

TSR@CASE 2025: Low Dimensional Multimodal Fusion Using Multiplicative Fine Tuning Modules

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Abstract

This study describes our submission to the CASE 2025 shared task on multimodal hate event detection, which focuses on hate detection, hate target identification, stance determination, and humour detection on text embedded images as classification challenges. Our submission contains entries in all of the subtasks. We propose FIMIF, a lightweight and efficient classification model that leverages frozen CLIP encoders. We utilise a feature interaction module that allows the model to exploit multiplicative interactions between features without any manual engineering. Our results demonstrate that the model achieves comparable or superior performance to larger models, despite having a significantly smaller parameter count. The source code and model checkpoints are available at github.com/sushant-k-ray/FIMIF

1 Introduction

The landscape of digital communication has evolved dramatically with the widespread adoption of social media platforms, fundamentally transforming how individuals express opinions and share content. This evolution has brought significant challenges in content moderation, particularly in the detection of hate speech that increasingly manifests in the form of memes, which are images with text embedded in them used to convey a message. The CASE (Challenges and Applications of Automated Extraction of Socio-political Events from Text) series has consistently addressed these challenges, with recent editions expanding from text-only analysis to encompass multimodal content understanding (Thapa et al., 2023, 2024).

Building upon the success of previous CASE workshops, the multimodal hate event detection task at CASE 2025 (Thapa et al., 2025a;

Hürriyetoğlu et al., 2025) represents a natural progression toward addressing more complex multimodal hate speech detection scenarios.

In this paper, we introduce FIMIF (Feature Interaction for Multimodal Integration and Fusion), a model conceptually similar to MemeCLIP (Shah et al., 2024). We utilise modified residual units to leverage the capabilities of deep neural networks while keeping the performance stable. We introduce a feature interaction module that automatically learns exponential and multiplicative relationships between features, enabling the model to capture higher-order interactions. While MemeCLIP is designed for general downstream tasks on meme images, our model specifically targets meme classification. Our approach relies on aggressive compression of multimodal embeddings to very low dimensions, followed by a multiplicative module that allows for richer feature interactions. We provide comprehensive experimental evaluation demonstrating the effectiveness of our approach.

2 Related Works

Hate Speech Detection: The task of hate speech detection has progressed from lexicon-based or shallow machine learning approaches (Burnap and Williams, 2015; Waseem and Hovy, 2016; Davidson et al., 2017) to deep learning models (Parihar et al., 2021). The advent of large pre-trained language models brought significant improvements in hate speech detection. BERT (Devlin et al., 2019), RoBERTa (Liu et al., 2019), and DistilBERT (Sanh et al., 2020) introduced contextual embeddings that improved performance on social media hate speech detection. These models have achieved state-of-the-art results on benchmarks such as: HateXplain (Mathew et al., 2021), Offensive Language Identification Dataset (OLID) (Rosenthal et al., 2021), Gab Hate Corpus (Kennedy et al., 2022), and Storm-

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front dataset (de Gibert et al., 2018). These language models are very efficient and powerful in terms of language understanding.

Multimodal Tasks: As harmful content increasingly appears in multimodal forms like memes, research has shifted toward models that process both text and images. Datasets such as Facebook’s Hateful Memes (Kielar et al., 2020) and MMHS150K (Gomez et al., 2020) have been instrumental in advancing this field. Some recent multimodal hate speech detection datasets include Harm-C (Pramanick et al., 2021a), Harm-P (Pramanick et al., 2021b), DisinfoMeme (Qu et al., 2022), and CrisisHateMM (Bhandari et al., 2023). Early multimodal systems use separate encoders (e.g., ResNet (He et al., 2016) for images and BERT for text) and combine features through concatenation or attention. Later models rely on fusion strategies to combine these different representations.

Vision Language Models: Vision-Language models aim to learn joint representations of visual and textual inputs, typically trained on large-scale image-text pairs. These models are broadly divided into two categories: Dual-encoder models, and Fusion models.

Dual-encoder models, such as OpenAI’s CLIP (Contrastive Language-Image Pre-training) (Radford et al., 2021) and Google’s ALIGN (Jia et al., 2021), encode images and text separately and align their embeddings using contrastive loss.

CLIP, in particular, has gained popularity due to its strong zero-shot performance and generalisation ability. Trained on 400 million internet image-text pairs, it can embed both modalities into a shared semantic space.

Low-Rank Multimodal Fusion: One of the key challenges in multimodal learning is the integration of information from multiple modalities. While tensor based fusion methods offer powerful and expressive means of capturing interactions between modalities, they are often computationally expensive and suffer from a rapid increase in parameters, particularly when modelling higher-order interactions across multiple input sources (Zadeh et al., 2017).

To mitigate these challenges, Low-rank Multimodal Fusion (LMF) (Liu et al., 2018) has emerged as a scalable and efficient paradigm. Rather than modelling the full tensor representation, LMF approximates it using modality specific low rank pro-

jections, which are then combined using element-wise operations. This dramatically reduces the parameter count and computational overhead while still retaining cross-modal interactions. LMF scales linearly with the number of modalities, in contrast to the exponential growth in traditional fusion approaches. We adapt a similar principle with the use of additive and multiplicative layers.

Highway And Residual Networks: Highway networks (Srivastava et al., 2015) and Residual networks (He et al., 2016) are widely used to improve training stability and depth in deep learning models. Residual layers mitigate vanishing gradients by adding skip connections, while highway layers introduce trainable gates to control information passage. These ideas motivate our use of lightweight residual projections to preserve essential features without over-fitting.

Multiplicative Modules: The Neural Arithmetic Logic Unit (NALU) (Trask et al., 2018) introduces a mechanism for learning arithmetic operations in neural networks using log-space computations to model multiplicative relationships. Several variants of NALU have been proposed to improve stability and expressiveness in different settings (Schlör et al., 2020; Madsen and Johansen, 2020; Heim et al., 2020). We extend NALU to multimodal classification in a residual framework to maintain flexibility while modelling higher-order relationships.

3 Dataset And Tasks

Shah et al. (2024) released a novel multimodal dataset, PrideMM consisting of text embedded images for classification of various aspects of hate against marginalised LGBTQ+ movement, and community in online discourse through images, particularly memes. The dataset is divided into four classification tasks: hate detection, hate target identification, stance determination, and humour detection.

The multimodal hate task at CASE 2025 utilises the PrideMM dataset, focusing on discrimination and hate against the LGBTQ+ community. The dataset is divided into an 80/10/10 train-validation-test split. This is different from the PrideMM dataset, where the split is 85/5/10. OCR of the images is provided as supplementary material to aid in the process of classification.

The following table shows the distribution of the training samples:

Task	Label	Samples	%
Hate	No Hate	2065	50.99%
	Hate	1985	49.01%
Target	Undirected	617	31.08%
	Individual	199	10.03%
	Community	931	46.90%
	Organization	238	11.99%
Stance	Neutral	1166	28.79%
	Support	1527	37.70%
	Oppose	1357	33.51%
Humour	No Humour	1313	32.42%
	Humour	2737	67.58%

Table 1: Distribution of the training samples in the shared task dataset.

3.1 Tasks

The PrideMM dataset focuses on following four subtasks:

Subtask A: Hate Detection. This task aims to identify instances of hate speech in the images. This task focuses on identifying whether the images intentionally convey hateful sentiments. The training data is balanced (1.04 : 1), and contains a total of 4050 data samples.

Subtask B: Hate Target Identification. This task focuses on identifying the targets of hate in hateful images. There are four categories: Undirected, Individual, Community, and Organization. Images are labeled ‘Undirected’ when they target abstract topics, societal themes, or ambiguous targets. Hateful images targeting specific people are labeled ‘Individual’. The label ‘Community’ is used for instances of hate in images targeting broader social, ethnic, or cultural groups. Images targeting corporate entities, institutions, or similar organizations are labeled ‘Organization’.

The training data is extremely imbalanced (3.1 : 1 : 4.7 : 1.2), and contains data samples for only those images which convey hate. As a consequence, only 1985 data samples are available for training.

Subtask C: Stance Determination. This task aims to determine the stance that the image is trying to convey towards the topic. There are three categories: Support, Oppose, and Neutral. The ‘Support’ label is given to images that express support for the goals of the movement, agree with

efforts to promote equal rights for LGBTQ+ individuals, or promote awareness of the movement. The ‘Oppose’ label is given to images that express disagreement with the goals of the movement, deny the problems faced by individuals who identify as LGBTQ+, or dismiss the need for equal rights and acceptance. The ‘Neutral’ label is given to images that are contextually relevant to the movement but exhibit neither support nor opposition towards the movement.

The training data is fairly well balanced (1 : 1.31 : 1.16), and contains a total of 4050 data samples.

Subtask D: Humour Detection. This task aims to detect whether the image showcases any form of humour, sarcasm, or satire related to the LGBTQ+ pride movement regardless of whether it presents a light-hearted or insensitive perspective on serious subjects.

The training data is imbalanced (1 : 2.08), and contains a total of 4050 data samples.

4 Methodology

In this section, we describe FIMIF (Feature Interaction for Multimodal Integration and Fusion), our proposed model for meme classification. We utilise the CLIP vision-language model to extract multimodal embeddings that effectively encode the semantic content of memes. [Figure 1](#) illustrates the overall architecture of our model. Below, we describe each component in detail.

Pre-Trained CLIP Model: Similar to MemeCLIP, we leverage CLIP encoders for their strong zero-shot generalisation and effective transfer learning capabilities. The CLIP model consists of an image encoder (E_I) and a text encoder (E_T). We freeze the weights of both encoders to retain the knowledge acquired during pre-training. We utilise CLIP ViT-L/14 image encoder pre-trained on 336x336 images instead of 224x224. 336x336 images can better represent high-frequency information than their 224x224 counterparts. [Figure 2](#) presents an example. Note that the use of 336px variant of CLIP’s image encoder does not increase the parameter count of the encoder. The unimodal image and text representations $X_I, X_T \in \mathbb{R}^{768}$ effectively encode the semantic content of a meme and are defined as:

$$X_I = E_I(I); X_T = E_T(T) \quad (1)$$

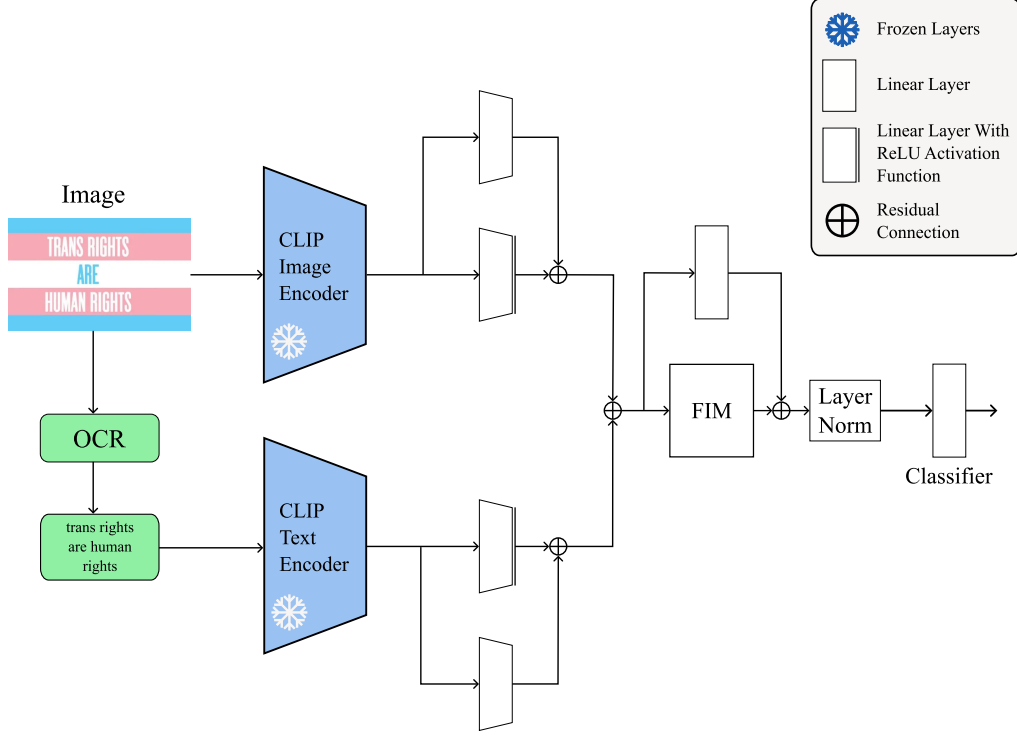


Figure 1: Architecture of our proposed model. Trapeziums are used to represent dimensionality compression.

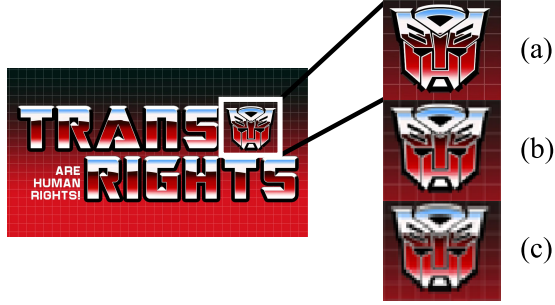


Figure 2: Meme at various resolutions (a) Original resolution (2314x1191) (b) Image downsampled to 336x336 (c) Image downsampled to 224x224. The downscaling and upscaling method used is bicubic interpolation.

where I is the image and T is its corresponding OCR text.

4.1 Linear Residual Projection Layer

Although CLIP is trained to maximise similarity between aligned image-text pairs, the inherently contrastive nature of memes, where visual and linguistic elements often convey conflicting messages, calls for additional adaptation of the embedding space. We hypothesise that only a small subset of elements within the embeddings significantly influence the classification outcome. To capture this, we utilise a modified residual module scheme that

effectively compresses the embedding spaces. A regular residual layer is defined as:

$$R(X) = A(X) + X \quad (2)$$

where A is typically a non-linear function. Our modified residual module, although similar to the one described above, performs better in compressing high-dimensional spaces, particularly when combined with lasso regularisation (Tibshirani, 1996). Our residual module is defined as:

$$R(X) = A(X) + B(X) \quad (3)$$

where A is a non-linear function and B is a linear function. The domain and co-domain for both functions are \mathbb{R}^{768} and \mathbb{R}^h , respectively, where h is a very small number (generally 8, or 16).

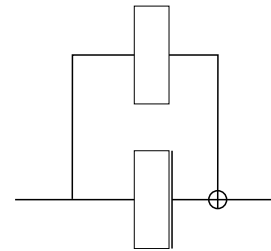


Figure 3: Our Modified Residual Module.

We use a ReLU activation function for A . We utilise this modified residual model for both modalities and combine them to extract linear relations between image and text embeddings. These projection layers result in the bimodal projection $X_{MM} \in \mathbb{R}^h$. Such a layer allows us to leverage the benefits of deep neural network layers while still having the flexibility to use a shallower architecture when required. Our final bimodal residual network is defined as:

$$\begin{aligned} X_{MM} &= R_I(X_I) + R_T(X_T) \\ &= (A_I(X_I) + B_I(X_I)) + \\ &\quad (A_T(X_T) + B_T(X_T)) \end{aligned} \quad (4)$$

4.2 Feature Interaction Module

Since the hidden dimension (h) of the layers is much smaller than CLIP’s embedding dimension, we would have difficulty fusing the text and image representations. To capture the non-linear feature interactions in a compact space, we require a multiplicative network. Conceptually, we would like to have a following module:

$$FIM(X) = \begin{bmatrix} M_0(X) \\ M_1(X) \\ \dots \\ M_{h-1}(X) \end{bmatrix} \quad (5)$$

where,

$$M_i(X) = \prod_{j=0}^{h-1} x_j^{w_{ij}} \quad (6)$$

This module is very generic in nature and can be used for automated feature selection. A module like this, however, would suffer from unstable training due to gradient issues. We design a multiplicative module inspired by Neural Arithmetic Logical Unit (NALU). Rather than directly applying exponentials, we utilise linear arithmetic between inputs in log-space followed by exponentiation. Mathematically, the multiplicative layer can be represented by the following relation:

$$M(X) = B(\exp(W \ln(\text{ReLU}(A(X)) + \epsilon))) \quad (7)$$

where A and B are some linear transformation function with both, domain and co-domain, in \mathbb{R}^h . Since logarithm of non-positive numbers is undefined, we use ReLU along with some ϵ (10^{-5} in our case). This strictly positive condition, however, prevents us from multiplying a positive and a negative

number. While several variants of the NALU, such as iNALU (Schlör et al., 2020) and NAU (Madsen and Johansen, 2020), introduce complex modifications to address this, we propose a simpler alternative that leverages multiple multiplicative layers. We call this the Feature Interaction Module (FIM). Mathematically, it is defined as follows:

$$FIM(X) = M_a(X) \cdot M_b(X) \quad (8)$$

The Feature Interaction Module is shown in the following diagram:

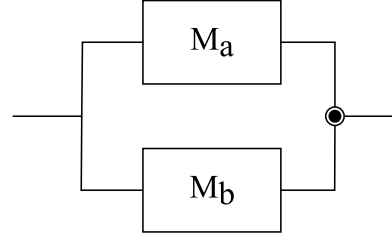


Figure 4: Feature Interaction Module.

We add a residual unit to the FIM in order to allow the network to bypass multiplicative layers if required. The complete residual FIM is defined as:

$$\begin{aligned} F_{MM} &= FIM(X_{MM}) + A(X_{MM}) \\ &= M_a(X_{MM}) \cdot M_b(X_{MM}) + A(X_{MM}) \end{aligned} \quad (9)$$

where A is a linear transformation function with domain and co-domain in \mathbb{R}^h .

4.3 Miscellaneous

Classifier: We apply layer normalisation on the outputs of the residual FIM (F_{MM}) before passing it through the classifier. The classifier is a linear transformation function from \mathbb{R}^h to \mathbb{R}^c , where c is the number of categories in the given subtask. A softmax function maps the final hidden representations to their respective class probabilities. The predicted class corresponds to the highest probability score.

Class Imbalance: There is a heavy class imbalance in the dataset. To get around this issue, we utilise weighted cross-entropy loss. Further, we utilise minority-class deterministic oversampling for subtask B, where there is an extreme class imbalance. The intuition behind this is to expose the model to more samples from minority classes in order to better classify them. Compared to the high dimensionality of the image and text embeddings

Method	# of trainable Parameters	Hate		Target		Stance		Humour	
		Accuracy	F1	Accuracy	F1	Accuracy	F1	Accuracy	F1
Gradient Boosting	-	78.90	78.90	59.44	57.39	61.54	60.52	76.13	70.60
FIMIF (submission)	25k - 51k	81.85	81.85	63.05	60.57	62.92	62.91	79.68	76.83
FIMIF (best)	25k - 51k	81.85	81.85	64.66	64.61	64.89	64.32	79.68	76.83

Table 2: Classification performance of different models on shared task dataset across two evaluation metrics: Accuracy, and F1 score. The hidden dimension of the FIMIF model for subtask A is set to 16, while a reduced hidden size of 8 is used for all other subtasks.

Method	# of trainable Parameters	Hate			Target			Stance			Humour		
		Acc.	AUC	F1	Acc.	AUC	F1	Acc.	AUC	F1	Acc.	AUC	F1
MemeCLIP	2.6M	76.06	84.52	75.09	66.12	81.66	58.65	62.00	80.11	57.98	80.27	85.59	77.21
FIMIF (ours)	25k	78.11	83.99	76.43	68.42	75.97	62.63	63.31	79.84	59.52	80.47	85.54	77.54

Table 3: Classification performance of different models on PrideMM dataset across three evaluation metrics: Accuracy, AUC, and F1 score. Performance metrics for MemeCLIP is sourced from its corresponding paper. The best performance is highlighted in **bold**.

from the CLIP encoders (768 dimensions each), the size of the training set for subtask B is relatively small, consisting of only 1985 samples. This type of high-dimensional data struggles to generalise. Algorithm 1 presents the pseudocode used for upsampling the minority class.

Algorithm 1 Deterministic Class-wise Upsampling.

Require: Dataset D of (x, y) pairs, number of classes C

- 1: Initialise `class_samples`[0... $C - 1$] \leftarrow empty lists
- 2: **for all** $(x, y) \in D$ **do**
- 3: Append (x, y) to `class_samples`[y]
- 4: **end for**
- 5: $M \leftarrow \max_{c \in \{0, \dots, C-1\}} \text{length of } \text{class_samples}[c]$
- 6: `upsampled_dataset` \leftarrow empty list
- 7: **for** $c = 0$ to $C - 1$ **do**
- 8: `samples` \leftarrow `class_samples`[c]
- 9: $n \leftarrow \text{length of } \text{samples}$
- 10: $r \leftarrow \lfloor M/n \rfloor$
- 11: **for** $i = 1$ to r **do**
- 12: Append all elements of `samples` to `upsampled_dataset`
- 13: **end for**
- 14: **end for**
- 15: Shuffle `upsampled_dataset`
- 16: **return** `upsampled_dataset`

Weight Initialisation: All weights and biases in our model are initialised using the Kaiming-Uniform distribution (He et al., 2015), which helps

maintain a stable gradient flow during the initial phases of training. However, for the weight matrix W in eq. 7, we instead use the identity matrix as the initial weights. By using this initialisation, we ensure that the multiplicative interactions introduced by the FIM initially behaves in a linear and interpretable manner. This allows the model to gradually learn multiplicative behaviour only when it is beneficial, rather than being forced into a multiplicative domain from the beginning. This identity initialisation improves the performance and training time by converging in the early training stages. We use the identity and zero matrices as layer-norm initial weights and biases, respectively.

5 Results

We provide results of our model on the test set of the respective subtask in table 2. We use weighted gradient boosting as a baseline for its excellent generalisation capability with high dimensional data.

Method	Acc.	AUC	F1
CLIP	81.62	88.87	79.89
BERT	80.43	88.08	78.90
RoBERTa	77.27	87.95	75.38
DeBERTaV3	79.45	87.94	77.71

Table 4: Classification performance on subtask A (hate) validation set with our model on CLIP’s ViT-L/14@336px image encoder and different text encoders.

Along with our submission results, we have also provided the best results we have encountered so far in order to demonstrate the viability of these very low parameter models. Table 3 compares our results on PrideMM dataset against MemeCLIP

Method	Hidden Dim.	Acc.	Hate AUC	F1	Acc.	Target AUC	F1	Acc.	Stance AUC	F1	Acc.	Humour AUC	F1
CLIP ViT-L/14 (Image Only 224x224)	8	77.87	86.70	75.82	38.71	64.77	36.27	61.46	79.80	59.64	78.85	84.94	71.87
	16	79.84	87.40	78.40	55.65	68.67	48.66	58.50	79.33	55.96	80.04	84.78	74.82
CLIP ViT-L/14@336px (Image Only 336x336)	8	79.05	87.62	77.12	39.92	65.51	37.41	63.44	81.06	60.20	78.46	85.54	74.05
	16	81.03	87.90	79.39	56.85	69.31	49.16	61.46	81.14	59.60	79.64	85.28	75.85
CLIP ViT-L/14@336px + OCR Text	8	83.20	88.72	81.75	60.48	70.77	51.06	64.03	81.65	62.10	79.45	85.02	74.75
	16	81.62	88.87	79.89	47.58	66.43	43.27	64.03	81.20	61.68	79.64	84.45	74.65

Table 5: Our experiments with the use of CLIP’s image encoders on the validation set of shared task dataset. We use three evaluation metrics: Accuracy, AUC, and F1 score. The best performance is highlighted in **bold**.

Method	Hidden Dim.	Acc.	Hate AUC	F1	Acc.	Target AUC	F1	Acc.	Stance AUC	F1	Acc.	Humour AUC	F1
FIMIF	8	83.20	88.72	81.75	60.48	70.77	51.06	64.03	81.65	62.10	73.72	84.86	70.69
	16	81.62	88.87	79.89	47.58	66.43	43.27	64.03	81.20	61.68	81.23	85.03	75.77
- FIM	8	79.05	89.18	76.98	59.68	70.76	50.28	62.65	81.73	60.45	76.68	85.22	73.34
	16	81.23	89.51	79.59	59.27	70.43	51.52	63.44	81.54	60.89	76.68	85.01	73.03
- Upsampling	8	79.05	89.18	76.98	58.47	71.16	50.84	63.44	81.33	60.91	75.10	85.07	71.17
	16	81.23	89.51	79.59	60.48	71.44	50.21	61.46	81.24	58.72	77.87	85.12	73.08
- Weighted Loss	8	78.66	89.04	76.54	60.48	72.26	51.87	61.66	81.22	57.75	80.63	85.22	73.92
	16	82.02	89.45	80.25	58.87	71.64	49.10	60.08	81.34	57.26	79.64	85.47	74.46

Table 6: Ablation experiments performed on the validation set of given shared task dataset.

Hidden Dim.	Acc.	AUC	F1
4	81.23	88.75	79.24
8	83.20	88.72	81.75
16	81.62	88.87	79.89
32	77.27	88.86	75.41
64	81.03	89.22	79.10
128	80.24	88.31	78.64
256	68.77	89.11	63.14

Table 7: Classification performance on the subtask A (hate) validation set across different hidden dimensions of our model. The best performance is highlighted in **bold**.

Method	Acc.	F1
MOMENTA (Pramanick et al., 2021b)	83.82	82.80
PromptHate (Cao et al., 2022)	84.47	-
Pro-Cap (Cao et al., 2023)	85.03	-
MemeCLIP (Shah et al., 2024)	84.72	83.74
FIMIF (ours)	87.01	83.94

Table 8: Performance comparison of meme classification models on the HarMeme-C dataset (binary classification). The best performance is highlighted in **bold**.

on all four subtasks. We compare CLIP’s text encoders with other large language models in table 4. These models are trained in a deterministic manner (having no randomness) in order to compare different methods. CLIP’s text encoder, despite having a shorter context length of 77 tokens, performs better than BERT, RoBERTa, and DeBERTaV3 (He et al., 2023), each supporting a context length of up to 512 tokens. Table 5 compares the results of our model on CLIP ViT-L/14 224px and 336px image encoders on the validation set of the shared task dataset. Table 7 presents a comparison of our model across different hidden dimensions, showing little to no improvement as the dimension size increases, possibly due to over-fitting. Table 8 reports results on the HarMeme-C dataset (Pramanick et al., 2021a), where our model is compared against several state-of-the-art approaches.

5.1 Ablation Study

We have performed our ablation study on the validation set. We compare our model with the one where feature interaction module has been replaced with a linear transformation layer having a non-linear ReLU activation function. The findings in table 6 suggest that the CLIP embeddings of PrideMM dataset is very linear in nature. Due to its residual design, our implementation of feature interaction module is very generic. It can perform just as well, if not better, than a residual module even when the data does not exhibit multiplicative relationships. The difference between these architectures is likely due to the overhead incurred by having a larger number of parameters (3.5 times that of a residual module). Use of upsampling does not seem to have a significant improvement in performance.

Our upsampling scheme should not have any effect on subtasks A and C, where the worst class ratio is less than 2:1. Any difference is likely due to a different shuffling than their non-upsampling counterparts. The use of weighted loss seems to degrade the performance in tasks B and D. However, the difference is not significant.

6 Conclusion

We present FIMIF (Feature Interaction for Multimodal Integration and Fusion), a lightweight parameter-efficient model that leverages CLIP encoders for multimodal meme classification on PrideMM dataset. Our approach relies on aggressive dimensionality compression. A key finding from our ablation study is that the classification problem becomes mostly linear in nature after this compression, indicating that the dimensionality reduction itself is a critical component of our model’s success. Our work highlights the potential of low-dimensional fusion as a viable path toward creating more efficient and sustainable models for complex multimodal tasks.

7 Limitations

Dependence On OCR Quality: The textual input relies heavily on the quality of the OCR. Errors in OCR, such as misread words or missing characters, are directly passed to the text encoder without correction or filtering. Moreover, CLIP’s text encoder has a maximum context length of 77 tokens. This severely limits our model’s ability to classify text-heavy memes. However, [Table 5](#) indicates that the model achieves comparable performance even without OCR.

Lack Of Future Proofing: The world of memes on the Internet evolves rapidly. Words, images, and cultural references can shift in meaning over time. Since our model heavily relies on the frozen CLIP embeddings, it severely limits the ability of our model to adapt to emerging slangs, visual styles, and evolving socio-cultural contexts. This static representation may cause the model’s performance to degrade over time.

8 Ethical Considerations

Environmental Impact: Training deep learning models can have a significant environmental impact, mainly due to high energy consumption and the resulting carbon emissions. To address this,

we designed our model with a very low parameter count, which helps reduce the overall computational load. In practice, the most time-consuming step is the extraction of CLIP embeddings, while the actual training phase is relatively quick and lightweight. Our fine-tuning approach helps the model adapt quickly to new datasets, reducing the need for repeated or prolonged training.

Potential For Misuse: Any technology designed to understand and identify a specific type of content can potentially be used for malicious purposes. A model that learns the constituent elements of hateful memes could be used to generate new, more effective hateful content to systematically find loopholes in other detection systems.

Societal Impact Of Automated Moderation:

The integration of automated moderation systems into digital platforms introduces several ethical concerns with severe societal implications. While such systems enable scalable and timely identification of harmful content, they also risk amplifying existing biases and disproportionately impacting certain user groups ([Thapa et al., 2025b](#)). Models trained on imbalanced or culturally narrow datasets may inadvertently silence marginalised communities, misclassify context-dependent expressions, or fail to generalise across linguistic and cultural boundaries. Automated moderation often lacks transparency and interpretability, limiting users’ ability to understand or contest moderation decisions. This opacity can undermine fairness and accountability, particularly in high-stakes environments where content removal may affect public discourse or individual reputation.

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