.

Secondly, we use an object detection model YOLOv8 (Jocher et al., 2023) pretrained on MSCOCO (Lin et al., 2014) to annotate the visual objects in the image, including the bounding boxes and categories. For the object category, we define three types, including *person*, *object*, and *back-ground*. Considering the two benchmark datasets often contain people, food, and other objects, we define the person and other categories. For images without any objects, we define the background category. Thus, YOLOv8 takes an image as input



Figure 2: The framework of our proposed CORSA. Unimodal features are extracted using image and text encoder, respectively. Note that three-scale visual features are used. Then, the conditional relation detector (CRD) uses image and text features to capture condition-related visual features. The visual object localizer (VOL) utilizes condition-related visual features and candidate aspects feature to capture condition-aligned visual features. Finally, the multi-modal BART in multimodal sentiment analysis (MSA) is adopted to extract aspect-sentiment pairs.

and generates the detected bounding boxes with its category probability. If the probability exceeds the threshold τ_2 of 0.8, we annotate the image as person or object; otherwise, we annotate it as a background category. Here, the bounding box is taken as the image size.

3.2 Our Proposed Model

Figure 2 provides an overview of CORSA framework. Conditional relation detector (CRD) is to mitigate the impact of the irrelevant condition. Visual object localizer (VOL) is to locate exact conditionrelated regions to specific aspects. Finally, multimodal sentiment analyzer (MSA) built on the multimodal BART encodes multimodal information to extract aspects and the corresponding sentiments.

Visual and Textual Encoders. Our multimodal feature encoder comprises two encoders of vision and language. The textual encoder uses a pretrained

BART (Lewis et al., 2020). We first obtain the initial word embeddings E. Then, BART generates the contextualized representation $H_T \in \mathbb{R}^{s \times d}$. Here, s is the length of the sequence S. The visual encoder uses the backbone of YOLOv8 (Jocher et al., 2023) to obtain multi-scale features in an image. Thus, we obtain the visual features in three scales, i.e., $H_{V_1} \in \mathbb{R}^{49 \times 2048}$, $H_{V_2} \in \mathbb{R}^{196 \times 1536}$, and $H_{V_3} \in \mathbb{R}^{784 \times 1024}$. The three features could help the model detect multi-scale objects.

Conditional Relation Detector (CRD). The goal of our CRD is to detect the relevance of imageaspects, thus filtering out irrelevant visual information to the aspects in a given image. Specifically, we first use the self-attention to capture the interactions between different image patches. In other word, we apply three self-attention layers for each of the three scales of visual features as follows,

$$H'_{V_i} = \operatorname{Att}_i^{\operatorname{SLF}} (H_{V_i} W_{V_i}), i \in \{1, 2, 3\}$$
(1)

where W_{V_i} is the learnable weight and the index *i* is used for the three scales.

Then, we apply cross-modal attention to model the interaction between the text and the image. We design three cross-modal attention layers. Here, we regard image features H'_{V_i} as queries, and the text features H_T as keys and values. The formulation is given as follows,

$$H_{V_i}'' = \operatorname{Att}_i^{\operatorname{CM}} \left(H_{V_i}', H_T, H_T \right), i \in \{1, 2, 3\}$$
(2)

where H_{V_i}'' is the generated text-based image features. Next, we apply max-pooling on the feature H_{V_i}'' , obtaining the most salient feature, $H_{V_i}^{\max}$. Then, based on the most salient feature, we use a softmax function to detect the conditional relation,

$$\hat{r}_i = \text{Softmax} \left(W_{R_i} H_{V_i}^{\max} + b_{R_i} \right), i \in \{1, 2, 3\}$$
(3)

where W_{R_i} is the learnable weight.

To learn CRD, we use the cross-entropy loss to optimize the binary classification task, i.e.,

$$\mathcal{L}^{\text{CRD}} = -\frac{1}{N} \sum_{n=1}^{N} \sum_{i=1}^{3} \log \hat{r}_i, \qquad (4)$$

where N is the total number of training samples.

Finally, we filter the visual features most relevant to aspects, i.e., condition-related visual features, used in VOL. Specifically, the probability \hat{r}_i in Eq. (3) indicates the relevant degree of an image-text pair. We use it to construct a visual filter matrix G_i , where each entry equals to the probability \hat{r}_i . Thus, we obtain the filtered image feature $H_{V_i}^{\prime\prime\prime}$, i.e.,

$$H_{V_i}^{\prime\prime\prime} = G_i \odot H_{V_i}^{\prime\prime}, i \in \{1, 2, 3\}$$
(5)

where \odot denotes the element-wise multiplication.

Visual Object Localizer (VOL). VOL aims to further enhance CRD and then localize the exact condition-related regions to the aspects. Specifically, we incorporate an object detector to obtain the bounding box of the visual object and its category. Since multi-scale features are adopted, we apply three object detection headers. Following YOLOv8 (Jocher et al., 2023), we detect visual objects with the previously filtered feature $H_{V_i}^{\prime\prime\prime}$ as input. The formulation is given as follows,

$$O_i = \text{DET}(H_{V_i}^{\prime\prime\prime}), i \in \{1, 2, 3\}$$
(6)

where $O_1 \in \mathbb{R}^{49 \times 24}$, $O_2 \in \mathbb{R}^{196 \times 24}$, and $O_3 \in \mathbb{R}^{784 \times 24}$. We predict three bounding boxes at each

scale. The column size of O_i equals $[3 \times (4+1+3)]$. Here, we have four bounding box offsets \hat{b} , one object's prediction \hat{c} , and three class's prediction \hat{c} .

We use two losses to optimize the coordinate regression task. The regression prediction loss is the distance between the predictive boxes and the real boxes. It includes the MSE of boxes' coordinates,

$$\mathcal{L}^{\text{LOC}} = \frac{1}{N} \sum_{n=1}^{N} \sum_{i=1}^{3} \left(b_n^i - \hat{b}_n^i \right)^2.$$
(7)

The classification loss is used to predict the class of objects in the boxes. The loss takes the form of cross-entropy loss,

$$\mathcal{L}^{\text{CLS}} = -\frac{1}{N} \sum_{n=1}^{N} \sum_{i=1}^{3} \left(c_n^i \log \hat{c}_n^i + \log \hat{o}_n^i \right), \quad (8)$$

where c_n is annotated visual object's categories and \hat{c}_n is the corresponding prediction.

Then, to obtain the visual object features associated with aspects, we utilize cross-model attention to align visual objects and aspects. Specifically, we use Spacy ¹ to extract noun phrases as candidate aspects and obtain their features H_T^A . The textual features $H_T^A = \{h_1^A, h_2^A, ..., h_l^A\}$ is obtained from the hidden state H_T of the BART encoder, where *l* is the number of noun phrases. We use features of all candidate aspects H_T^A as key-value pairs and visual features $H_{V_i}^{\prime\prime\prime}$ as queries. The process for the aligned visual features is formulated as follows,

$$H_{V_i}^A = \operatorname{Att}_i^{\operatorname{CM}}(H_{V_i}^{\prime\prime\prime}, H_T^A, H_T^A), i \in \{1, 2, 3\}$$
(9)

Finally, we use gating mechanism to concatenate two visual features, i.e., $H_{V_i}^{\prime\prime\prime}$ and $H_{V_i}^A$ as follows,

$$\begin{cases} \alpha_j = \sigma \left(W_\alpha [W''' h_{v_j}''' \oplus W^A h_{v_j}^A] + b_\alpha \right) \\ \hat{h_j} = \alpha_j h_{v_j}''' + (1 - \alpha_j) h_{v_j}^A \end{cases}$$
(10)

where $h_{v_j}^{\prime\prime\prime}$ and $h_{v_j}^A$ are *j*-th column of $H_{V_i}^{\prime\prime\prime}$ and $H_{V_i}^A$, respectively. In addition, W_{α} , $W^{\prime\prime\prime}$ and W^A are learnable weights. Thus, we obtain the condition-aligned visual features $\hat{H}_{V_i} = \{\hat{h}_1, ..., \hat{h}_j, ..., \hat{h}_m\}, i \in \{1, 2, 3\}$. The visual feature \hat{H}_{V_i} is relevant to aspects and contain the accurate aspect's visual information.

Multi-modal Sentiment Analyzer (MSA). The goal of MSA is to encode multimodal inputs while decoding aspects and their sentiment. Specifically,

¹https://spacy.io/

	TW	ITTER	-15	TWI	TTER	-17
	Train	Dev	Test	Train	Dev	Test
Positive	928	303	317	1508	515	493
Neutral	1883	670	607	1638	517	573
Negative	368	149	113	416	144	168
Sentence	2101	727	674	1746	577	587
Single aspect	1302	441	416	586	202	188
Multiple aspects	799	286	258	1160	375	399

Table 1: Statistics on two benchmark datasets.

we first concatenate the three scales of visual features, i.e., $\hat{H}' = \hat{H}_{V_1} \oplus W_{V_2} \hat{H}_{V_2} \oplus W_{V_3} \hat{H}_{V_3}$, where $W_{V_2} \in \mathbb{R}^{49 \times 196}$ and $W_{V_3} \in \mathbb{R}^{49 \times 784}$ are learnable weights for obtaining an identical dimension. Then, we use a linear layer to map the concatenated feature to 49-dimension, obtaining a visual feature \hat{H}'' . Second, we use the multimodal BART (Ling et al., 2022) encoder-decoder to predict the token probability distribution y_t as follows,

$$\begin{cases} \hat{H}''' = \operatorname{Encoder}(\hat{H}'' \oplus E) \\ h_t = \operatorname{Decoder}(\hat{H}'''; Y_{< t}) \\ y_t = \operatorname{Softmax}(W_t h_t + b_t) \end{cases}$$
(11)

in which, E is the word embedding and $Y_{<t}$ is the previous time-step decoder outputs. y_t is predicted aspects and sentiment.

To learn MSA, we use the cross-entropy loss to optimize the tuple extraction task, i.e.,

$$\mathcal{L}^{\text{MSA}} = -\frac{1}{N} \sum_{n=1}^{N} \sum_{t=1}^{T} \log y_t, \qquad (12)$$

where T is the length of Y.

Finally, to train our CORSA, we use a joint framework by optimize the following loss,

$$\mathcal{L} = \lambda_D \mathcal{L}^{\text{CRD}} + \lambda_L (\mathcal{L}^{\text{LOC}} + \mathcal{L}^{\text{CLS}}) + \mathcal{L}^{\text{MSA}},$$
(13)

where λ_D and λ_L are two hyper-parameters.

4 Experiment and Analysis

4.1 Experimental settings

Datasets. We use two benchmark datasets, Twitter-15 and Twitter-17 (Yu and Jiang, 2019) for all our experimental evaluations. The statistics of these two datasets are summarized in Table 1. Specifically, Twitter15 has fewer aspects for one sample, and one aspect accounts for 61.6%. In contrast, Twitter17 has more aspects, and multiple aspect accounts for 66.7%. Thus, we could evaluate the

	TWITTER-15			TWITTER-17		
Method	Р	R	F1	Р	R	F1
UMT-collapse (Yu et al., 2020)	61.0	60.4	61.6	60.8	60.0	61.7
OSCGA-collapse (Wu et al., 2020b)	63.1	63.7	63.2	63.5	63.5	63.5
RpBERT-collapse (Sun et al., 2021)	49.3	46.9	48.0	57.0	55.4	56.2
JML (Ju et al., 2021)	65.0	63.2	64.1	66.5	65.5	66.0
VLP (Ling et al., 2022)	65.1	68.3	66.6	66.9	69.2	68.0
CMMT (Yang et al., 2022b)	64.6	68.7	66.5	67.6	69.4	68.5
MOCOLNet (Mu et al., 2023)	66.3	67.9	67.1	67.3	68.7	68.0
AoM (Zhou et al., 2023)	67.9	69.3	68.6	68.4	71.0	69.7
M2DF (Zhao et al., 2023)	67.0	67.3	67.6	67.9	68.8	68.3
Atlantis (Xiao et al., 2024)	65.6	69.2	67.3	68.6	70.3	69.4
MCPL-VLP (Zhang et al., 2024)	67.2	69.2	68.2	69.0	69.4	69.2
RNG (Liu et al., 2024b)	67.8	69.5	68.6	69.5	71.0	70.2
CORSA (Ours)	69.0	70.8	69.9	70.1	71.0	70.6

Table 2: Performance comparison on JMASA task.

model's performance when dealing with various settings.

Evaluation Metrics. For JMASA and MATE tasks, we evaluate the performance of these models by Micro-F1 score (F1), Precision (P), and Recall (R). In addition, following previous works such as (Yu and Jiang, 2019; Zhou et al., 2023), we use Accuracy (Acc) and F1 on MASC task.

Implementation Details. We use AdamW optimizer (Loshchilov and Hutter, 2017) during the training of our CORSA. Specifically, we set the batch size to 32 and the training epoch to 50. The learning rate is set to 7e-5. The two hyperparameters λ_D and λ_L are set to 1.0 and 0.5.

Baselines. We compare three groups of baselines. They correspond to the main task JMASA and two auxiliary ones, i.e., MATE and MASC. The detailed comments are given in Section 5.

4.2 Main Results

We show the performance of CORSA with stateof-the-art baselines on benchmark datasets. The results of the main task, JMASA and the other two tasks, MATE and MASC are reported as follows.

On JMASA. The results for JMASA task are reported in Table 2. Our CORSA model outperforms all multimodal methods on all metrics on Twitter-15 and Twitter-17 datasets. Specifically, our model achieves the improvement of 1.3% and 0.4% with respect to F1 in contrast with the second best model, i.e., RNG, on these two datasets. The results demonstrate the effectiveness of detecting unmet conditional information and localizing exact condition-related regions from the image.

On MATE. As shown in Table 3, our model performs the best in Twitter-15 by 0.1%, which is higher than the second best AoM on F1. The performance of CMMT in Twitter-17 is 0.3% higher than ours. This may due to Twitter-17 containing

	TW	TWITTER-15			TWITTER-17		
Method	Р	R	F1	Р	R	F1	
RAN (Wu et al., 2020a)	80.5	81.5	81.0	90.7	90.7	90.0	
UMT (Yu et al., 2020)	77.8	81.7	79.7	86.7	86.8	86.7	
OSCGA (Wu et al., 2020b)	81.7	82.1	81.9	90.2	90.7	90.4	
JML (Ju et al., 2021)	83.6	81.2	82.4	92.0	90.7	91.4	
VLP (Ling et al., 2022)	83.6	87.9	85.7	90.8	92.6	91.7	
CMMT (Yang et al., 2022b)	83.9	88.1	85.9	92.2	93.9	93.1	
MNER-QG (Jia et al., 2023)	77.4	72.1	74.7	88.2	85.6	86.9	
PGIM (Li et al., 2023)	79.2	79.4	79.3	90.8	92.0	91.4	
MGICL (Guo et al., 2023)	80.3	80.0	80.1	91.0	90.6	90.9	
Prompt-Me-Up (Hu et al., 2023)	80.0	80.9	80.5	91.7	91.3	91.6	
M2DF (Zhao et al., 2023)	85.0	87.2	86.1	91.2	93.0	92.2	
AoM (Zhou et al., 2023)	84.6	87.9	86.2	91.8	92.8	92.3	
Atlantis (Xiao et al., 2024)	84.2	87.7	86.1	91.8	93.2	92.7	
MCPL-VLP (Zhang et al., 2024)	84.8	87.4	86.1	91.9	92.4	92.2	
CORSA (Ours)	85.1	87.6	86.3	92.6	93.0	92.8	

Table 3: Performance comparison on MATE task.

	TWIT	ГER-15	TWIT	ГER-17
Method	ACC	F1	ACC	F1
TomBERT (Yu and Jiang, 2019)	77.2	71.8	70.5	68.0
CapTrBERT (Khan and Fu, 2021)	78.0	73.2	72.3	70.2
FITL (Yang et al., 2022a)	78.7	74.7	73.8	73.0
VEMP (Yang and Li, 2023)	78.88	75.09	73.01	72.42
JML (Ju et al., 2021)	78.7	-	72.7	-
VLP (Ling et al., 2022)	78.6	73.8	73.8	71.8
CMMT (Yang et al., 2022b)	77.9	-	73.8	-
SeqCSG (Wang et al., 2023)	79.3	75.0	74.6	73.2
ARFN (Xiao et al., 2023)	78.50	73.70	70.58	68.43
CoolNet (Huang et al., 2023)	79.92	75.28	71.64	69.58
M2DF (Zhao et al., 2023)	78.9	74.8	74.3	73.0
AoM (Zhou et al., 2023)	80.2	75.9	76.4	75.0
A ² II (Feng et al., 2024)	79.5	75.1	74.3	72.3
Atlantis (Xiao et al., 2024)	79.3	-	74.2	-
AMIFN (Yang et al., 2024)	78.69	75.50	72.29	70.21
MCPL-VLP (Zhang et al., 2024)	79.3	74.9	75.1	74.0
CORSA (Our)	81.1	77.7	76.6	74.5

Table 4: Performance comparison on MASC task.

a larger sample of multiple aspects, as shown in Table 1. Our approach to annotate the conditional relation by averaging the probabilities undermines the conditional relation detection and the sentiment prediction, when dealing with multiple aspects.

On MASC. Table 4 shows the performance of MASC. Our model achieves the best results with the improvement of 0.9% on Accuracy, 1.8% on F1 score on Twitter-15 and 0.2% on Accuracy on Twitter-17. AoM's F1 on Twitter-17 is 0.5% higher than that of our CORSA. In fact, the reason behind is the same as on MATE task. In other words, the inaccuracies in our annotation method is imperfect.

4.3 Ablation Study

In this section, we conduct ablation studies on Twitter-15 and Twitter-17 of the JMASA task.

To verify the effectiveness of CRD and VOL in CORSA, we perform the ablation studies. The results are reported in Table 5. First, we remove CRD. The obtained F1 scores decline by 0.9% on

	TWITTER-15			TW	ITTEF	R-17
Method	Р	R	F1	Р	R	F1
Full CORSA	69.0	70.8	69.9	70.1	71.0	70.6
w/o CRD	68.4	70.0	69.0	69.7	69.6	69.6
w/o VOL	68.1	70.5	69.3	69.4	70.7	70.0
w/o CRD+VOL	67.1	69.1	68.0	68.5	69.7	69.1

Table 5: The performance comparison of our full model and its variants.

TWITTER-15			TW	ITTE	R-17
Р	R	F1	Р	R	F1
69.0	70.8	69.9	70.1	71.0	70.6
66.0	69.7	67.8	68.4	70.0	69.2
66.7	70.4	68.5	69.7	69.3	69.5
67.6	70.7	69.1	70.0	69.8	69.9
68.0	69.7	68.9	69.2	70.3	69.7
69.2	69.3	69.2	68.7	69.1	70.1
69.6	69.5	69.6	69.4	71.2	70.3
	TW 69.0 66.0 66.7 67.6 68.0 69.2 69.6	TWITTER P R 69.0 70.8 66.0 69.7 66.7 70.4 67.6 70.7 68.0 69.7 69.2 69.3 69.6 69.5	TWITTER-15 P R F1 69.0 70.8 69.9 66.0 69.7 67.8 66.7 70.4 68.5 67.6 70.7 69.1 68.0 69.7 68.9 69.2 69.3 69.2 69.6 69.5 69.6	TWITTER-15 TW P R F1 P 69.0 70.8 69.9 70.1 66.0 69.7 67.8 68.4 66.7 70.4 68.5 69.7 67.6 70.7 69.1 70.0 68.0 69.7 68.9 69.2 69.2 69.3 69.2 68.7 69.6 69.5 69.6 69.4	TWITTER-15 TWITTER P R F1 P R 69.0 70.8 69.9 70.1 71.0 66.0 69.7 67.8 68.4 70.0 66.7 70.4 68.5 69.7 69.3 67.6 70.7 69.1 70.0 69.8 68.0 69.7 68.9 69.2 70.3 69.2 69.3 69.2 69.1 69.1 69.6 69.5 69.6 69.4 71.2

Table 6: Ablation results on scales of the visual encoder.

Twitter-15 and 1.0% on Twitter-17. It shows that the damage inflicted by unmet conditional image information and the necessary elimination of such information. Second, we remove VOL. We observe that the model's performance on Twitter-15 and Twitter-17 has also declined notably. The results demonstrate the importance of locating conditionrelated regions. Meanwhile, we notice that the performance decline of removing CRD is more remarkable than that of removing VOL. This demonstrates the significance of the processing sequence, i.e., first eliminating unmet conditional image information and then localizing the exact conditionrelated regions. Third, we remove both CRD and VOL. The decrease in the model's performance shows their contributions to learning the most valuable information.

To show the advantage of using multi-scale features, we perform ablations. Specifically, we compare the performances of using only small scale (i.e., H_{V_1}), middle scale (i.e, H_{V_2}), and large scale (i.e., H_{V_3}), and a combination of any two scales, respectively. The experimental results are reported in Table 6. This result shows the use of multi-scale features facilitates the model's prediction. In addition, small-scale features in our stetting is more beneficial to the model.

To show the effect of two hyper-parameters λ_D and λ_L in our loss, we perform experiments as follows. To be brief, we fix the parameter $\lambda_D =$ 1.0 to evaluate the parameter λ_L . On the other



Figure 3: F1-score against two hyper-parameters λ_D and λ_L on two benchmark datasets for JMASA task.

Threshold	TWITTER-15			TWITTER-17			
$ au_1$	Р	R	F1	Р	R	F1	
0.4	67.5	69.7	68.6	68.8	70.8	69.8	
0.5	67.6	70.2	68.9	70.1	71.0	70.6	
0.6	69.6	69.3	69.4	69.6	70.6	70.1	
0.7	69.0	70.8	69.9	69.0	69.8	69.4	
0.8	68.8	70.5	69.6	68.9	69.5	69.2	

Table 7: The performance comparison of different annotating threshold τ_1 for CRD.

Threshold	TWITTER-15			TW	ITTEF	R-17
$ au_2$	Р	R	F1	Р	R	F1
0.6	68.7	69.5	69.1	69.6	70.2	69.9
0.7	69.8	69.0	69.5	69.2	70.9	70.1
0.8	69.0	70.8	69.9	70.1	71.0	70.6

Table 8: The performance comparison of different annotating thresholds τ_2 for VOL.

hand, we fix the parameter $\lambda_L = 0.5$ to evaluate the parameter λ_D . The experimental results are shown in Figure 3. Therefore, we suppose that our CORSA model is optimal when the two parameters λ_D equals 1.0 and λ_L equals 0.5, respectively.

To show the impact of various thresholds in our annotation data generation, we perform the following experiments. Specifically, we first evaluate the annotating conditional relation with thresholds τ_1 of 0.4, 0.5, 0.6, 0.7, and 0.8. The results are shown in Table 7. The thresholds τ_1 of 0.7 and 0.5 are chosen for Twitter-15 and Twitter-17, respectively. Compared to those in Twitter-15, the aspects in Twitter-17 have better relevance to the corresponding images. Secondly, we evaluate the annotating visual objects with various thresholds τ_2 of 0.6, 0.7 and 0.8. The results are shown in Table 8. Therefore, the threshold τ_2 of 0.8 is chosen.

	TWITTER-15		TW	ITTEF	R-17	
Method	Р	R	F1	Р	R	F1
ChatGPT 3.5	54.3	53.6	55.0	58.2	57.6	58.8
Llama 2	51.4	50.9	51.9	55.8	55.6	56.1
CORSA (Ours)	69.0	70.8	69.9	70.1	71.0	70.6

Table 9: The performance comparison with LLMs on JMASA task.

4.4 Comparison with LLMs

Recently, large-scale language models have evolved extremely rapidly and have advanced language understanding and generation skills in a variety of NLP tasks. Therefore, we conduct experiments on LLMs and MLLMs to compare with CORSA. Firstly, we compare our model with Chat-GPT 3.5 (OpenAI, 2023) and Llama 2 (Touvron et al., 2023) on the JMASA task. Here, we use only text as input, since they cannot support multimodal input. Table 9 shows the result that our model obtains better performance than these two LLMs. Secondly, to demonstrate the superiority of the usage of multimodal input, we compare our model with MLLM, including VisualGLM-6B (Du et al., 2022), Llava 1.5 (Liu et al., 2024a), MMICL (Zhao et al., 2024a), mPLUG-Owl2 (Ye et al., 2024) and GPT4V (OpenAI, 2024) on the MASC task. Table 10 shows the experimental results. The results demonstrate that our model achieves higher performance, even though with fewer parameters.

4.5 Case Study

Figure 4 shows four examples with their predictions from VLP-MABSA (Ling et al., 2022), AoM (Zhou et al., 2023), and our CORSA model.

Consider the left two columns. For the first example, VLP-MABSA and AoM incorrectly predict

Image				If You Vote to Leave the E.U. Then Godzilla Will IV vade the U.KI Vade the U.KI
Text	School holiday program kicks off in Kingston and Glen Eira.	RT @ UberFootball: On this day, 8-years ago, a 19 - year old Lionel Messi did this . Wow .	@ CristianoRonaldo set for a @ M- anUtd return next season # # SSFo- Otball.	David Cameron unveils h- is most convincing argum- ent yet to stay in the EU.
Conditional Relation	Irrelevance	Irrelevance	Relevance	Relevance
GT	(Kingston, NEU) (Glen Eira, NEU)	(Lionel Messi, POS)	(CristianoRonaldo, POS) (ManUtd, NEU)	(David Cameron, NEG) (EU, NEU)
VLP	(Kingston, POS) × (Glen Eira, POS) ×	(Lionel Messi, NEU) ×	(CristianoRonaldo, NEU) × (ManUtd, NEU) √	(David Cameron, NEU) × (EU, NEU) √
AoM	(Kingston, POS) × (Glen Eira, POS) ×	(Lionel Messi, NEU) ×	(CristianoRonaldo, NEU) × (ManUtd, NEU) √	(David Cameron, NEG) ✓ (EU, NEG) ×
CORSA	(Kingston, NEU) ✓ (Glen Eira, NEU) ✓	(Lionel Messi, POS) ✓	(CristianoRonaldo, POS) ✓ (ManUtd, NEU) ✓	(David Cameron, NEG) ✓ (EU, NEU) ✓

Figure 4: The results of the comparison among different methods on four testing samples. The left two columns are two unmet conditional samples; the other two columns are met conditional samples. The ground-truth and predicted bounding boxes for VOL are visualized as red and blue boxes, respectively.

	TWITTER-15		TWITTER-1		
Method	ACC	F1	ACC	F1	
VisualGLM-6B	66.1	68.2	69.0	68.5	
Llava 1.5	77.9	74.3	74.6	74.3	
MMICL	76.0	72.7	74.1	74.0	
mPLUG-Owl2	76.8	72.3	74.2	73.0	
GPT4V	75.3	74.2	76.0	75.5	
CORSA (Our)	81.1	77.7	76.6	74.5	

Table 10: The performance comparison with Multimodal LLMs (MLLMs) on MASC task.

the sentiment of aspects *Kingston* and *Glen Eira* as positive. It is due to the condition that the image contains the objects referred by the aspect *Kingston* and *Glen Eira* cannot be met. And the girl's smiling face misleads incorrect predictions. Our CORSA model filters information about the girl in the image and could predict correctly. The image in the second example does not contain information about *Lionel Messi*. Therefore, for the same reason, VLP-MABSA and AoM wrongly utilize the information, and give incorrect predictions. Our CORSA model obtains the correct predictions due to filtering the unmet conditional image information. The results demonstrate the importance of filtering unmet conditional information from the image.

Consider the right two columns. For the first example, VLP-MABSA and AoM do not correctly predict the positive sentiment in *CristianoRonaldo*. These two methods cannot detect the aspect *CristianoRonaldo* related visual Information, especially the smiling face of the man in the image. Our model explicitly detect the exact condition-related regions with *CristianoRonaldo*, correctly predicting its positive sentiment. Similarly, in the second example, due to the lack of explicitly locating exact condition-related regions, VLP-MABSA and AoM incorrectly predict the sentiments of two aspects. Our model gives correct predictions.

5 Related Work

MABSA consists of three related tasks: MATE, MASC, and JMASA. **On MATE.** Earlier methods (Moon et al., 2018; Arshad et al., 2019; Wu et al., 2020a) adopt cross-modal attention mechanisms. These methods are too simple to effectively learn multimodal information. Recent methods (Yu et al., 2020; Liu et al., 2022; Zheng et al., 2023) use pretrained language models and modality translationbased approaches. With the wide applications of large-scale generative models, Yu et al. (2023) expand Multimodal NER methods to MATE with a generative framework.

On MASC. Existing MASC methods are usually based on attention mechanisms and graph convolutional networks (GCNs). For example, Zhang et al. (2021) introduce an attention network with a discriminative mechanism. Xiao et al. (2023) propose a crossmodal fine-grained alignment and fusion network. Zhao and Yang (2023) propose a fusion model with GCN and SE-ResNeXt network. To solve the problem of irrelevant aspects-images, Wang et al. (2023) design an aspect-oriented filtration module which utilizes the given aspects to

compute attention scores with sentence as well as image. However, this method of calculating the relevance scores between the given aspects to the images cannot transfer well to JMASA, in which the aspects are not given. Recently, some methods adopt LLMs. Feng et al. (2024) propose to use LLVM during the fusion of textual and visual modalities.

On JMASA. Some methods are based on the pipeline framework. Ju et al. (2021) jointly learn MATE and MASC tasks. Yang et al. (2022b) introduce a text-guided cross-modal interaction module to dynamically control the contributions of the visual information. This pipeline approach ignores the potential semantic associations between these two tasks. Other methods are based on generative models. Ling et al. (2022) propose a task specific Vision-Language Pretraining framework. Zhou et al. (2023) propose to detect aspect-relevant semantic and sentiment information. This generative approach could flexibly produce complex text, but their training are time-consuming. Recently, Liu et al. (2024b) propose a framework which implicitly calculates the similarity between the sentences and the images to simultaneously reduce multilevel modality noise and multi-grained semantic gap. However, this method lacks explicit monitoring of aspect-image relevance, and therefore cannot learn fine-grained relations.

Unfortunately, most of previous works ignore the multimodal conditional relations between the images and texts when performing MABSA task. The premise that the image contains the objects referred by the aspects within the text sometimes cannot be met. In this paper, we propose CORSA framework by explicitly considering this issue.

6 Conclusion and Future Work

In this paper, we propose CORSA framwork for MABSA. Our CORSA involves two key modules, CRD and VOL. CRD is designed to mitigate the impact of the unmet conditional image. VOL aims to locate the exact condition-related visual regions with the aspects. We perform two types of annotations on benchmark datasets for training. Extensive experimental results show the effectiveness of our proposed CORSA model. Although our model achieves significant performance, there are still room for improvement. In the future, we consider exploring annotation methods, such as using MLLMs to improve the accuracy of the annotation.

Limitation

Our method still has some limitations. We automatically annotate the data using a pretrained model (UNINEXT), which would cause the problem of inaccuracies. In other words, we have no groundtruth for this conditional relation. Therefore, on one side, we cannot perform accurate statistics on the conditional relation on these two benchmark datasets. On the other side, the inaccuracies affect the CORSA model's performance. These limitations present challenges for further investigations.

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