

# COUNTDOWN: Contextually Sparse Activation Filtering Out Unnecessary Weights in Down Projection

Jaewon Cheon

Industrial and Management Engineering  
Korea University  
jaewon\_cheon@korea.ac.kr

Pilsung Kang\*

Industrial Engineering  
Seoul National University  
pilsung\_kang@snu.ac.kr

## Abstract

The growing size of large language models has created significant computational inefficiencies. To address this challenge, sparse activation methods selectively deactivate non-essential parameters during inference, reducing computational costs in Feed-Forward Networks (FFN) layers. While existing methods focus on non-linear gating mechanisms, we hypothesize that the sparsity lies globally in the form of a linear combination over its internal down projection matrix. Based on this insight, we propose two methods: M-COUNTDOWN, leveraging indirect coefficients, and D-COUNTDOWN, utilizing direct coefficients of the linear combination. Experimental results demonstrate that D-COUNTDOWN can omit 90% of computations with performance loss as low as 5.5% ideally, while M-COUNTDOWN provides a predictor-free solution with up to 29.4% better performance preservation compared to existing methods. Our specialized kernel implementations effectively realize these theoretical gains into substantial real-world acceleration.

## 1 Introduction

Large Language Models (LLMs) have demonstrated remarkable capabilities across diverse applications, from handling specific tasks to orchestrating agent-based operations (OpenAI et al., 2024; DeepSeek-AI et al., 2024; Gemma Team et al., 2025). However, these advancements came at the cost of dramatically increased model sizes, creating enormous computational and resource demands.

The inference process has emerged as a particularly acute efficiency constraint, forming a critical bottleneck for deploying LLMs in practical applications. This inefficiency is further amplified by recent trends in test-time scaling, where models generate extensive reasoning, significantly increasing computational demands during inference (Jang et al., 2024; Deng et al., 2024). Consequently, research on LLM inference efficiency has intensified,

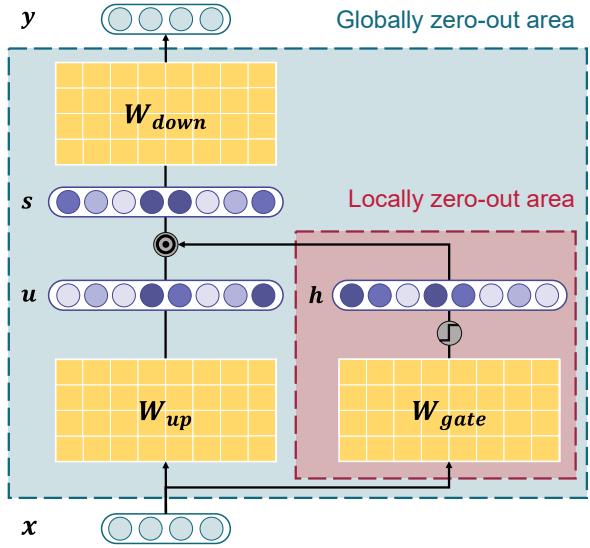


Figure 1: Comparison of sparsity determinations: our approach determines sparsity from the full FFN computation (turquoise box), whereas conventional methods like CATS (Lee et al., 2024) rely solely on non-linear activations (red box).

aiming to reduce latency and memory consumption while preserving generation quality (Liu et al., 2024; Kwon et al., 2023; Cai et al., 2024).

In this context, sparse activation has emerged as a prominent strategy to improve the efficiency of the Feed-Forward Networks (FFN) in LLM (Liu et al., 2023; Lee et al., 2024; Akhouri et al., 2024; Alizadeh et al., 2024). Sparse activation methods dynamically identify and deactivate parameters unnecessary for a given input, thereby reducing computational load and accelerating inference. These methods are particularly beneficial since FFN layers incur significant computational overhead in modern LLM architectures (Awasthi et al., 2024).

The zero-out gating property of ReLU (Agarap, 2019) creates extensive sparsity in FFN layers by forcing a large portion of neurons to output zero (Mirzadeh et al., 2024). This natural sparsity makes computations associated with these zero-valued neurons completely redundant. Existing sparse

activation methods leverage this property to identify and skip these unnecessary computations (Sun et al., 2024; Zhang et al., 2024). However, recent LLMs largely employ activations such as GeLU or SiLU (Hendrycks and Gimpel, 2016; Elfwing et al., 2018) with far less prevalent zero-out behavior (Mirzadeh et al., 2024), limiting these methods’ applicability. Further, Gated-MLP structures, now widely adopted as FFN layers (Shazeer, 2020; Dauphin et al., 2017), introduce more complex parameter interactions than standard architectures. This invalidates the assumption that sparsity occurs only around non-linear activations.

To overcome these limitations, we propose an approach that defines sparsity from a global view, extending beyond the non-linear activations by reformulating the FFN layer’s output as a weighted sum, as illustrated in Figure 1. Based on this approach, we derive two sparse activation methodologies: MONO-COUNTDOWN (M-COUNTDOWN) and DUAL-COUNTDOWN (D-COUNTDOWN). M-COUNTDOWN identifies sparsity based on the output of a single weight matrix in Gated-MLP, while D-COUNTDOWN leverages two weight matrices. In evaluations, M-COUNTDOWN consistently outperforms the baseline method CATS (Lee et al., 2024), achieving up to 29.4% better performance preservation with comparable inference speed. D-COUNTDOWN attains greater efficiency gains, reducing computations by up to 90% in FFN layers with performance loss as low as 5.5% under optimal conditions.

The contributions of this paper are as follows.

- We introduce a novel theoretical framework that redefines sparsity through a weighted-sum perspective over down projection matrices, extending beyond the conventional focus on activation functions.
- We demonstrate that analyzing coefficient vectors in the weighted sum enables superior sparsity decisions, resulting in two distinct approaches with complementary strengths.
- We provide practical acceleration through optimized kernel implementations, enabling both methods to achieve substantial throughput improvements across multiple state-of-the-art LLM architectures.

## 2 Related Works

**ReLU-based Sparse Activation** Early works on sparse activation primarily leveraged the prop-

erty of ReLU to enhance computational efficiency. These approaches identified that ReLU activation functions naturally create substantial built-in sparsity by producing zeros for negative values (Li et al., 2023b). Several approaches have tried to detect these zero-valued activations to preemptively skip associated computations, as these neurons would have no impact on subsequent layers (Mirzadeh et al., 2024). Deja Vu (Liu et al., 2023) extended this concept by training lightweight predictors to anticipate which neurons would be zeroed out, further improving efficiency. While these methods showed impressive speed gains with minimal performance loss, their application faced significant constraints. Notably, these approaches were practical only on architectures explicitly designed with ReLU activations, limiting their applicability as LLMs increasingly adopted alternative activation functions (Akhauri et al., 2024).

**Non-ReLU Sparse Activation** As LLMs evolved to favor non-ReLU activation functions such as GeLU and SiLU, which rarely produce exact zeros, new methods emerged to extend sparsity benefits to these architectures. One direction involved ReLUification techniques that replace non-ReLU functions with ReLU, enabling the reuse of existing sparsity strategies (Song et al., 2024b, 2025; Zhang et al., 2024; Alizadeh et al., 2024). Another approach, such as by CATS (Lee et al., 2024), redesigned sparsity criteria to identify and skip computations associated with near-zero activations rather than exact zeros. While these adaptations improved compatibility with modern LLM architectures, they remain fundamentally constrained by their narrow focus on local patterns around non-linear transformations, overlooking potential sparsity from a global perspective of the FFN layer. This localized perspective may fail to fully capitalize on the potential sparsity distributed throughout modern Gated-MLP architectures, particularly considering the complex interactions among multiple weight matrices that define these structures.

## 3 Generalization of Sparse Activation

**Problem Formulation** A Gated-MLP block consists of three weight matrices:  $W_{up}$ ,  $W_{gate}$ ,  $W_{down} \in \mathbb{R}^{d_{model} \times d_{inter}}$ . For this block, the input vector  $x$  and the output vector  $y$  are in  $\mathbb{R}^{d_{model}}$ . The computation involves intermediate states defined as  $u = x \cdot W_{up}$ ,  $h = \sigma(x \cdot W_{gate})$ ,  $s = u \odot h$  in  $\mathbb{R}^{d_{inter}}$ .

When no sparsification is applied, which we refer to as the Dense scenario, all parameters are activated, and the operation proceeds as follows:

$$y = ((x \cdot W_{up}) \odot \sigma(x \cdot W_{gate})) \cdot W_{down}^T \quad (1)$$

where  $\sigma$  denotes a non-linear activation function, typically GeLU or SiLU.

We now introduce our sparsity propagation framework, establishing sparse activation from a global perspective. We can activate only a valuable subset of weight vectors, with a marginal performance loss. Specifically, sparse activation under our framework follows:

$$y = ((x \cdot W_{up}^I) \odot \sigma(x \cdot W_{gate}^I)) \cdot (W_{down}^I)^T \quad (2)$$

where  $I$  denotes the column of indices of the weights selected for computation:

$$W^I = W[:, IDX], \quad IDX = THLD(\cdot) \quad (3)$$

where  $THLD$  is any function filtering effective  $I$ .

Notably, when individual threshold functions are defined separately for each matrix, identical output can be achieved through the unified intersection  $IDX$ :

$$IDX = IDX_{up} \cap IDX_{gate} \cap IDX_{down} \quad (4)$$

Consequently, even when sparsifying just one matrix and keeping others dense, the computation remains equivalent to applying this unified  $IDX$  across all matrices, which we denote as shared-index property. Thus, if valuable sparsity patterns are identified in one matrix, they can propagate throughout the entire Gated-MLP.

A critical challenge, therefore, is defining the optimal filtering function  $THLD$  to identify the most effective index set  $IDX$  to preserve globally essential computations while significantly reduce computational overhead.

### Limitation of Comparative Methodology

CATS (Lee et al., 2024) partially satisfies our sparsity propagation framework. It identifies sparsity by examining the activation magnitude  $h = \sigma(x \cdot W_{gate})$ , assuming activations squashed near zero indicate parameters to omit. Specifically, given a sparsity ratio  $k \in (0, 1)$ , CATS computes a threshold  $\tau_C^k$  via the  $\text{Quantile}(k, |h|)$  operation, selecting a cutoff below which the lowest  $k$  fraction of activations is excluded. Based on this threshold, CATS defines a sparse activation index as shown in Equation 6a.

CATS leverages the shared-index property. However, since the optimal  $THLD$  might depend on factors beyond non-linear activation region, CATS is theoretically limited in propagating an optimal  $IDX$  throughout the Gated-MLP. Additionally, although  $h[i]$  is large, if the corresponding  $u[i] = x \cdot W_{up}[i]$  is near zero, the final contributions become minimal, which ideally should be filtered out due to their elementwise product.

**Threshold Variants** To overcome these limitations, we reformulate the Gated-MLP computation as a linear combination of the  $W_{down}$  weight vectors, thereby exploring additional possibilities for defining  $THLD$  as follows:

$$\begin{aligned} y &= ((x \cdot W_{up}) \odot \sigma(x \cdot W_{gate})) \cdot W_{down}^T \\ &= \sum_i s[i] \cdot W_{down}^T[i] \end{aligned} \quad (5)$$

This reformulation allows us to interpret output  $y$  as a weighted sum over  $W_{down}^T$  row vectors, where coefficient  $s[i] = ((x \cdot W_{up}) \odot \sigma(x \cdot W_{gate}))[i]$  reflects the  $i$ -th row vector's contribution to computation. The magnitude of these coefficients provides a natural metric for determining which parameters to activate, as they quantify each vector's significance to the output.

Furthermore, since  $s$  is calculated as the elementwise multiplication of  $u = x \cdot W_{up}$  and  $h = \sigma(x \cdot W_{gate})$ , these intermediate vectors can also serve as indirect coefficient signals. This generalized view reveals that each computation stage in the Gated-MLP can provide a distinct sparsity indicator, with selecting  $h$  as the basis being equivalent to CATS's approach.

$$THLD_C^k(h, \tau_C^k) = \{i \mid |h[i]| > \tau_C^k\} \quad (6a)$$

$$THLD_M^k(u, \tau_M^k) = \{i \mid |u[i]| > \tau_M^k\} \quad (6b)$$

$$THLD_D^k(s, \tau_D^k) = \{i \mid |s[i]| > \tau_D^k\} \quad (6c)$$

Based on this view, we propose two variants of sparse activation that extend beyond prior approaches relying solely on the magnitude of  $h$ . As shown in Equation 6, where subscripts C, M, and D denote CATS, M-COUNTDOWN, and D-COUNTDOWN methods respectively, the first method, M-COUNTDOWN, applies thresholding directly to vector  $u$ , while the second method, D-COUNTDOWN, applies thresholding to  $s$ . For each method, thresholds  $\tau_M^k$  and  $\tau_D^k$  are calculated via  $\text{Quantile}(k, |u|)$  and  $\text{Quantile}(k, |s|)$  respectively.

These methods offer complementary strengths: M-COUNTDOWN provides practical implementation with minimal overhead by examining only one matrix multiplication, while D-COUNTDOWN can offer more precise sparsity identification through direct coefficients of the weighted sum. A detailed discussion of these methods follows in section 4

## 4 Implementation of Sparse Activation

**SP<sup>Ideal</sup> and SP<sup>Prac</sup>** In the previous section, we focused on establishing  $THLD$  and the corresponding indicator that theoretically guarantee the safe omission of parameters. Ideally, if these indicators are tractable in real-time inference, we can achieve the upper-bound performance defined by the method. However, accessing the indicator and deriving  $IDX$  from it is not trivial.

Given this constraint, we distinguish between two distinctive perspectives: SP<sup>Ideal</sup> examines the theoretical upperbound performance achievable by each method, assuming that filtering based on sparsity indicators incurs no computational overhead. SP<sup>Prac</sup> accounts for real-world deployment constraints, particularly the latency of identifying sparse activation patterns. It evaluates whether methods can deliver actual inference speedups when all practical overheads are considered.

The distinction is critical because methods with strong SP<sup>Ideal</sup> performance may not translate to SP<sup>Prac</sup> benefits if their practical implementation is computationally expensive. Conversely, focusing solely on SP<sup>Prac</sup> without understanding the theoretical SP<sup>Ideal</sup> limits can lead to suboptimal solutions that fail to approach the best possible performance. Effective sparse activation requires both identifying truly essential computations via SP<sup>Ideal</sup> and creating an efficient implementation to realize total computational savings through SP<sup>Prac</sup>.

**Constructing SP<sup>Prac</sup> for COUNTDOWN** We now describe how to transform the theoretical SP<sup>Ideal</sup> formulations of M-COUNTDOWN and D-COUNTDOWN into efficient, practical SP<sup>Prac</sup> implementations.

For M-COUNTDOWN, the implementation is straightforward because its indicator  $u$  depends only on the matrix  $W_{up}$ . Therefore, its index set  $IDX_M^k$  defined in its SP<sup>Ideal</sup> perspective can be obtained independently of other matrices in the Gated-MLP. This allows M-COUNTDOWN to operate without additional inference-time components, as computation over the remaining matrices can be

selectively skipped based on  $u$ .

To further reduce overhead, we avoid computing  $\tau_M^k$  dynamically for each input. Instead, we approximate it with a layerwise constant  $\hat{\tau}_M^k = \frac{1}{T} \sum_{t=1}^T \text{Quantile}(k, |u^{(t)}|)$  estimated during a calibration phase with  $T$  sampled inputs.

In contrast, implementing D-COUNTDOWN poses greater challenges because its indicator  $s$  requires nearly the entire Gated-MLP computation, negating the advantages of sparse activation. To tackle this challenge, we train a lightweight predictor that estimates the optimal index set  $IDX_D^k$  directly from input  $x$ , avoiding the need to compute  $s$  during inference. For each layer, the predictor outputs a score vector  $\hat{s}$  where:

$$\hat{s}[i] = \begin{cases} +\infty & \text{if } |s[i]| > \text{Quantile}(k, |s|) \\ -\infty & \text{otherwise} \end{cases}$$

Using this output, we define the predicted index set as  $\widehat{IDX}_D^k = \{i \mid \hat{s}[i] > 0\}$  and activate only the corresponding weight columns during inference.

For efficiency, the predictor must be highly accurate and computationally inexpensive during inference. Following (Liu et al., 2023; Alizadeh et al., 2024), we employ a low-rank approximator consisting of two matrices:  $\theta_A \in \mathbb{R}^{d_{\text{model}} \times d_{\text{rank}}}$  and  $\theta_B \in \mathbb{R}^{d_{\text{rank}} \times d_{\text{inter}}}$ , minimizing computational overhead while preserving prediction accuracy. algorithm 1 details the complete training procedure.

**Hardware Aware Kernel Design** Once the sparse activation index set  $IDX$  is determined, computation can be restricted to only the corresponding subset of weights, reducing the actual floating-point operation count (FLOPs). However, reducing FLOPs does not necessarily translate to improved inference latency. For instance, materializing an indexed weight matrix and performing standard vector-matrix multiplication may still reduce FLOPs, but at the cost of increased memory access (Song et al., 2024a; Xue et al., 2024). Therefore, sparse computation should avoid incurring excessive memory traffic solely for the sake of reducing arithmetic operations.

To address this, we implement custom kernels for both M-COUNTDOWN and D-COUNTDOWN using Triton (Tillet et al., 2019). The M-COUNTDOWN kernel builds upon CATS’s structure (Lee et al., 2024), but optimizes it by fusing the non-linear activation to reduce additional memory access. For D-COUNTDOWN, we design a kernel

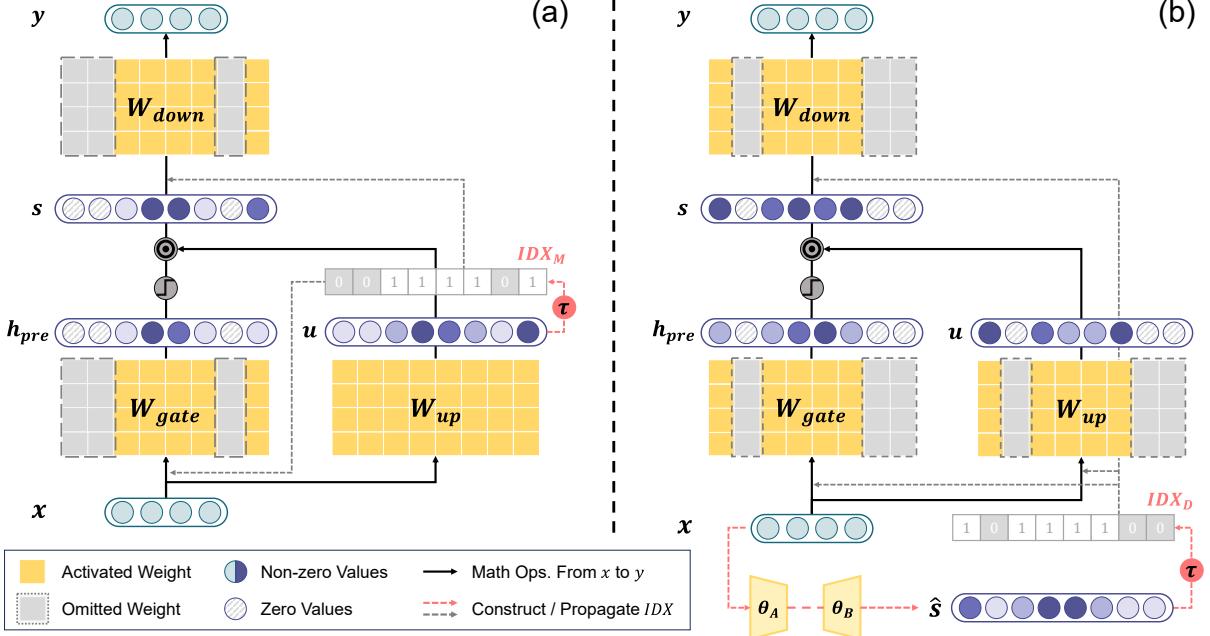


Figure 2: COUNTDOWN Pipeline. Note that  $h_{pre} = x \cdot W_{gate}$ . *Left (a):* In M-COUNTDOWN, we determine which parameters to activate by binarizing densely computed  $u$  with pre-calculated  $\tau_M^k$ . *Right (b):* In D-COUNTDOWN, low-rank predictors ( $\theta_A, \theta_B$ ) determine which parameters to activate.

that efficiently supports predictor-based activation patterns. A naive implementation would require eight separate kernel launches for sparse computation: indexing and GEMV for each of the three matrices, plus non-linear activation and elementwise multiplication. Our implementation compresses this workload into just two kernels. This design ensures that FLOPs reductions directly translate into improved token throughput. Full implementation details and pseudocode are in [algorithm 2](#) and [algorithm 3](#).

## 5 Experiments

**Experimental Setup** We evaluate the proposed methods against other sparse activation baselines, primarily CATS ([Lee et al., 2024](#)), CHESS () and Deja Vu ([Liu et al., 2023](#)). We also include a Dense variant without any sparse activation for comparison. Experiments are conducted using four diverse state-of-the-art LLMs ranging from 8B to 14B parameters: Llama-3.1-8B-Instruct ([Grattafiori et al., 2024](#)), gemma-2-9b-it ([Gemma Team et al., 2024](#)), Qwen2.5-14B-Instruct ([Qwen et al., 2024](#)), and phi-4 ([Abdin et al., 2024](#)). We test multiple sparsity ratios by varying  $k$  from 0.7 to 0.9, representing the fraction of parameters excluded from computation. Implementation details are provided in [Appendix A.2](#).

We examine both model performance preser-

vation and computational efficiency. For model performance, we use the lm-eval-harness ([Gao et al., 2024](#)) framework to assess downstream tasks including ARC ([Clark et al., 2018](#)), HellaSwag ([Zellers et al., 2019](#)), PIQA ([Bisk et al., 2020](#)), OpenbookQA ([Mihaylov et al., 2018](#)), TruthfulQA ([Lin et al., 2022](#)), WinoGrande ([Sakaguchi et al., 2020](#)), and GSM8K ([Cobbe et al., 2021](#)). Unlike prior sparse activation studies, we also evaluate conversational ability using LLM-as-a-Judge framework AlpacaEval 2.0 ([Li et al., 2023a](#)).

To assess computational efficiency and inference speed, we benchmark kernel-level latency to quantify Gated-MLP speedups from sparse activation. We also measure end-to-end token throughput and analyze theoretical reductions in floating-point operations (FLOPs) and memory traffic.

**Downstream Task Performance** As shown in [Table 1](#), in the  $SP^{Ideal}$  setting, D-COUNTDOWN consistently outperforms all methods across all models and sparsity ratios, exhibiting negligible degradation even when compared to the dense baseline. This demonstrates the effectiveness of D-COUNTDOWN’s sparsity criterion: the indicator  $s$  accurately reflects each parameter’s importance to the final output, serving as the coefficient in our linear combination formulation. This provides more informed filtering than methods like CATS which rely solely on gating magnitude. Even at

InferenceMode	Llama-3.1-8B-Instruct			gemma-2-9b-it			Qwen2.5-14B-Instruct			phi-4		
	$k=0.7$	$k=0.8$	$k=0.9$	$k=0.7$	$k=0.8$	$k=0.9$	$k=0.7$	$k=0.8$	$k=0.9$	$k=0.7$	$k=0.8$	$k=0.9$
<b>Dense</b>												
Full	<b>0.616</b>			<b>0.645</b>			<b>0.674</b>			<b>0.655</b>		
<b>SP<sup>Ideal</sup></b>												
DEJAVU	0.314	0.315	0.322	0.360	0.360	0.360	0.379	0.382	0.385	0.398	0.405	0.396
CATS	0.471	0.412	0.337	0.592	0.483	0.367	0.502	0.428	0.389	0.615	0.535	0.427
M-COUNTDOWN	0.570	0.513	0.421	0.624	0.607	0.549	0.644	0.610	0.479	0.636	0.608	0.512
D-COUNTDOWN	<b>0.603</b>	<b>0.587</b>	<b>0.525</b>	<b>0.635</b>	<b>0.625</b>	<b>0.590</b>	<b>0.660</b>	<b>0.647</b>	<b>0.555</b>	<b>0.651</b>	<b>0.649</b>	<b>0.620</b>
<b>SP<sup>Prac</sup></b>												
CATS	0.504	0.450	0.350	0.605	0.502	0.360	0.556	0.478	0.390	0.633	0.591	0.448
M-COUNTDOWN	<b>0.571</b>	<b>0.528</b>	<b>0.447</b>	<b>0.632</b>	<b>0.617</b>	<b>0.588</b>	<b>0.651</b>	<b>0.624</b>	<b>0.535</b>	<b>0.639</b>	<b>0.620</b>	<b>0.555</b>
D-COUNTDOWN	0.442	0.419	0.387	0.555	0.563	0.520	0.526	0.457	0.437	0.499	0.445	0.417

Table 1: Average  $SP^{Ideal}$  and  $SP^{Prac}$  scores compared to Dense across all downstream tasks. Full task-wise results are provided in Appendix C.

90% sparsity, D-COUNTDOWN retains only the most impactful neurons, limiting performance drop to 5.5% in the best case among evaluated models.

M-COUNTDOWN, although less effective than D-COUNTDOWN, consistently outperforms CATS. The gap between the two widens as the sparsity ratio increases, reaching over 29.4%. This demonstrates that M-COUNTDOWN’s indicator  $u$  is more predictive of useful computation than CATS’ indicator  $h$ . This may seem counterintuitive since  $u$  and  $h$  contribute symmetrically via their element-wise product and thus should be equally informative. We revisit this comparison in section 6.

Deja Vu, which assumes ReLU-style zero-out behavior, suffers severe degradation in the  $SP^{Ideal}$  setting. Given its reliance on predictors, which would further degrade under the  $SP^{Prac}$  setting, we excluded it from subsequent experiments.

In the  $SP^{Prac}$  setting, D-COUNTDOWN experiences performance loss relative to the  $SP^{Ideal}$  due to predictor sub-optimality, suggesting better prediction strategies are needed to fully realize its potential in deployment. In contrast, M-COUNTDOWN, thanks to its predictor-free design, exhibits nearly identical performance to its  $SP^{Ideal}$  counterpart. Notably, M-COUNTDOWN continues to outperform CATS across all sparsity settings, reinforcing the effectiveness of its signal even under realistic constraints.

**LLM Chat Performance** While prior studies rely on downstream task accuracy or perplexity, these metrics often fail to capture conversational performance. To address this, we evaluate each method using an LLM-as-a-Judge framework that directly assesses chat-level performance.

As shown in Table 2, M-COUNTDOWN maintains nearly identical performance between the

$SP^{Ideal}$  and  $SP^{Prac}$  settings, while also outperforming CATS in both. D-COUNTDOWN exhibits noticeable degradation in  $SP^{Prac}$  due to predictor limitations, but retains a dominant lead under  $SP^{Ideal}$ . This trend aligns with the results observed in the downstream task evaluations.

InferenceMode	AlpacaEval 2.0		
	$k = 0.7$	$k = 0.8$	$k = 0.9$
<b>SP<sup>Ideal</sup></b>			
CATS	25.10	1.72	0.19
M-COUNTDOWN	45.84	29.22	3.90
D-COUNTDOWN	<b>48.86</b>	<b>45.85</b>	<b>29.95</b>
<b>SP<sup>Prac</sup></b>			
CATS	31.63	10.47	0.25
M-COUNTDOWN	<b>38.31</b>	<b>33.80</b>	<b>15.88</b>
D-COUNTDOWN	3.40	2.81	1.16

Table 2: Average  $SP^{Ideal}$  and  $SP^{Prac}$  win rates against Dense across all models. Full model-wise results are provided in Table 7.

**Efficiency and Speed** To confirm that reductions in computation indeed translate into inference speedups, we measured kernel-level execution latency under various sparsity ratios. Each kernel’s execution time was recorded from the start of the Gated-MLP computation, explicitly excluding other operations like token embedding or attention mechanisms. This allowed us to isolate the precise efficiency gains attributable to sparse activation.

As shown in Figure 3, D-COUNTDOWN achieves the fastest kernel execution time overall, despite the presence of a predictor, by skipping all three weight matrix computations. Although both M-COUNTDOWN and CATS are predictor-free, M-COUNTDOWN slightly outperforms CATS in kernel speed. Given that the only architectural difference between their kernels is whether the non-

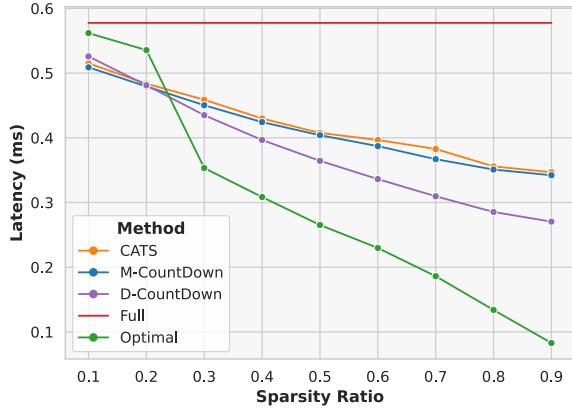


Figure 3: Kernel Speed for Llama-3.1-8B-Instruct. CATS, M-COUNTDOWN and D-COUNTDOWN show their respective  $SP^{Prac}$  kernel speeds, Full and Optimal show Dense while  $\text{int}(d_{inter} \times k)$  instead of  $d_{inter}$  for the Optimal. Results for other models are in Figure 5.

linear activation function is fused, this suggests that M-COUNTDOWN gains a minor but consistent speed advantage by fusing the activation computation, thereby reducing memory traffic and avoiding additional overhead.

Furthermore, we measured average tokens generated per second for generation lengths of 512 and 1024, providing a model-level speedup assessment in typical generation scenarios. As shown in Table 3, M-COUNTDOWN achieves the highest end-to-end token throughput. Meanwhile, D-COUNTDOWN demonstrates the best performance at the kernel level, and with further optimization, its overall throughput may be further enhanced.

## 6 Analysis

**M-COUNTDOWN vs CATS** While CATS and M-COUNTDOWN share similar core ideas for sparse activation, our experimental results show that M-COUNTDOWN consistently achieves better performance. To understand the performance gap between the indirect coefficient vectors  $u$  and  $h$ , we conduct a comparative analysis of how each influences and aligns with the oracle-like reference signal  $s$ , the direct coefficient used in D-COUNTDOWN.

To enable direct comparison, we define binary masks  $S^k$ ,  $U^k$ , and  $H^k$  based on the top- $k$  magnitude entries of each vector. Each mask marks components as “alive” (1) if they survive quantile thresholding, and “dead” (0) otherwise. These binary masks are equivalent to the index sets  $IDX^k$  used for sparse activation, as each represents the support of the corresponding  $IDX^k$  in vector form.

k	Method	FLOPs(M)	Mem.(MB)	Throughput	
				512	1024
0.0	Dense	352.41	168.121	24.64	22.63
	CATS	188.00	89.746	32.62	29.40
	MC	187.95	89.719	33.61	30.32
0.7	DC	<b>124.59</b>	<b>59.480</b>	<b>30.69</b>	<b>27.80</b>
	CATS	164.52	78.550	32.72	29.60
	MC	164.46	78.522	33.80	30.61
0.8	DC	<b>89.37</b>	<b>42.684</b>	<b>30.70</b>	<b>27.57</b>
	CATS	141.02	67.345	32.98	29.81
	MC	140.96	67.318	33.51	30.78
0.9	DC	<b>54.11</b>	<b>25.877</b>	<b>30.73</b>	<b>27.55</b>

Table 3: Theoretical FLOPs and Memory Traffic of Gated-MLP and actual throughput per second at sequence lengths 512 and 1024 for Llama-3.1-8B-Instruct ( $d_{model} = 4096$ ,  $d_{inter} = 14336$ ). MC and DC refer to M-COUNTDOWN and D-COUNTDOWN respectively.

We first define a metric called **Comparative Influential Factor (CIF)** to measure how much influence  $u$  (or  $h$ ) has on the final decision of  $s$ , especially in cases where it overrides the other component. Analogously, for instance,  $\text{CIF}^k(u, \text{alive})$  measures how often  $u$  “rescues” a component that would otherwise have been pruned by  $h$ , allowing it to survive in  $s$  due to its strong contribution. Formally, this is computed as:

$$\text{CIF}^k(u, \text{alive}) = \frac{|S^k \wedge \neg H^k|}{|S^k|} \quad (7)$$

This formulation follows from the definition of  $s$  as the elementwise product of  $u$  and  $h$ . When  $s[i]$  is alive but  $h[i]$  is small enough to be pruned, it implies that  $u[i]$  must have been large enough to compensate, effectively “saving” that entry.

Next, we define the **Comparative Agreement Factor (CAF)** to evaluate how often one signal aligns with  $s$  while the other disagrees. For instance,  $\text{CAF}^k(u, \text{alive})$  measures how frequently  $u$  agrees with  $s$  on keeping a component, specifically when  $h$  disagrees. This is given by:

$$\text{CAF}^k(u, \text{alive}) = \frac{|S^k \wedge \neg H^k \wedge U^k|}{|S^k|} \quad (8)$$

Both CIF and CAF can also be defined symmetrically for the “dead” case by inverting the roles of activation and pruning.

As shown in Figure 4,  $u$  outperforms  $h$  across all sparsity levels in both CIF and CAF. These results suggest that  $u$  more closely reflects the true activation behavior captured by  $s$  and exerts a greater direct impact on sparsity decisions than  $h$ . In other

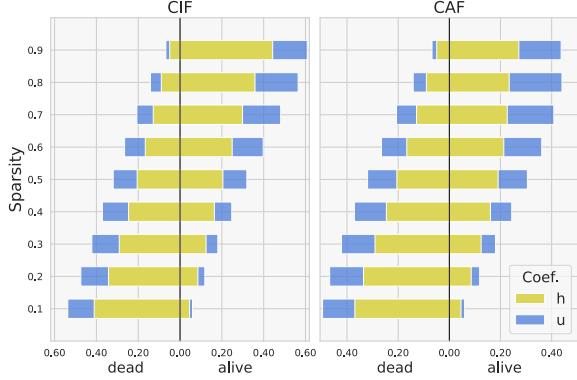


Figure 4: Tornado plots of CIF and CAF across whitening ratios. Bars to the right indicate the proportion of  $\text{CIF}^k(\cdot, \text{alive})$ , while those to the left indicate  $\text{CIF}^k(\cdot, \text{dead})$ .

words,  $u$  is more effective at preserving important activations and filtering out unimportant ones, explaining M-COUNTDOWN’s stable and reliable performance under sparsity.

Nevertheless, since M-COUNTDOWN still relies on an indirect coefficient  $u$ , it cannot fully match the upper-bound performance of D-COUNTDOWN, which uses the full signal  $s$  directly. Despite  $u$ ’s strong CIF and CAF scores, substantial mismatches with respect to the oracle mask  $S^k$  remain, with peak CIF values reaching only about 0.6 and CAF values about 0.4, underscoring the need for future work to translate D-COUNTDOWN’s upper-bound potential into SP<sup>Prac</sup> deployments.

**Possible Predictor Candidate: TernaryLinear** D-COUNTDOWN demonstrates a theoretically sound and effective sparse activation strategy, achieving strong performance in the SP<sup>Ideal</sup> setting. However, in the SP<sup>Prac</sup> scenario, performance degradation occurs due to the predictor’s limited accuracy in recovering optimal sparsity patterns. This reflects the difficulty of the prediction task rather than a flaw in the sparsity criterion itself. The task simultaneously demands precision and computational efficiency, presenting a significant challenge with considerable room for improvement.

To empirically explore this potential, we evaluate an alternative predictor architecture, **TernaryLinear**, whose weights are quantized as  $\theta_{\text{ternary}} \in \{-1, 0, +1\}^{d_{\text{model}} \times d_{\text{inter}}}$ . We compare its performance with the previously utilized low-rank approximator. TernaryLinear achieves significant parameter compression by sacrificing numerical precision while preserving the matrix rank structure. Motivated by recent studies demonstrating successful LLM pretraining with ternary quanti-

Metric	TernaryLinear	Low-Rank
Latency (ms)	0.082	<b>0.030</b>
Theoretical footprint (MiB)	<b>112</b>	144
F1-score (%)	<b>0.435</b>	0.403

Table 4: Comparison between TernaryLinear and the Low-Rank Approximator. Latency for TernaryLinear was measured using the BitBLAS library (Wang et al., 2024). F1 score is reported as the average binary classification performance on  $S^{0.7}$  across all evaluated models.

zation while retaining strong model performance (Ma et al., 2024), we regard TernaryLinear as a promising candidate due to its demonstrated expressiveness even under aggressive quantization.

As shown in Table 4, TernaryLinear outperforms the low-rank baseline in F1 score, while also being more compact in terms of memory footprint. This suggests that preserving rank information, even at the cost of numerical precision, is more effective for sparse mask recovery than the reverse approach.

However, TernaryLinear has not yet been adopted due to its relatively slower runtime despite its small size. This limitation stems not from algorithmic complexity, but rather the lack of optimized GPU kernel support for ultra-low-precision operations. Prior work (Ma et al., 2025) suggests that future advances in kernel optimization and ultra-low-bit quantization are needed to fully leverage such architectures. With these improvements, techniques like TernaryLinear could become viable candidates for enabling D-COUNTDOWN to achieve its full SP<sup>Ideal</sup> performance in SP<sup>Prac</sup> scenarios.

## 7 Conclusion

We introduce COUNTDOWN, a novel sparse activation framework for improving inference efficiency of large language models. To overcome the limitations of traditional non-linear activation-based sparsity, we reformulate the computation as a weighted sum over the FFN’s down projection matrix, effectively capturing inherent sparsity in modern Gated-MLP architectures. From this perspective, we present two complementary strategies: M-COUNTDOWN, which uses  $u$  derived from a single matrix  $W_{up}$  as its activation indicator, achieves faster inference and better performance preservation than prior state-of-the-art methods while remaining predictor-free. D-COUNTDOWN directly leverages  $s$ , the coefficient vector of the weighted sum, for fine-grained sparsity selection, demonstrating robust performance even when skipping 90% of computations under ideal conditions.

## Limitations

Like most prior work on sparse activation, our study assumes a single-batch greedy decoding setting in on-device environments. While this scenario is realistic for latency-sensitive edge inference, it may be less applicable in multi-batch or server-based deployments. In such cases, strategies such as computing the union of predicted index sets  $IDX$  across multiple samples could be explored. However, such an approach would require further investigation into how much parameter activation can be shared across inputs, a direction we leave for future work.

Additionally, our sparsity criteria rely exclusively on activation magnitude. This choice offers clear interpretability and aligns well with the weighted-sum perspective we adopt. Nevertheless, alternative sparsity metrics, such as those explored by (Akhauri et al., 2024), remain an open research avenue. Expanding beyond simple magnitude-based thresholding could further enhance the performance of sparse activation methods.

## Ethical Considerations

We affirm adherence to the ACL Rolling Review (ARR) ethical guidelines, explicitly addressing potential risks and responsible research practices. This research focuses on optimizing computational efficiency in large language models (LLMs), aimed at reducing resource usage and consequently lowering environmental impact. We foresee no direct risks or potential harms to individuals or communities resulting from this work.

Comprehensive details regarding the ethical use of scientific artifacts, reproducibility of computational experiments, and related considerations are thoroughly documented in [Appendix A](#).

## Acknowledgments

This research was supported by Basic Science Research Program through the National Research Foundation of Korea(NRF) funded by the Ministry of Education(No. 2340012238). This work was also supported by Institute of Information & Communications Technology Planning & Evaluation (IITP) grant funded by the Korea government (MSIT) (RS-2025-02214591, Development of an Innovative AI Agent for Worker-Friendly Autonomous Manufacturing), (RS-2024-00460011, Climate and Environmental Data Platform for Enhancing Climate Technology Capabilities in the An-

thropocene (CEDP)), and (RS2021-II211343, Artificial Intelligence Graduate School Program (Seoul National University)). This work was also supported by the National Research Foundation of Korea (NRF) grant funded by the Korea government (MSIT) (RS-2024-00407803, RS-2025-23523657). This work was also supported by the BK21 FOUR Program (Education and Research Center for Industrial Innovation Analytics) funded by the Ministry of Education, Korea (No. 4120240214912).

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## A Experimental Details

### A.1 Hyperparameters for Predictors

Name	Low-Rank( $\theta_A, \theta_B$ )	BitLinear( $\theta_{\text{ternary}}$ )
Loss	Binary Cross Entropy	
Sparsity ratio ( $k$ )	{0.7, 0.8, 0.9}	
Learning rate	{1e-3, 5e-4}	
Training batch size	{16, 32}	
Optimizer	AdamW	
Target	Binary mask $s_{\text{alive}}^k$	
Epochs	{10, 20, 40, 80}	
Seed	42	
Predictor shape $d_{\text{rank}}$	Low-Rank Approximator {128, 256, 512, 1024}	TernaryLinear –
Hardware	1 × NVIDIA A100 80GB	

Table 5: Hyperparameter settings and additional reproducibility details for training predictors used in D-COUNTDOWN. All experiments were conducted using a single run without multiple random seeds.

### A.2 Environments

All experiments were performed on an NVIDIA A100 80GB GPU. We used Triton v3.1.0 for custom kernel development, while the rest of the experimental pipeline was built on HuggingFace Transformers v4.51.3, PyTorch v2.5.1, and CUDA v12.1.

### A.3 Dataset Description

Table 6 summarizes the licenses and dataset statistics used for evaluation.

We evaluate seven Natural Language Understanding(NLU) tasks and one Natural Language Generation(NLG) task focused on mathematical reasoning (GSM8K). All datasets primarily contain English text.

Dataset	License	Train	Test
ARC-Easy	cc-by-sa-4.0	2251 (500)	2376
ARC-Challenge	cc-by-sa-4.0	1119 (500)	1172
HellaSwag	MIT	39905 (500)	10042
PIQA	AFL 3.0	16113 (500)	1838
WinoGrande	apache-2.0	40398 (500)	1267
OpenBookQA	apache-2.0	4957 (500)	500
TruthfulQA	apache-2.0	0	817
GSM8K	MIT	0	1319

Table 6: Summary statistics and licenses for datasets used in evaluation. Following previous research (Akhauri et al., 2024), we used subsets of each downstream task’s training set, each containing 500 examples.

## B Pseudo Codes

### B.1 Training Procedures

D-COUNTDOWN’s predictor training only requires 2 hours for smaller models (Llama-3.1-8B, Gemma-2-9B) and 4 hours for larger models (Phi-4, Qwen2.5-14B) on a single NVIDIA A100 GPU. The resulting predictors are as compact as 576-900MB, representing merely 6-7% of model parameters.

---

**Algorithm 1:** Training the predictor for a Gated-MLP in D-COUNTDOWN

---

**Input:** Training samples  $\{x_j\}_{j=1}^N$ , Target module *GatedMLP*, Target sparsity ratio  $k$   
**Output:** Trained predictor parameters  $\theta$

```

1 foreach training sample  $x_j$  do
2    $s_j \leftarrow$  Compute GatedMLP( $x_j$ );
3    $s_j \leftarrow$  Binarize using Quantile( $k, |s_j|$ );
4 if Predictor is Low-Rank then
5   Initialize parameters  $\theta_A, \theta_B$ ;
6 else if Predictor is TernaryLinear then
7   Initialize parameters  $\theta_{\text{ternary}}$ ;
8 foreach training iteration do
9   Sample mini-batch  $\{x_b, s_b\}$ ;
10  if Predictor is Low-Rank then
11     $\hat{s}_b = x_b \cdot \theta_A \cdot \theta_B$ ;
12  else if Predictor is TernaryLinear then
13     $\hat{s}_b = x_b \cdot \theta_{\text{ternary}}$ ;
14  Compute BCE loss between  $\hat{s}_b$  and  $s_b$ ;
15  Update predictor parameters  $\theta$ ;
```

---

## B.2 Kernel in Detail: M-COUNTDOWN

---

### Algorithm 2: M-COUNTDOWN Inference Kernel (Triton-style)

---

```

Input:  $X, W_{up}, \hat{\tau}_M$ 
Output:  $U, \text{Mask}$ 
1 # PyTorch ;
2  $U \leftarrow X @ W_{up}$  ;
3  $\text{Mask} \leftarrow (|U| \geq \hat{\tau}_M)$  ;

Input:  $X, U, W_{gate}, \text{Mask}, \text{BLK}_M, \text{BLK}_N$ 
Output:  $S$ 
4 # Triton 1 ;
5 start_m  $\leftarrow$  tl.program_id(0) ;
6 rm  $\leftarrow$  start_m  $\times$  BLKM + tl.arange(0, BLKM) ;
7 rn  $\leftarrow$  tl.arange(0, BLKN) ;
8 Mask  $\leftarrow$  Mask + rm ;
9 flag  $\leftarrow$  tl.load(Mask)  $>$  0 ;
10  $W_{gate} \leftarrow W_{gate} + (rm[:, \text{None}] \times d_{model} + rn[\text{None}, :])$  ;
11  $X \leftarrow X + rn$  ;
12 acc  $\leftarrow$  tl.zeros([BLKM]) ;
13 i_mask  $\leftarrow$  flag[:, None] ;
14 foreach block in rm do
15    $w \leftarrow$  tl.load( $W_{gate}$ , mask = i_mask, other = 0) ;
16    $x \leftarrow$  tl.load( $X$ ) ;
17   acc  $\leftarrow$  acc + tl.sum( $w \times x[\text{None}, :]$ , 1) ;
18    $W_{gate} \leftarrow W_{gate} + \text{BLK}_N$  ;
19    $X \leftarrow X + \text{BLK}_N$  ;
20  $U \leftarrow U + rm$  ;
21  $u \leftarrow$  tl.load( $U$ , mask = flag, other = 0) ;
22 acc  $\leftarrow$  silu(acc)  $\times$  u ;
23  $S \leftarrow S + rm$  ;
24 tl.store( $S, acc, \text{mask} = rm < d_{inter}$ ) ;

Input:  $S, W_{down}, \text{Mask}, \text{BLK}_M, \text{BLK}_N$ 
Output:  $Y$ 
25 # Triton 2 ;
26 start_m  $\leftarrow$  tl.program_id(0) ;
27 start_n  $\leftarrow$  tl.program_id(1) ;
28 rm  $\leftarrow$  start_m  $\times$  BLKM + tl.arange(0, BLKM) ;
29 rn  $\leftarrow$  start_n  $\times$  BLKN + tl.arange(0, BLKN) ;
30 Mask  $\leftarrow$  Mask + rm ;
31 flag  $\leftarrow$  tl.load(Mask)  $>$  0 ;
32  $W_{down} \leftarrow W_{down} + (rm[:, \text{None}] \times d_{model} + rn[\text{None}, :])$  ;
33  $S \leftarrow S + rm$  ;
34  $w \leftarrow$  tl.load( $W_{down}$ , mask = flag[:, None], other = 0) ;
35  $x \leftarrow$  tl.load( $S$ ) ;
36 acc  $\leftarrow$  tl.sum( $w \times x[:, \text{None}]$ , 0) ;
37  $Y \leftarrow Y + rn$  ;
38 tl.atomic_add( $Y, acc$ ) ;

```

---

## B.3 Kernel in Detail: D-COUNTDOWN

---

### Algorithm 3: D-COUNTDOWN Inference Kernel (Triton-style)

---

```

Input:  $X, \theta_A, \theta_B, \tau_D$ 
Output:  $\text{Mask}$ 
1 # PyTorch ;
2  $\hat{s} \leftarrow X @ \theta_A @ \theta_B$  ;
3  $\text{Mask} \leftarrow (\hat{s} \geq \tau_D)$  ;

Input:  $X, W_{gate}, W_{up}, \text{Mask}, \text{BLK}_M, \text{BLK}_N$ 
Output:  $S$ 
4 # Triton 1 ;
5 start_m  $\leftarrow$  tl.program_id(0) ;
6 rm  $\leftarrow$  start_m  $\times$  BLKM + tl.arange(0, BLKM) ;
7 rn  $\leftarrow$  tl.arange(0, BLKN) ;
8 Mask  $\leftarrow$  Mask + rm ;
9 flag  $\leftarrow$  tl.load(Mask)  $>$  0 ;
10  $W_{gate} \leftarrow W_{gate} + (rm[:, \text{None}] \times d_{model} + rn[\text{None}, :])$  ;
11  $W_{up} \leftarrow W_{up} + (rm[:, \text{None}] \times d_{model} + rn[\text{None}, :])$  ;
12  $X \leftarrow X + rn$  ;
13 gate  $\leftarrow$  tl.zeros([BLKM]) ;
14 up  $\leftarrow$  tl.zeros([BLKM]) ;
15 i_mask  $\leftarrow$  flag[:, None] ;
16 foreach block in rm do
17    $w_{gate} \leftarrow$  tl.load( $W_{gate}$ , mask = i_mask, other = 0) ;
18    $w_{up} \leftarrow$  tl.load( $W_{up}$ , mask = i_mask, other = 0) ;
19    $x \leftarrow$  tl.load( $X$ ) ;
20   gate  $\leftarrow$  gate + tl.sum( $w_{gate} \times x[\text{None}, :]$ , axis = 1) ;
21   up  $\leftarrow$  up + tl.sum( $w_{up} \times x[\text{None}, :]$ , axis = 1) ;
22    $X \leftarrow X + \text{BLK}_N$  ;
23    $W_{gate} \leftarrow W_{gate} + \text{BLK}_N$  ;
24    $W_{up} \leftarrow W_{up} + \text{BLK}_N$  ;
25 up  $\leftarrow$  up  $\times$  SiLU(gate) ;
26 tl.store( $S, up, \text{mask} = rm < M$ ) ;

Input:  $S, W_{down}, \text{Mask}, \text{BLK}_M, \text{BLK}_N$ 
Output:  $Y$ 
27 # Triton 2 ;
28 start_m  $\leftarrow$  tl.program_id(0) ;
29 start_n  $\leftarrow$  tl.program_id(1) ;
30 rm  $\leftarrow$  start_m  $\times$  BLKM + tl.arange(0, BLKM) ;
31 rn  $\leftarrow$  start_n  $\times$  BLKN + tl.arange(0, BLKN) ;
32 Mask  $\leftarrow$  Mask + rm ;
33 flag  $\leftarrow$  tl.load(Mask)  $>$  0 ;
34  $W_{down} \leftarrow W_{down} + (rm[:, \text{None}] \times d_{model} + rn[\text{None}, :])$  ;
35  $S \leftarrow S + rm$  ;
36  $w \leftarrow$  tl.load( $W_{down}$ , mask = flag[:, None], other = 0) ;
37  $x \leftarrow$  tl.load( $S$ ) ;
38 acc  $\leftarrow$  tl.sum( $w \times x[:, \text{None}]$ , 0) ;
39  $Y \leftarrow Y + rn$  ;
40 tl.atomic_add( $Y, acc$ ) ;

```

---

## C Full Results

All downstream task results are in [Table 11](#) and [Table 12](#). Chat performance results are shown in [Table 7](#). Kernel Speed results are shown in [Figure 5](#). Sparsity<sup>Real</sup> indicates the actual proportion of indicator elements filtered out during SP<sup>Prac</sup> inferences.

Method	Scenario	Llama-3.1-8B			Gemma-2-9B		
		Target Sparsity			Target Sparsity		
		0.70	0.80	0.90	0.70	0.80	0.90
CATS	SP <sup>Ideal</sup>	1.02	0.48	0.50	35.41	2.55	0.00
	SP <sup>Prac</sup> (Win)	3.26	0.55	0.72	40.76	6.72	0.00
	SP <sup>Prac</sup> (Sparsity <sup>Real</sup> )	70.8	80.0	89.7	68.8	79.3	88.1
DC	SP <sup>Ideal</sup>	45.79	39.33	11.85	50.44	48.90	37.79
	SP <sup>Prac</sup> (Win)	1.35	1.57	0.77	6.72	7.99	3.57
	SP <sup>Prac</sup> (Sparsity <sup>Real</sup> )	68.8	71.5	80.8	67.0	72.9	83.2
MC	SP <sup>Ideal</sup>	46.59	2.74	0.60	47.81	41.83	6.91
	SP <sup>Prac</sup> (Win)	9.68	3.19	0.74	48.78	47.88	28.08
	SP <sup>Prac</sup> (Sparsity <sup>Real</sup> )	72.7	82.3	91.0	68.0	77.8	87.6
		Qwen2.5-14B			Phi-4		
CATS	SP <sup>Ideal</sup>	21.94	0.38	0.00	42.05	3.45	0.25
	SP <sup>Prac</sup> (Win)	33.62	7.80	0.00	48.87	26.81	0.31
	SP <sup>Prac</sup> (Sparsity <sup>Real</sup> )	70.0	80.0	89.1	67.6	78.3	89.7
DC	SP <sup>Ideal</sup>	50.10	48.71	32.73	49.10	46.46	37.45
	SP <sup>Prac</sup> (Win)	4.40	0.77	0.20	1.11	0.90	0.12
	SP <sup>Prac</sup> (Sparsity <sup>Real</sup> )	66.6	82.8	87.6	65.4	78.5	86.8
MC	SP <sup>Ideal</sup>	45.01	36.90	2.83	43.96	35.43	5.28
	SP <sup>Prac</sup> (Win)	48.57	42.51	15.89	46.24	41.62	18.82
	SP <sup>Prac</sup> (Sparsity <sup>Real</sup> )	70.0	80.0	90.0	70.1	79.6	89.6

Table 7: Summary of Win Rate on AlpacaEval 2.0

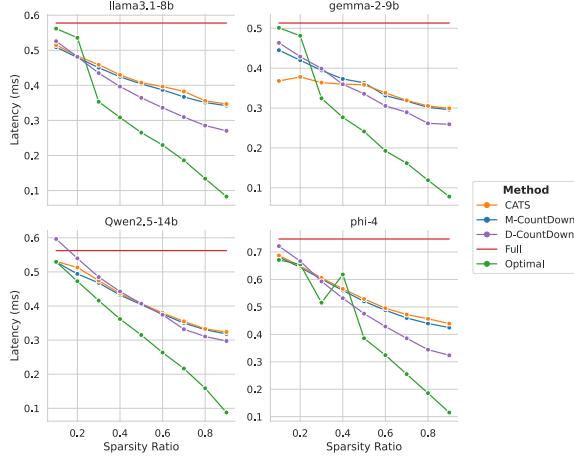


Figure 5: All results for kernel speed.

## D Theoretical Analysis Details

### D.1 Notation

Notation	Explanation
$d_m$	$d_{model}$
$d_i$	$d_{inter}$
$d_r$	$d_{rank}$
$s$	$int(d_{inter} \times k)$
$c_{act}$	act FLOPs (e.g. SiLU $\approx 5$ )

Table 8: Notation Used in Theoretical Analysis

## D.2 Theoretical FLOPs Analysis

Method	Compute	Explanation
Dense	$6 d_m d_i$	Full GEMV $\times 3$
	$+ c_{act} d_i$	Full $\sigma$
	$+ d_i$	Full $\odot$
CATS	$2 d_m d_i$	Full GEMV $W_{gate}$
	$+ c_{act} d_i$	Full $\sigma$
	$+ 2 d_i$	Apply abs and $THLD$
	$+ 2 d_m s$	Sparse GEMV $W_{up}$
	$+ s$	Sparse $\odot$
M-COUNTDOWN	$+ 2 d_m s$	Sparse GEMV $W_{down}$
	$2 d_m d_i$	Full GEMV $W_{up}$
	$+ 2 d_i$	Apply abs and $THLD$
	$+ 2 d_m s$	Sparse GEMV $W_{gate}$
	$+ c_{act} s$	Sparse $\sigma$
D-COUNTDOWN	$+ s$	Sparse $\odot$
	$+ 2 d_m s$	Sparse GEMV $W_{down}$
	$2 d_m d_r$	Low-rank GEMV $\theta_A$
	$+ 2 d_r d_i$	Low-rank GEMV $\theta_B$
	$+ d_i$	Apply $THLD$
D-COUNTDOWN	$+ 4 d_m s$	Sparse GEMV $W_{gate}, W_{up}$
	$+ c_{act} s$	Sparse $\sigma$
	$+ s$	Sparse $\odot$
	$+ 2 d_m s$	Sparse GEMV $W_{down}$

Table 9: Comparison of Theoretical FLOPs Across Methods

## D.3 Theoretical Memory Traffic Analysis

Method	Mem. R/W	Explanation
Dense	$2 d_m d_i$	Read Full $W_{up}, W_{gate}$
	$+ 2 d_m$	Read $x \times 2$
	$+ 2 d_i$	Write gate, up
	$+ d_i$	Read gate
	$+ d_i$	Write act_gate
	$+ 2 d_i$	Read act_gate, up
	$+ d_i$	Write inter
	$+ d_m d_i$	Read Full $W_{down}$
	$+ d_i$	Read inter
	$+ d_m$	Write $y$
CATS	$d_m d_i$	Read Full $W_{gate}$
	$+ d_m$	Read $x$
	$+ d_i$	Write gate
	$+ d_i$	Read gate
	$+ d_i$	Write act_gate
	$+ d_i$	Read act_gate
	$+ d_i$	Write abs_act_gate
	$+ d_i$	Read abs_act_gate
	$+ d_i$	Write mask
	$+ d_m s$	Read Sparse $W_{up}$
	$+ d_m$	Read $x$
	$+ s$	Read Sparse act_gate
	$+ d_i$	Read mask
D-COUNTDOWN	$+ d_i$	Read inter
	$+ d_i$	Write inter
	$+ d_m s$	Read Sparse $W_{down}$
	$+ d_i$	Read inter
	$+ d_m$	Write $y$

Method	Mem. R/W	Explanation
	$d_m d_i$	Read Full $W_{up}$
	$+ d_m$	Read $x$
	$+ d_i$	Write up
	$+ d_i$	Read up
	$+ d_i$	Write abs_up
	$+ d_i$	Read abs_up
	$+ d_i$	Write mask
M-Countdown	$+ d_m s$	Read Sparse $W_{gate}$
	$+ d_m$	Read $x$
	$+ s$	Read Sparse up
	$+ d_i$	Read mask
	$+ d_i$	Write inter
	$+ d_m s$	Read Sparse $W_{down}$
	$+ d_i$	Read inter
	$+ d_m$	Write $y$
	$d_m d_r$	Read $\theta_A$
	$+ d_m$	Read $x$
	$+ d_r$	Write latent
	$+ d_r d_i$	Read $\theta_B$
	$+ d_r$	Read latent
	$+ d_i$	Write $\hat{s}$
	$+ d_i$	Read $\hat{s}$
D-Countdown	$+ d_i$	Write mask
	$+ 2 d_m s$	Read Sparse $W_{up}, W_{gate}$
	$+ d_m$	Read $x$
	$+ d_i$	Read mask
	$+ d_i$	Write inter
	$+ d_m s$	Read Sparse $W_{down}$
	$+ d_i$	Read inter
	$+ d_m$	Write $y$

Table 10: Comparison of Theoretical Memory Traffic Across Methods

Sparsity	Method	ARC-C	TFQA	HS	ARC-E	PIQA	WG	OBQA	GSM8K
<b>Llama-3.1-8B-Instruct</b>									
0.0	DENSE	<b>0.520</b>	<b>0.367</b>	<b>0.590</b>	<b>0.819</b>	<b>0.800</b>	<b>0.737</b>	<b>0.336</b>	<b>0.760</b>
0.7	DEJAVU	0.292	0.229	0.272	0.445	0.553	0.503	0.218	0.000
	CATS	0.453	0.343	0.523	0.754	0.739	0.653	0.298	0.003
	M-COUNTDOWN	0.493	<b>0.372</b>	0.568	0.784	0.776	0.695	0.330	0.544
	D-COUNTDOWN	<b>0.509</b>	0.370	<b>0.592</b>	<b>0.812</b>	<b>0.795</b>	<b>0.727</b>	<b>0.332</b>	<b>0.688</b>
0.8	DEJAVU	0.282	0.231	0.273	0.440	0.557	0.511	0.228	0.000
	CATS	0.358	0.326	0.428	0.651	0.676	0.582	0.278	0.000
	M-COUNTDOWN	0.458	0.343	0.534	0.759	0.748	0.661	0.314	0.288
	D-COUNTDOWN	<b>0.502</b>	<b>0.356</b>	<b>0.585</b>	<b>0.809</b>	<b>0.789</b>	<b>0.713</b>	<b>0.334</b>	<b>0.605</b>
0.9	DEJAVU	0.296	0.230	0.273	0.455	0.557	0.530	0.236	0.000
	CATS	0.293	0.252	0.303	0.495	0.574	0.534	0.242	0.000
	M-COUNTDOWN	0.411	0.304	0.430	0.649	0.676	0.613	0.286	0.001
	D-COUNTDOWN	<b>0.484</b>	<b>0.330</b>	<b>0.548</b>	<b>0.776</b>	<b>0.755</b>	<b>0.680</b>	<b>0.312</b>	<b>0.313</b>
<b>Qwen2.5-14B-Instruct</b>									
0.0	DENSE	<b>0.608</b>	<b>0.517</b>	<b>0.657</b>	<b>0.861</b>	<b>0.817</b>	<b>0.758</b>	<b>0.364</b>	<b>0.807</b>
0.7	DEJAVU	0.336	0.318	0.365	0.612	0.616	0.533	0.254	0.000
	CATS	0.488	0.443	0.585	0.777	0.729	0.629	0.318	0.043
	M-COUNTDOWN	0.573	0.488	0.638	0.829	0.792	0.704	0.352	<b>0.776</b>
	D-COUNTDOWN	<b>0.588</b>	<b>0.518</b>	<b>0.654</b>	<b>0.850</b>	<b>0.801</b>	<b>0.736</b>	<b>0.364</b>	0.770
0.8	DEJAVU	0.340	0.322	0.357	0.609	0.619	0.554	0.258	0.000
	CATS	0.410	0.371	0.472	0.683	0.632	0.568	0.284	0.000
	M-COUNTDOWN	0.532	0.476	0.614	0.813	0.743	0.670	0.352	0.681
	D-COUNTDOWN	<b>0.579</b>	<b>0.488</b>	<b>0.644</b>	<b>0.837</b>	<b>0.799</b>	<b>0.716</b>	<b>0.360</b>	<b>0.751</b>
0.9	DEJAVU	0.358	0.333	0.369	0.612	0.621	0.531	0.256	0.000
	CATS	0.356	0.327	0.385	0.619	0.621	0.547	0.260	0.000
	M-COUNTDOWN	0.468	0.421	0.525	0.736	0.686	0.589	0.304	0.100
	D-COUNTDOWN	<b>0.512</b>	<b>0.436</b>	<b>0.607</b>	<b>0.801</b>	<b>0.756</b>	<b>0.648</b>	<b>0.312</b>	<b>0.371</b>
<b>gemma-2-9b-bit</b>									
0.0	DENSE	<b>0.632</b>	<b>0.433</b>	<b>0.597</b>	<b>0.856</b>	<b>0.812</b>	<b>0.761</b>	<b>0.404</b>	<b>0.663</b>
0.7	DEJAVU	0.339	0.246	0.300	0.596	0.590	0.532	0.276	0.000
	CATS	0.575	0.412	0.559	0.840	0.755	0.680	0.348	0.565
	M-COUNTDOWN	0.605	<b>0.421</b>	0.592	0.849	0.793	0.726	0.374	0.632
	D-COUNTDOWN	<b>0.626</b>	0.417	<b>0.600</b>	<b>0.854</b>	<b>0.800</b>	<b>0.750</b>	<b>0.384</b>	<b>0.649</b>
0.8	DEJAVU	0.346	0.246	0.296	0.599	0.581	0.548	0.262	0.000
	CATS	0.490	0.366	0.486	0.788	0.696	0.604	0.328	0.105
	M-COUNTDOWN	0.583	0.408	0.582	0.842	0.767	0.707	0.360	0.610
	D-COUNTDOWN	<b>0.604</b>	<b>0.421</b>	<b>0.599</b>	<b>0.851</b>	<b>0.796</b>	<b>0.728</b>	<b>0.374</b>	<b>0.624</b>
0.9	DEJAVU	0.356	0.246	0.303	0.616	0.573	0.523	0.264	0.000
	CATS	0.364	0.242	0.310	0.617	0.589	0.537	0.278	0.000
	M-COUNTDOWN	0.534	0.383	0.517	0.799	0.727	0.648	0.344	0.438
	D-COUNTDOWN	<b>0.578</b>	<b>0.410</b>	<b>0.572</b>	<b>0.833</b>	<b>0.777</b>	<b>0.676</b>	<b>0.352</b>	<b>0.524</b>
<b>phi-4</b>									
0.0	DENSE	<b>0.558</b>	<b>0.404</b>	<b>0.632</b>	<b>0.814</b>	<b>0.808</b>	<b>0.766</b>	<b>0.338</b>	<b>0.923</b>
0.7	DEJAVU	0.387	0.311	0.348	0.655	0.626	0.587	0.266	0.000
	CATS	0.536	0.400	0.595	0.794	0.791	0.696	0.304	0.807
	M-COUNTDOWN	0.533	0.384	0.616	0.800	0.796	0.733	<b>0.334</b>	0.888
	D-COUNTDOWN	<b>0.554</b>	<b>0.411</b>	<b>0.630</b>	<b>0.809</b>	<b>0.807</b>	<b>0.752</b>	0.332	<b>0.916</b>
0.8	DEJAVU	0.409	0.333	0.354	0.655	0.632	0.585	0.270	0.000
	CATS	0.516	0.397	0.539	0.771	0.760	0.644	0.298	0.351
	M-COUNTDOWN	0.503	0.386	0.594	0.792	0.778	0.715	0.330	0.767
	D-COUNTDOWN	<b>0.552</b>	<b>0.408</b>	<b>0.622</b>	<b>0.807</b>	<b>0.810</b>	<b>0.755</b>	<b>0.340</b>	<b>0.898</b>
0.9	DEJAVU	0.392	0.317	0.357	0.640	0.630	0.566	0.266	0.000
	CATS	0.426	0.356	0.414	0.676	0.672	0.591	0.280	0.000
	M-COUNTDOWN	0.479	0.370	0.524	0.759	0.728	0.654	0.296	0.287
	D-COUNTDOWN	<b>0.529</b>	<b>0.399</b>	<b>0.601</b>	<b>0.798</b>	<b>0.789</b>	<b>0.695</b>	<b>0.318</b>	<b>0.827</b>

Table 11:  $SP^{ideal}$  scores compared to Dense across all downstream tasks. Dense scores are in bold, as well as the highest score for each task within each sparsity level.

Sparsity	Method	Sparsity <sup>Real</sup>	ARC-C	TFQA	HS	ARC-E	PIQA	WG	OBQA	GSM8K
<b>Llama-3.1-8B-Instruct</b>										
0.7	CATS	0.684	0.461	0.355	0.549	0.778	0.764	0.683	<b>0.316</b>	0.127
	M-COUNTDOWN	0.709	<b>0.484</b>	<b>0.375</b>	<b>0.574</b>	<b>0.788</b>	<b>0.778</b>	<b>0.708</b>	0.310	<b>0.547</b>
	D-COUNTDOWN	0.705	0.422	0.318	0.373	0.748	0.714	0.663	0.298	0.002
0.8	CATS	0.784	0.420	0.322	0.495	0.718	0.721	0.624	0.296	0.000
	M-COUNTDOWN	0.806	<b>0.460</b>	<b>0.361</b>	<b>0.549</b>	<b>0.770</b>	<b>0.757</b>	<b>0.680</b>	<b>0.322</b>	<b>0.322</b>
	D-COUNTDOWN	0.739	0.382	0.306	0.388	0.688	0.673	0.621	0.292	0.003
0.9	CATS	0.902	0.299	0.273	0.323	0.521	0.607	0.537	0.238	0.000
	M-COUNTDOWN	0.895	<b>0.416</b>	<b>0.321</b>	<b>0.471</b>	<b>0.711</b>	<b>0.721</b>	<b>0.620</b>	<b>0.304</b>	<b>0.009</b>
	D-COUNTDOWN	0.843	0.349	0.285	0.345	0.628	0.635	0.593	0.260	0.000
<b>Qwen2.5-14B-Instruct</b>										
0.7	CATS	0.698	0.518	0.460	0.612	0.805	0.761	0.660	0.336	0.293
	M-COUNTDOWN	0.719	<b>0.590</b>	<b>0.509</b>	<b>0.640</b>	<b>0.838</b>	<b>0.792</b>	<b>0.712</b>	<b>0.358</b>	<b>0.767</b>
	D-COUNTDOWN	0.678	0.513	0.426	0.536	0.798	0.748	0.668	0.322	0.197
0.8	CATS	0.802	0.472	0.421	0.551	0.754	0.712	0.627	0.284	0.000
	M-COUNTDOWN	0.804	<b>0.553</b>	<b>0.492</b>	<b>0.625</b>	<b>0.826</b>	<b>0.769</b>	<b>0.669</b>	<b>0.354</b>	<b>0.704</b>
	D-COUNTDOWN	0.827	0.454	0.394	0.468	0.740	0.693	0.615	0.292	0.000
0.9	CATS	0.906	0.347	0.350	0.393	0.631	0.616	0.527	0.258	0.000
	M-COUNTDOWN	0.889	<b>0.492</b>	<b>0.450</b>	<b>0.580</b>	<b>0.794</b>	<b>0.727</b>	<b>0.632</b>	<b>0.320</b>	<b>0.287</b>
	D-COUNTDOWN	0.893	0.434	0.384	0.429	0.689	0.669	0.605	0.282	0.000
<b>gemma-2-9b-bit</b>										
0.7	CATS	0.695	0.580	0.427	0.567	0.843	0.770	0.693	0.368	0.593
	M-COUNTDOWN	0.685	<b>0.608</b>	<b>0.431</b>	<b>0.598</b>	<b>0.854</b>	<b>0.801</b>	<b>0.745</b>	<b>0.386</b>	<b>0.633</b>
	D-COUNTDOWN	0.689	0.567	0.403	0.493	0.821	0.751	0.702	0.364	0.340
0.8	CATS	0.806	0.542	0.392	0.501	0.811	0.729	0.615	0.346	0.083
	M-COUNTDOWN	0.779	<b>0.596</b>	<b>0.412</b>	<b>0.589</b>	<b>0.847</b>	<b>0.788</b>	<b>0.712</b>	0.370	<b>0.618</b>
	D-COUNTDOWN	0.755	0.564	0.401	0.506	0.819	0.758	0.702	<b>0.374</b>	0.381
0.9	CATS	0.911	0.340	0.258	0.306	0.617	0.586	0.514	0.262	0.000
	M-COUNTDOWN	0.875	<b>0.573</b>	<b>0.395</b>	<b>0.554</b>	<b>0.829</b>	<b>0.761</b>	<b>0.686</b>	<b>0.360</b>	<b>0.544</b>
	D-COUNTDOWN	0.853	0.529	0.383	0.492	0.806	0.747	0.665	0.354	0.187
<b>phi-4</b>										
0.7	CATS	0.675	0.539	<b>0.417</b>	0.613	0.801	0.795	0.724	0.322	0.856
	M-COUNTDOWN	0.707	<b>0.540</b>	0.393	<b>0.620</b>	<b>0.804</b>	<b>0.796</b>	<b>0.736</b>	<b>0.332</b>	<b>0.894</b>
	D-COUNTDOWN	0.687	0.471	0.368	0.485	0.750	0.733	0.685	0.294	0.208
0.8	CATS	0.771	0.525	<b>0.390</b>	0.587	<b>0.795</b>	<b>0.786</b>	0.673	0.300	0.675
	M-COUNTDOWN	0.799	<b>0.527</b>	0.381	<b>0.607</b>	0.793	0.784	<b>0.715</b>	<b>0.334</b>	<b>0.817</b>
	D-COUNTDOWN	0.815	0.418	0.343	0.438	0.707	0.692	0.657	0.268	0.036
0.9	CATS	0.889	0.458	0.360	0.460	0.713	0.692	0.605	0.294	0.000
	M-COUNTDOWN	0.894	<b>0.498</b>	<b>0.386</b>	<b>0.563</b>	<b>0.777</b>	<b>0.750</b>	<b>0.698</b>	<b>0.316</b>	<b>0.450</b>
	D-COUNTDOWN	0.895	0.408	0.294	0.404	0.674	0.668	0.616	0.270	0.000

Table 12: SP<sup>Prac</sup> scores compared across all downstream tasks. Bold indicates the highest score at each sparsity level for each task.