

KGE Calibrator: An Efficient Probability Calibration Method of Knowledge Graph Embedding Models for Trustworthy Link Prediction

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Abstract

Knowledge graph embedding (KGE) models are designed for the task of link prediction, which aims to infer missing triples by learning representations for entities and relations. While KGE models excel at ranking-based link prediction, the critical issue of probability calibration has been largely overlooked, resulting in uncalibrated estimates that limit their adoption in high-stakes domains where trustworthy predictions are essential. Addressing this is challenging, as we demonstrate that existing calibration methods are ill-suited to KGEs, often significantly degrading the essential ranking performance they are meant to support. To overcome this, we introduce the KGE Calibrator (KGEC), the first probability calibration method tailored for KGE models to enhance the trustworthiness of their predictions. KGEC integrates three key techniques: a Jump Selection Strategy that improves efficiency by selecting the most informative instances while filtering out less significant ones; Multi-Binning Scaling, which models different confidence levels separately to increase capacity and flexibility; and a Wasserstein distance-based calibration loss that further boosts calibration performance. Extensive experiments across multiple datasets demonstrate that KGEC consistently outperforms existing calibration methods in terms of both effectiveness and efficiency, making it a promising solution for calibration in KGE models¹.

1 Introduction

Knowledge graphs (KGs) are essential resources for a wide range of knowledge-driven tasks, including semantic search (Xiong et al., 2017), knowledge reasoning (Liu et al., 2021), question answering (Shen et al., 2019; Ye et al., 2023), and Neuro-Symbolic AI (Yang and Curry, 2025). Prominent

| Query: (Greece, _member_of_domain_region, ?) | |
|--|---------------------|
| True answer: sibyl | |
| Ranked candidate entities | Uncalibrated scores |
| Greece | -0.1873 |
| Holy_See | -0.2946 |
| sibyl | -0.5992 |
| Colosseum | -0.8017 |
| Sistine_Chapel | -0.8683 |

Figure 1: Uncalibrated scores for a query from WN18RR (Dettmers et al., 2018) produced by the TransE model (Bordes et al., 2013). Although the correct entity (“sibyl”) is highly ranked, the uncalibrated scores lack probabilistic interpretability, highlighting the need for calibration.

large-scale KGs such as YAGO (Suchanek et al., 2007), DBpedia (Lehmann et al., 2015), and Freebase (Bollacker et al., 2008) encompass millions of entities and hundreds of millions of relational facts, which are typically structured as sets of $\langle \text{head entity}, \text{relation}, \text{tail entity} \rangle$ triples.

However, most KGs are incomplete due to extraction errors and limited input resources. This makes link prediction, also known as knowledge graph completion, crucial for inferring missing links and improving KG quality. To this end, knowledge graph embedding (KGE) models such as TransE (Bordes et al., 2013) and ComplEx (Trouillon et al., 2016) tackle this problem by learning latent representations of entities and relations to score the plausibility of candidate triples. Beyond link prediction, KGE models have demonstrated remarkable success across diverse applications, including entity alignment (Sun et al., 2018) and canonicalization (Shen et al., 2022).

While the ranking accuracy of KGE models has seen significant advancements, the critical issue of probability calibration remains largely overlooked. Specifically, KGE models should output calibrated probabilities alongside their predictions. How-

¹Codes available at <https://github.com/Yang233666/KGE-Calibrator>

ever, they typically produce uncalibrated scores (Pezeshkpour et al., 2020; Tabacof and Costabello, 2020). This stems from link prediction being framed as a ranking task, where metrics like Mean Rank (MR) and HITS@N prioritize relative ordering while ignoring the reliability of output scores. As a result, KGE models can assign implausible scores to correct entities yet still perform well, as shown in Figure 1. This shortcoming limits their applications in high-stakes domains such as drug and protein target discovery (Zeng et al., 2022; Mohamed et al., 2020), where calibrated estimates are essential.

To address this critical issue, increasing attention has been directed toward the probability calibration task of KGE models, which aims to convert the uncalibrated scores assigned to candidate triples into well-calibrated probability estimates. As a post-processing technique, calibration improves the trustworthiness of link prediction results, making them more reliable for downstream applications. However, probability calibration in KGE poses unique challenges compared to traditional classification. Image classification datasets like CIFAR-100 (Krizhevsky et al., 2009) or document classification datasets like SST (Socher et al., 2013) involve tens or hundreds of classes. In contrast, KGE tasks treat each entity as a distinct class. This creates a massive class space, a challenge present even in standard benchmarks (e.g., FB15K and WN18RR contain 14,951 and 40,943 entities, respectively). This high cardinality yields extremely small per-class probabilities and makes calibration highly sensitive. On WN18RR, for instance, we empirically observe that 99.1% of uncalibrated scores produced by TransE fall below 10^{-4} , highlighting the dominance of near-zero values. Even small perturbations in such distributions can distort the original ranking and negatively affect link prediction performance. Therefore, preserving the original ranking quality becomes a critical requirement, posing a distinctive challenge for probability calibration in the KGE setting.

Despite its importance and unique challenges, probability calibration in KGE remains largely underexplored. Prior studies (Tabacof and Costabello, 2020; Pezeshkpour et al., 2020) have shown that popular KGE models produce poorly calibrated scores, resulting in unreliable probability estimates. Several off-the-shelf calibration methods, such as Platt Scaling, Isotonic Regression, and Temperature Scaling, have been evaluated (Safavi et al.,

2020; Zhu et al., 2022), but these methods are designed for standard classifiers and are not well-suited to the scale and ranking-sensitive nature of KGE. A few works have explored calibration in specific tasks, including triple classification (Tabacof and Costabello, 2020), relation prediction (Safavi et al., 2020), and low-dimensional entity expit transformations (Wang et al., 2021). However, no existing approach offers a calibration method explicitly tailored to the probabilistic characteristics of KGE models. This leaves a critical gap in improving the trustworthiness of KGE-based link prediction.

To fill this gap, we propose KGE Calibrator (KGEC), the first probability calibration method tailored specifically for KGE models. To enhance training efficiency under the large-scale class space characteristic of KGE, we introduce the Jump Selection Strategy, which selects the most informative instances while discarding less significant ones. To increase model expressiveness and better capture the ranking-sensitive nature of KGE predictions, we propose Multi-Binning Scaling, which models different probability levels separately, thereby increasing model capacity and flexibility. Additionally, we propose a Wasserstein distance-based loss function to further boost calibration performance. To the best of our knowledge, this is the first use of the Wasserstein distance for probability calibration.

Contributions. Our major contributions can be summarized as follows:

- We demonstrate that five of nine widely-used post-hoc calibration methods degrade link prediction performance for KGE entity prediction, indicating they are unsuitable in this setting.
- We propose KGEC, the first probability calibration method specifically designed for KGE models, which addresses the challenge of large class space in calibration while preserving the original ranking performance.
- A thorough experimental study over four datasets demonstrates that KGEC consistently outperforms existing calibration methods in both performance and efficiency.

2 Related Work

Probability Calibration in KGE Models. Several studies have highlighted that KGE models produce poorly calibrated probability estimates. Early work by (Tabacof and Costabello, 2020) and (Pezeshkpour et al., 2020) showed that widely used KGE models are poorly calibrated in triple

classification tasks. To address this, (Tabacof and Costabello, 2020) applied Platt Scaling (Platt et al., 1999) and Isotonic Regression (Zadrozny and Elkan, 2002), while (Safavi et al., 2020) explored Matrix Scaling and Vector Scaling (Guo et al., 2017) in relation prediction. A broader evaluation by (Zhu et al., 2022) tested additional off-the-shelf calibration techniques, including Histogram Binning (Zadrozny and Elkan, 2001), Beta Calibration (Kull et al., 2017), and Temperature Scaling (Guo et al., 2017) for triple classification. Furthermore, (Rao, 2021) examined calibration under both closed-world and open-world assumptions. While these works shed light on the calibration issue in KGE, they all rely on existing techniques originally designed for traditional classification problems. None propose a calibration method specifically tailored for KGE models, leaving a critical gap in the literature. For completeness, we provide a summary of calibration methods explored in prior KGE studies in Table 4 (Appendix A.1).

Expit Transformations. Expit transformations aim to convert uncalibrated scores into probabilities using functions such as the Sigmoid (Nickel et al., 2015; Tabacof and Costabello, 2020; Zhu et al., 2022) and Softmax (Pezeshkpour et al., 2020). Other approaches include neighborhood intervention consistency (NIC) (Wang et al., 2021) and min-max scaling (Rao, 2021). However, recent research (Zhu et al., 2022) has shown that even when expit-transformed scores can be interpreted as probabilities, they are still uncalibrated and unreliable. As a result, these expit transformations are generally viewed as a preliminary step, typically followed by a dedicated calibration method such as Platt Scaling or Isotonic Regression. In fact, (Zhu et al., 2022) concluded that expit transformations are ineffective in most cases and suggested probability calibration as a better approach. Following this direction, our work focuses exclusively on probability calibration and does not include expit transformations as part of our method design.

3 Preliminaries

Notations. We use calligraphic font for sets (e.g., \mathcal{E}). Matrices are denoted by bold uppercase (e.g., $\mathbf{P} \in \mathbb{R}^{n \times m}$). Row and column vectors extracted from a matrix are bold lowercase (e.g., the i -th row $\mathbf{p}_i \in \mathbb{R}^{1 \times m}$ and the j -th column $\mathbf{p}^j \in \mathbb{R}^{n \times 1}$). Standalone vectors (e.g., an embedding \mathbf{h} or a vector of probability estimates \mathbf{p}) are also bold lowercase.

The vector of calibrated estimates is distinguished with a hat (e.g., $\hat{\mathbf{p}}$). Scalars are denoted by plain italic letters (e.g., n, m).

Knowledge Graph. A knowledge graph (KG) \mathcal{G} consists of a set of triples (h, r, t) , where each triple includes a head entity $h \in \mathcal{E}$, a tail entity $t \in \mathcal{E}$, and a relation $r \in \mathcal{R}$ connecting head and tail. Here, \mathcal{E} and \mathcal{R} refer to the sets of entities and relations of \mathcal{G} respectively, and $m = |\mathcal{E}|$ denotes the total number of entities.

Knowledge Graph Embeddings. Knowledge graph embedding (KGE) models aim to represent each head entity h , relation r , and tail entity t from a KG \mathcal{G} as d -dimensional continuous embeddings \mathbf{h} , \mathbf{r} , and $\mathbf{t} \in \mathbb{R}^d$. A core component of the KGE model is its score function ψ , which evaluates the plausibility of a triple (h, r, t) by computing a compatibility score $\psi(\mathbf{h}, \mathbf{r}, \mathbf{t})$ from the corresponding embeddings. Table 10 in Appendix F lists the score functions of the most widely used KGE models.

Link Prediction. Link prediction, the primary downstream task for KGE models, encompasses both entity prediction and relation prediction. Entity prediction is generally more challenging due to the large number of candidate entities. For example, the widely used WN18RR (Dettmers et al., 2018) dataset contains 40,943 entities but only 11 relations. In this paper, we focus on the more challenging entity prediction task, which includes both head and tail prediction.

For head prediction, given a query $(?, r, t)$, each entity $e_i \in \mathcal{E}$ is treated as a candidate for the missing head entity. The trained KGE model assigns a score $\psi(\mathbf{e}_i, \mathbf{r}, \mathbf{t})$ to each candidate triple (e_i, r, t) , where e_i is a candidate head entity, and r and t are the given relation and tail entity. These scores are then ranked, with higher-ranked triples considered more plausible, indicating that the corresponding entity e_i is a likely answer to the query $(?, r, t)$. The task of tail prediction is defined analogously for queries of the form $(h, r, ?)$.

KGE Probability Calibration. Given a head-entity query $(?, r, t)$, a KGE model with score function ψ first produces an uncalibrated score vector over all m entities:

$$\mathbf{s} = [\psi(\mathbf{e}_1, \mathbf{r}, \mathbf{t}), \dots, \psi(\mathbf{e}_m, \mathbf{r}, \mathbf{t})]^\top \in \mathbb{R}^m, \quad (1)$$

where \mathbf{s} is the uncalibrated score vector. These scores are typically converted into an initial vector of uncalibrated probability estimates \mathbf{p} using an expit transformation such as the Softmax function (σ_{SM}), where $\mathbf{p} = \sigma_{\text{SM}}(\mathbf{s})$. However, these

Table 1: Effect of calibration on TransE’s ranking performance (FB15K). Lower MR indicates better performance; higher MRR and HITS@K are better. \downarrow denotes performance degradation compared to the uncalibrated (Uncal) baseline. Methods shown are Platt Scaling (PS), Histogram Binning (HB), Isotonic Regression (IR), Bayesian Binning into Quantiles (BBQ), Vector Scaling (VS), Matrix Scaling (MS), Temperature Scaling (TS), Meta-Cal, Parametrized Temperature Scaling (PTS), and our proposed KGEc.

| Method | MR | MRR | HITS@1 | HITS@3 | HITS@10 |
|--------------|-------------------|--------------------|--------------------|--------------------|--------------------|
| FB15K | | | | | |
| Uncal | 40 | 0.731 | 0.646 | 0.793 | 0.865 |
| PS | 40 | 0.731 | 0.646 | 0.793 | 0.865 |
| HB | 2275 \downarrow | 0.570 \downarrow | 0.510 \downarrow | 0.614 \downarrow | 0.670 \downarrow |
| IR | 982 \downarrow | 0.615 \downarrow | 0.530 \downarrow | 0.675 \downarrow | 0.761 \downarrow |
| BBQ | 1275 \downarrow | 0.589 \downarrow | 0.509 \downarrow | 0.646 \downarrow | 0.726 \downarrow |
| VS | 41 \downarrow | 0.730 \downarrow | 0.646 | 0.791 \downarrow | 0.862 \downarrow |
| MS | 3687 \downarrow | 0.038 \downarrow | 0.024 \downarrow | 0.039 \downarrow | 0.061 \downarrow |
| TS | 40 | 0.731 | 0.646 | 0.793 | 0.865 |
| Meta-Cal | 1149 \downarrow | 0.677 \downarrow | 0.604 \downarrow | 0.735 \downarrow | 0.787 \downarrow |
| PTS | 40 | 0.731 | 0.646 | 0.793 | 0.865 |
| KGEc | 40 | 0.731 | 0.646 | 0.793 | 0.865 |

estimates often provide poor reflections of the true likelihoods (Zhu et al., 2022).

The goal of probability calibration is to learn a mapping that transforms the uncalibrated estimates \mathbf{p} into calibrated estimates $\hat{\mathbf{p}}$, such that each element \hat{p}_i more faithfully reflects the likelihood of correctness for the i -th candidate. Addressing this challenge for KGE models is the primary focus of this work. After calibration, the predicted answer \hat{y} to the query and its associated calibrated confidence are obtained as:

$$\hat{y} = \arg \max(\hat{\mathbf{p}}), \quad \hat{p} = \max(\hat{\mathbf{p}}), \quad (2)$$

where \hat{y} denotes the most likely entity and \hat{p} quantifies the calibrated confidence in this prediction.

Calibration Method Evaluation. To motivate our work, we first demonstrate that preserving ranking performance is a non-trivial requirement that many standard calibration methods fail to meet. We evaluate a set of widely used post-processing methods² in the context of entity prediction. Specifically, we consider nine representative methods and examine whether they preserve or degrade the ranking performance of KGE models after calibration.

Table 1 presents the results of applying these calibration methods to the TransE model on the FB15K dataset. The results reveal the following observations: (1) HB, IR, BBQ, MS, and Meta-Cal substantially degrade performance, making them

²Brief descriptions of these calibration methods are provided in Appendix A.2.

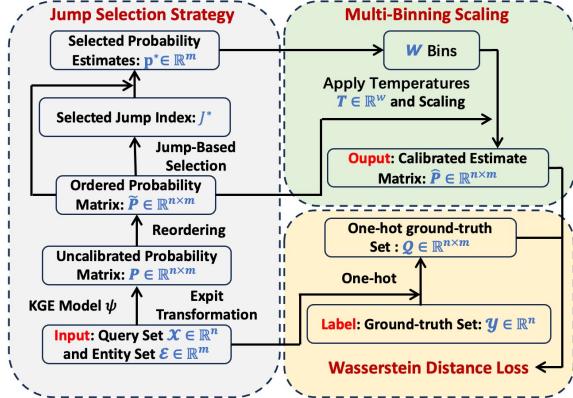


Figure 2: An illustration of the proposed KGEc method.

unsuitable as calibrators for KGE models in the entity prediction task; (2) PS, TS, and KGEc successfully preserve the original ranking performance, demonstrating their suitability for this task; (3) VS slightly degrades performance on FB15K, but given that the decline is minor, so its overall impact remains acceptable.

These findings suggest that not all well-known calibration methods are compatible with KGE-based entity prediction. For a more comprehensive view, the detailed results for additional KGE models across multiple datasets are reported in Tables 5–8 in Appendix B.

4 KGE Calibrator

Figure 2 presents an overview of our proposed KGE Calibrator (KGEc). We begin by describing the Jump Selection Strategy and Multi-Binning Scaling, followed by the Wasserstein distance-based loss function.

4.1 Jump Selection Strategy

Calibrating KGE models is challenging due to their extremely large class spaces: each query involves thousands of candidate entities, resulting in long-tailed probability estimates dominated by near-zero values. Directly using all candidates for calibration training is both computationally prohibitive and highly redundant. Our intuition is that calibration for KGE models requires selecting a small but informative subset of candidates for training. Building on this idea and inspired by the Log-Jump algorithm (Shen et al., 2022), we propose the **Jump Selection Strategy (JSS)**, which retains only the most informative instance per query identified via the *Jump measure* (Sugar and James, 2003), while discarding others. This reduces training size dra-

Algorithm 1 Jump Selection Strategy (JSS)

Input: Query set $\mathcal{X} = \{x_i = (\cdot, r_i, t_i)\}_{i=1}^n$, candidate entities $\mathcal{E} = \{e_j\}_{j=1}^m$, trained KGE model ψ .

Output: Most informative column index J^* and vector of probability estimates $\mathbf{p}^* \in \mathbb{R}^n$.

- 1: **for** $i = 1, \dots, n$ **do**
- 2: Compute scores: $\mathbf{s}_i \leftarrow [\psi(\mathbf{e}_j, \mathbf{r}_i, \mathbf{t}_i)]_{j=1}^m$.
- 3: Convert to probabilities: $\mathbf{p}_i \leftarrow \sigma_{\text{SM}}(\mathbf{s}_i)$.
- 4: **end for**
- 5: Stack row vectors to form probability matrix $\mathbf{P} \leftarrow [\mathbf{p}_1, \dots, \mathbf{p}_n]^\top \in \mathbb{R}^{n \times m}$.
- 6: Sort each row of \mathbf{P} in descending order to obtain $\tilde{\mathbf{P}}$.
- 7: **for** $j = 1, \dots, m - 1$ **do**
- 8: $J_j \leftarrow D_{\text{KL}}(\tilde{\mathbf{p}}^j \parallel \tilde{\mathbf{p}}^{j+1})$.
- 9: **end for**
- 10: $J^* \leftarrow \arg \max_j J_j$.
- 11: $\mathbf{p}^* \leftarrow \tilde{\mathbf{p}}^{J^*}$.

matically without sacrificing essential informativeness.

Principle of Informativeness. The core idea is that the most informative instance lies at the *transition point* between highly informative and less informative candidates. When candidate scores are ranked, the resulting distribution typically exhibits a steep drop from a few high-probability candidates to a long tail of near-zero values. Selecting the instance at this sharp transition ensures that the retained example captures the highest degree of informativeness. We formalize this intuition using the *Jump measure* to quantify informativeness.

Method. The JSS procedure is detailed in Algorithm 1. Given a set of queries $\mathcal{X} = \{x_i\}_{i=1}^n$ and candidate entities $\mathcal{E} = \{e_j\}_{j=1}^m$, the procedure begins by iterating through each query. For each query x_i , the trained KGE model ψ first produces a vector of uncalibrated scores $\mathbf{s}_i \in \mathbb{R}^m$ over all candidate entities (line 2). This score vector is then converted into a vector of probability estimates \mathbf{p}_i using the Softmax function σ_{SM} (line 3).

After processing all queries, the resulting probability vectors $\{\mathbf{p}_i\}$ are stacked as rows to form a single matrix $\mathbf{P} \in \mathbb{R}^{n \times m}$ (line 5). To make confidence transitions explicit, each row of \mathbf{P} is then sorted in descending order to yield a new matrix $\tilde{\mathbf{P}}$ (line 6). This reordering does not affect downstream performance. Link prediction metrics depend only on relative ranks, and the following

calibration operates on the full vector of probability estimates, regardless of order.

To quantify informativeness and detect the most significant transition point, we compute the Kullback–Leibler (KL) divergence between consecutive columns of $\tilde{\mathbf{P}}$, i.e., $\tilde{\mathbf{p}}^j$ and $\tilde{\mathbf{p}}^{j+1}$, as the *Jump measure* J_j (lines 7–9). KL divergence is employed here not as a loss function, but as a measure of the informativeness shift between ranked adjacent columns. Finally, the column index J^* that maximizes this *Jump measure* is selected, and its corresponding vector of probability estimates $\mathbf{p}^* \in \mathbb{R}^n$ is retained as the most informative vector for subsequent calibration training (lines 10–11).

By transforming the training instances from a full probability matrix $\mathbf{P} \in \mathbb{R}^{n \times m}$ into a single informative column vector $\mathbf{p}^* \in \mathbb{R}^n$, JSS reduces the number of training instances by a factor of m without discarding critical information. A detailed discussion and theoretical analysis of potential information loss are provided in Appendix C.

4.2 Multi-Binning Scaling

An effective post-hoc calibrator for KGE models must satisfy two properties: it should be expressive enough to correct complex miscalibration patterns while strictly preserving the model’s original ranking order, as metrics like MRR and HITS@K are paramount. Temperature Scaling (TS) (Guo et al., 2017), a widely used method, perfectly satisfies the second property by applying a single scalar temperature $T > 0$ to the logits. However, its simplicity comes at the cost of limited expressiveness: TS applies the same transformation to all probability estimates regardless of magnitude (e.g., scaling probabilities of 0.1 and 0.9 identically), making it inadequate for calibrating the highly non-uniform confidence distributions typical of KGE models. A single global parameter is often too restrictive to capture the nuanced calibration required across different confidence levels.

To address this limitation, we introduce **Multi-Binning Scaling (MBS)**, a highly expressive and flexible approach that inherits the rank-preserving benefit of TS while improving calibration quality. Inspired by histogram binning (Zadrozny and Elkan, 2001), the core idea of MBS is to partition the confidence space into multiple segments and learn a separate temperature for each, allowing the model to apply different transformations to different confidence levels.

Concretely, we partition the interval $[0, 1]$ into

W disjoint, equal-width bins, B_1, \dots, B_W , and associate each bin with an independent trainable temperature parameter $T_w > 0$. For a given query i , we use the single most informative probability, p_i^* , identified by our Jump Selection Strategy (Section 4.1), to select the appropriate bin. The associated temperature is squared and inverted to yield a bin-specific scaling factor $1/T_w^2$, which then multiplies the entire vector of probability estimates $\hat{\mathbf{p}}_i$, uniformly rescaling estimates across all candidate entities. For example, with $W = 10$ bins, a probability of $p_i^* = 0.75$ falls into the bin $B_8 = (0.7, 0.8]$, and its corresponding temperature T_8 determines the scaling factor applied to all candidate entities for that query.

This simple multiplicative rescaling is crucial: it guarantees ranking preservation while adaptively modulating confidence levels across bins. Squaring the temperature stabilizes optimization by smoothing gradients, ensuring positive scaling, and preventing excessively sharp updates. While we adopt equal-width bins for simplicity, more advanced strategies, such as adaptive or data-driven binning, represent a promising extension. Ultimately, MBS is highly efficient, as its complexity depends only on the number of bins, requiring the training of just W scalar temperature parameters. By combining the rank-preserving property of TS with the enhanced expressiveness of a bin-based transformation, MBS offers a principled and scalable solution for KGE model calibration.

4.3 Optimization

While KL divergence is a commonly used loss function in deep learning, it poses notable limitations for calibration in KGE models, such as gradient instability and explosion³. To address these issues, we propose using the Wasserstein distance as the loss function for KGE. Unlike KL divergence, the Wasserstein distance provides a more stable and geometrically meaningful way to compare confidence distributions by considering the minimum cost of transforming one distribution into another. This perspective is especially valuable in calibration, where we aim to align the calibrated estimates with ground-truth probability distributions while preserving their structure.

The Wasserstein distance models calibration as an optimal transport (OT) problem. As the loss function requires a probability distribution, we first

apply a Softmax transformation to the rescaled estimates from Multi-Binning Scaling (Section 4.2), yielding the calibrated probability distribution $\hat{\mathbf{p}}_i$. The goal of OT problem is to find the most efficient way to move mass from this calibrated probability distribution $\hat{\mathbf{p}}_i \in \mathbb{R}^m$ to the ground-truth one-hot⁴ distribution $\mathbf{q}_i \in \{0, 1\}^m$. The feasible set of transport plans is defined by the transportation polytope $U(\hat{\mathbf{p}}_i, \mathbf{q}_i)$, which contains all nonnegative transport matrices $\mathbf{P} \in \mathbb{R}_+^{m \times m}$:

$$U(\hat{\mathbf{p}}_i, \mathbf{q}_i) = \{\mathbf{P} \in \mathbb{R}_+^{m \times m} \mid \mathbf{P}\mathbf{1}_m = \hat{\mathbf{p}}_i, \mathbf{P}^\top \mathbf{1}_m = \mathbf{q}_i\}, \quad (3)$$

where $\mathbf{1}_m \in \mathbb{R}^m$ is the vector of ones.

Given a cost matrix $\mathbf{M} \in \mathbb{R}^{m \times m}$, the Wasserstein distance is defined as the minimum transport cost required to map $\hat{\mathbf{p}}_i$ to \mathbf{q}_i using the transport matrix \mathbf{P} .

$$\begin{aligned} D_{WD}(\hat{\mathbf{p}}_i, \mathbf{q}_i) &= \min_{\mathbf{P} \in U(\hat{\mathbf{p}}_i, \mathbf{q}_i)} \langle \mathbf{P}, \mathbf{M} \rangle \\ &= \sum_j^m \sum_l^m \mathbf{P}_j^l \mathbf{M}_j^l, \end{aligned} \quad (4)$$

where $\langle \cdot, \cdot \rangle$ denotes the Frobenius dot-product and $\mathbf{M}_j^l = |\hat{\mathbf{p}}_i^j - \mathbf{q}_i^l|$ represents the absolute difference between the j -th and l -th elements of $\hat{\mathbf{p}}_i$ and \mathbf{q}_i .

To improve computational efficiency, we use the Sinkhorn distance (Cuturi, 2013), which provides a fast approximation to the constrained Wasserstein distance by introducing entropy regularization. Given the OT plan \mathbf{P}^λ and cost matrix \mathbf{M} , the Sinkhorn distance D_{SD} is defined as follows:

$$D_{SD}(\hat{\mathbf{p}}_i, \mathbf{q}_i) = \langle \mathbf{P}^\lambda, \mathbf{M} \rangle, \quad (5)$$

where $\lambda > 0$ is the weight for entropy regularization. The OT plan \mathbf{P}^λ is obtained by solving:

$$\mathbf{P}^\lambda = \arg \min_{\mathbf{P} \in U(\hat{\mathbf{p}}_i, \mathbf{q}_i)} \langle \mathbf{P}, \mathbf{M} \rangle - \frac{1}{\lambda} h(\mathbf{P}), \quad (6)$$

where $h(\mathbf{P})$ is the entropy of \mathbf{P} . The solution \mathbf{P}^λ is computed iteratively via Sinkhorn normalization (Cuturi, 2013) as follows:

$$\begin{aligned} \mathbf{u}^{(t)} &= \hat{\mathbf{p}}_i \oslash (\mathbf{K}^\top \mathbf{v}^{(t-1)}), \\ \mathbf{v}^{(t)} &= \mathbf{q}_i \oslash (\mathbf{K} \mathbf{u}^{(t)}), \end{aligned} \quad (7)$$

where \oslash indicates element-wise division, (t) denotes the iteration time, and $\mathbf{K} = \exp(-\frac{\mathbf{M}}{\lambda})$ is the

⁴Here, \mathbf{q}_i is a one-hot vector where $\mathbf{q}_i^j = 1$ for the correct entity j , and $\mathbf{q}_i^l = 0$ for all $l \neq j$.

³A detailed analysis is provided in Appendix D.

kernel matrix with entropy regularization weight λ . Finally, the optimal transport plan \mathbf{P}^λ is given by:

$$\mathbf{P}^\lambda = \text{diag}(\mathbf{v}^{(t)}) \mathbf{K} \text{diag}(\mathbf{u}^{(t)}). \quad (8)$$

This Sinkhorn-regularized Wasserstein loss enables more stable optimization and improves calibration performance, particularly in the large class-space settings typical of KGE tasks.

5 Experiments

We structure our experimental study to answer three key research questions (RQs): **RQ1**: Can KGEC outperform existing calibration methods? **RQ2**: Is KGEC efficient in terms of training time and memory usage? **RQ3**: What is the contribution of each of its components? We first detail our experimental setting (Section 5.1), then address each RQ in turn (Sections 5.2–5.4), and conclude with a sensitivity analysis and case study.

5.1 Experimental Setting

5.1.1 Datasets

We evaluate our proposed model on four popular datasets, which are commonly used to evaluate link prediction, where FB15K (Bordes et al., 2013) and FB15K-237 (Toutanova and Chen, 2015) were extracted from Freebase (Bollacker et al., 2008), WN18 (Bordes et al., 2013) and WN18RR (Dettmers et al., 2018) were extracted from WordNet (Miller, 1995). Note that FB15K-237 and WN18RR are subsets of FB15K and WN18, respectively, in which near-same and near-reverse relations have been removed. These datasets are publicly available, and already partitioned into training, validation and testing splits. The statistics of them are summarized into Table 9 in Appendix E.

5.1.2 KGE Models

We evaluate KGEC on four well-established KGE models: TransE (Bordes et al., 2013), DistMult (Yang et al., 2015), ComplEx (Trouillon et al., 2016), and RotatE (Sun et al., 2019). Their score functions are listed in Table 10 in the Appendix F. It is noted that our proposed method KGEC is model-agnostic, as it can be applied to any KGE model that produces a score for each candidate triple. We therefore leave the evaluation of KGEC on other KGE architectures for future work.

5.1.3 Evaluation Measures

To evaluate calibration performance, we adopt three widely used evaluation metrics: Expected

Calibration Error (ECE) (Naeini et al., 2015), Adaptive Calibration Error (ACE) (Nixon et al., 2019), and Negative Log-Likelihood (NLL). Each metric captures different aspects of calibration quality. Due to space constraints, we refer readers to (Naeini et al., 2015; Nixon et al., 2019) for detailed formulations. For an overall comparison, we report the **Average** performance by averaging each metric across all datasets and KGE models.

5.1.4 Setting Details

To ensure a fair comparison, all calibration baselines⁵ and metrics we used are from third-party frameworks or their original implementations. Specifically, the code of PS, HB, IR, BBQ, and TS is from the `net:cal` library⁶. The code of MS and VS, as well as all calibration metrics, is provided by `TorchUncertainty`⁷. The code of Meta-Cal⁸ and PTS⁹ is from their official repositories. For the hyperparameter setting of KGEC, the number of bins is set to 10, the learning rate to 0.01, the batch size to 32, the initial temperature for each bin to 1.0, and the optimizer is AdamW (Loshchilov and Hutter, 2019). Except for VS, MS, and TS, which use the *Multiclass* setting, all other baselines use the *One-vs-All* setting to avoid prohibitive training time. We follow the closed world assumption in our experiments, since the open world assumption requires a label for each triple, which is not available in existing datasets. All reported results are averaged over 10 independent runs.

5.2 Effectiveness Study for RQ1

Table 2 presents the calibration performance of various methods across multiple KGE models and datasets. Notably, baselines such as HB, IR, BBQ, MS, and Meta-Cal are excluded, due to their detrimental impact on ranking performance, as evidenced in Table 1 (Section 3). Since preserving the original ranking order is essential in KGE settings, these calibration methods that degrade ranking performance are considered unsuitable for practical deployment and omitted from further evaluation.

Overall, KGEC consistently outperforms all competitive baselines, achieving the lowest average ECE, ACE, and NLL across all datasets and models.

⁵Due to space limitations, detailed descriptions of the calibration baselines are deferred to Appendix A.2.

⁶<https://efs-opensource.github.io/calibration-framework/build/html/index.html>

⁷<https://torch-uncertainty.github.io>

⁸<https://github.com/maxc01/metacal/tree/master>

⁹<https://github.com/tochris/pts-uncertainty>

Table 2: Effect of different calibration methods on the performance of various KGE models across multiple datasets. Best and second-ranked results are in bold and underlined, respectively. For ECE, ACE, and NLL, lower values indicate better calibration performance.

| ECE | TransE | | | ComplEx | | | DistMult | | | RotatE | | | Average | | | | |
|-------|--------|--------|-------|---------|--------|-------|----------|--------|-------|--------|--------|-------|---------|-------|-------|-------|--------------|
| | WN18 | WN18RR | FB15K | WN18 | WN18RR | FB15K | WN18 | WN18RR | FB15K | WN18 | WN18RR | FB15K | | | | | |
| Uncal | 0.502 | 0.265 | 0.580 | 0.212 | 0.852 | 0.424 | 0.696 | 0.228 | 0.528 | 0.389 | 0.694 | 0.221 | 0.429 | 0.385 | 0.684 | 0.224 | 0.457 |
| PS | 0.634 | 0.031 | 0.530 | 0.218 | 0.854 | 0.427 | 0.701 | 0.229 | 0.529 | 0.394 | 0.700 | 0.222 | 0.876 | 0.425 | 0.722 | 0.235 | 0.483 |
| VS | 0.706 | 0.014 | 0.646 | 0.231 | 0.852 | 0.424 | 0.697 | 0.228 | 0.528 | 0.389 | 0.695 | 0.215 | 0.944 | 0.413 | 0.739 | 0.239 | 0.498 |
| TS | 0.634 | 0.031 | 0.680 | 0.203 | 0.852 | 0.424 | 0.701 | 0.228 | 0.528 | 0.389 | 0.700 | 0.221 | 0.687 | 0.384 | 0.722 | 0.223 | 0.475 |
| PTS | 0.523 | 0.013 | 0.530 | 0.231 | 0.854 | 0.430 | 0.060 | 0.214 | 0.456 | 0.393 | 0.526 | 0.778 | 0.337 | 0.425 | 0.221 | 0.365 | 0.397 |
| KGEC | 0.171 | 0.280 | 0.459 | 0.150 | 0.833 | 0.418 | 0.678 | 0.189 | 0.446 | 0.383 | 0.683 | 0.178 | 0.467 | 0.307 | 0.466 | 0.094 | 0.388 |
| ACE | TransE | | | ComplEx | | | DistMult | | | RotatE | | | Average | | | | |
| | WN18 | WN18RR | FB15K | WN18 | WN18RR | FB15K | WN18 | WN18RR | FB15K | WN18 | WN18RR | FB15K | | | | | |
| Uncal | 0.506 | 0.274 | 0.565 | 0.180 | 0.852 | 0.424 | 0.696 | 0.228 | 0.528 | 0.389 | 0.694 | 0.220 | 0.429 | 0.385 | 0.684 | 0.224 | 0.455 |
| PS | 0.628 | 0.033 | 0.530 | 0.217 | 0.854 | 0.427 | 0.701 | 0.229 | 0.529 | 0.394 | 0.700 | 0.222 | 0.876 | 0.425 | 0.722 | 0.235 | 0.483 |
| VS | 0.506 | 0.274 | 0.565 | 0.180 | 0.852 | 0.424 | 0.697 | 0.228 | 0.528 | 0.389 | 0.694 | 0.215 | 0.429 | 0.385 | 0.684 | 0.224 | 0.455 |
| TS | 0.628 | 0.033 | 0.312 | 0.154 | 0.852 | 0.423 | 0.701 | 0.228 | 0.528 | 0.389 | 0.700 | 0.220 | 0.687 | 0.384 | 0.722 | 0.222 | 0.636 |
| PTS | 0.516 | 0.013 | 0.530 | 0.231 | 0.854 | 0.424 | 0.060 | 0.207 | 0.446 | 0.391 | 0.522 | 0.778 | 0.337 | 0.418 | 0.221 | 0.363 | 0.394 |
| KGEC | 0.131 | 0.277 | 0.293 | 0.082 | 0.833 | 0.418 | 0.465 | 0.207 | 0.457 | 0.383 | 0.516 | 0.199 | 0.467 | 0.306 | 0.466 | 0.063 | 0.348 |
| NLL | TransE | | | ComplEx | | | DistMult | | | RotatE | | | Average | | | | |
| | WN18 | WN18RR | FB15K | WN18 | WN18RR | FB15K | WN18 | WN18RR | FB15K | WN18 | WN18RR | FB15K | | | | | |
| Uncal | 2.891 | 6.582 | 3.911 | 5.396 | 6.892 | 7.815 | 5.954 | 7.513 | 7.447 | 7.858 | 5.919 | 7.705 | 1.376 | 6.145 | 4.090 | 5.750 | 5.828 |
| PS | 3.839 | 7.304 | 3.829 | 5.836 | 8.831 | 8.974 | 7.093 | 8.438 | 9.117 | 9.065 | 7.257 | 8.621 | 3.350 | 7.364 | 4.799 | 6.271 | 6.874 |
| VS | / | / | / | / | 6.892 | 7.814 | 5.952 | 7.510 | 7.446 | 7.857 | 5.916 | 7.692 | 1.376 | / | / | / | 6.495 |
| TS | 3.839 | 7.304 | 1.285 | 4.909 | 6.892 | 7.802 | 7.093 | 7.513 | 7.447 | 7.856 | 7.257 | 7.704 | 2.069 | 6.121 | 4.799 | 5.617 | 5.969 |
| PTS | / | 9.181 | 3.829 | 9.448 | 9.314 | 9.171 | 1.906 | 5.714 | / | 9.496 | 4.847 | / | / | / | / | / | 6.990 |
| KGEC | 2.462 | 5.965 | 2.536 | 2.889 | 4.350 | 6.965 | 1.357 | 2.911 | 2.843 | 7.119 | 1.319 | 3.106 | 1.036 | 4.698 | 2.033 | 2.743 | 3.396 |

Table 3: Training time in seconds and memory usage in MBs taken to calibrate entity prediction using different calibration methods. Best and second-ranked results are in bold and underlined, respectively. For a fair comparison, these results are obtained using CPU only.

| Method | Average Time | Average Memory |
|-------------|--------------|----------------|
| PS | 40856.945 | 2542.715 |
| VS | <u>7.577</u> | 83.294 |
| TS | 8.649 | 2540.274 |
| PTS | 7035.177 | 8410.493 |
| KGEC | 4.716 | 21.665 |

A breakdown of these results reveals several key findings: (1) *Limited effectiveness of simple baselines*. PS, VS, and TS often perform worse than the uncalibrated models. Their poor performance is likely due to their low model capacity, which is insufficient to capture complex calibration patterns in high-cardinality KGE settings. (2) *Improved results with PTS*. PTS shows marked improvement over simple baselines by predicting temperature parameters adaptively using a neural network. This flexibility enables better handling of distributional variation, leading to improved performance. (3) *Superior performance of KGEC*. KGEC achieves the best overall results across all metrics and datasets. Together, these findings confirm that KGEC effectively addresses the unique challenges of KGE calibration while preserving ranking quality.

5.3 Efficiency Study for RQ2

Table 3 reports the average training time and memory usage of different calibration methods across multiple KGE models and datasets. To ensure a

fair comparison, all methods are evaluated on CPU-only environments. Detailed experimental results for each calibration method on individual datasets and KGE models are presented in Table 11 (Appendix G).

Key Observations from Table 3: (1) KGEC is the most efficient model in both training time and memory usage, consistently outperforming all baseline methods. (2) VS and TS exhibit comparable efficiency, with slightly longer training times than KGEC, which can be attributed to their simple parametric structures. (3) PTS incurs significantly higher computational costs, both in time and memory, despite its strong calibration performance. This high overhead may limit its applicability in large-scale or resource-constrained scenarios. (4) PS is the slowest method, largely due to the immense number of classes in KGE settings, which makes binary logistic regression computationally expensive.

5.4 Ablation Study for RQ3

To assess the individual contribution of each component in KGEC, we perform a comprehensive ablation study across five key metrics: ECE, ACE, NLL, training time, and memory usage. We evaluate the following four variants: (1) KGEC: The full model, incorporating all components: Jump Selection Strategy (JSS), Multi-Binning Scaling (MBS), and the Wasserstein distance-based loss. (2) KGEC-loss: Replaces the Wasserstein loss with KL divergence while retaining JSS and MBS. (3) KGEC-loss-MBS: Further removes MBS, retaining

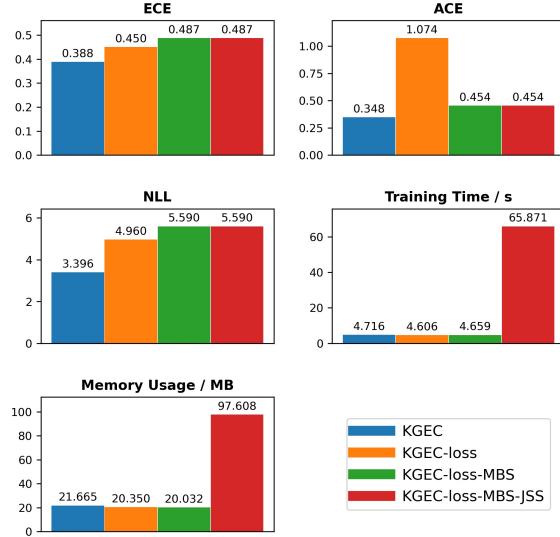


Figure 3: Ablation study of KGEC components across five evaluation metrics: ECE, ACE, NLL, training time (seconds), and memory usage (MB). Lower values indicate better performance.

only JSS and KL divergence. (4) KGEC-loss-MBS-JSS: The base version using only KL divergence, without any of the proposed enhancements. Figure 3 reports the average performance across all datasets and KGE models, providing an overall comparison of model variants. Detailed experimental results for each component on individual datasets and KGE models are presented in Table 12 (Appendix H).

Key Observations: (1) *Full Model Superiority.* KGEC achieves the best performance across all five metrics. It yields the lowest calibration errors (ECE = 0.388, ACE = 0.348, NLL = 3.396) while maintaining high efficiency (training time = 4.716s, memory usage = 21.665MB). (2) *Impact of Wasserstein Loss.* Comparing KGEC to KGEC-loss reveals substantial calibration improvements, validating the advantage of using Wasserstein distance over KL divergence in high-cardinality, ranking-sensitive KGE settings. This supports our hypothesis that the Wasserstein-based objective is better suited to the probability distribution landscape of KGE. (3) *Effect of MBS.* Removing MBS (KGEC-loss vs. KGEC-loss-MBS) degrades ECE (from 0.450 to 0.487) and NLL (from 4.960 to 5.590), indicating that MBS enhances calibration by modeling probability intervals more effectively. Interestingly, ACE improves after removing MBS. This anomaly may arise because the KL divergence used in KGEC-loss amplifies ACE more than ex-

pected, suggesting ACE is especially sensitive to the choice of loss function. (4) *Efficiency Gain from JSS.* While KGEC-loss-MBS and KGEC-loss-MBS-JSS exhibit similar calibration performance, the inclusion of JSS dramatically reduces training time (from 65.871s to 4.659s) and memory usage (from 97.608MB to 20.032MB), confirming JSS’s effectiveness in improving computational efficiency. Furthermore, a direct comparison against a random sampling baseline shows JSS is not only more efficient but also significantly more effective at preserving calibration quality (see Appendix H).

Overall, all three components are essential for balancing calibration performance and computational cost. MBS and Wasserstein loss enhance calibration performance, while JSS ensures efficiency and stability. The full KGEC model thus delivers the strongest and most balanced performance.

5.5 Sensitivity Analysis and Case Study

To further assess the robustness and practical utility of KGEC, we conducted a sensitivity analysis on its key hyperparameters and a qualitative case study. Our sensitivity analysis, which varies three hyperparameters: the number of bins, initial temperature, and learning rate, confirms that KGEC’s performance is stable across a wide range of settings. Additionally, the case study provides concrete examples of how the method corrects miscalibrated predictions, addressing both over- and under-confidence from base models. A detailed presentation is shown in Appendix I and Appendix J.

6 Conclusion

In this paper, we propose KGEC, the first probability calibration method tailored to the unique challenges of KGE models. By integrating a novel Jump Selection Strategy for efficiency, a Multi-Binning Scaling module for expressiveness, and a Wasserstein distance-based loss for stable optimization, KGEC effectively calibrates KGE predictions while strictly preserving their ranking performance. Comprehensive experiments across multiple KGE models and datasets demonstrate that KGEC significantly outperforms existing calibration baselines in both calibration performance and computational efficiency. Our work establishes a strong foundation for trustworthy link prediction, and future work may explore extensions to dynamic KGs or integration with uncertainty-aware reasoning systems.

Limitations

While KGEc achieves strong performance, we identify several promising directions for future work based on its current limitations:

(1) Alternative Expit Transformations. In this work, we adopt the Softmax function as the expit transformation, as our primary focus is on the calibration method itself. However, alternative approaches, such as NIC (Wang et al., 2021) and min-max normalization (Rao, 2021), may further improve performance and merit exploration in future work.

(2) Task-Specific Calibration Considerations.

KGEc is optimized for static entity prediction tasks in knowledge graphs. Its effectiveness in other KGE-based applications, such as multi-hop reasoning, fact verification, or temporal/dynamic KG settings, remains untested. These tasks may require adaptation or redesign of the calibration strategy to accommodate different data characteristics and evaluation protocols.

(3) Limited Evaluation Across Advanced KGE Architectures. While KGEc has been extensively evaluated on several representative KGE models (e.g., TransE, DistMult, ComplEx, and RotatE), its generalization to more complex architectures, such as hyperbolic embeddings, graph neural networks, or transformer-based KGE models, has not yet been studied. Extending KGEc to these settings poses challenges in modeling and scalability, and is an important direction for future work.

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A Calibration Baselines

A.1 Calibration Techniques Explored in Existing KGE Literature

For completeness, Table 4 summarizes which calibration methods have been employed in prior studies of KGE calibration. This overview highlights that existing works all exclusively adapt off-the-shelf methods originally designed for standard classification tasks, underscoring the need for calibration techniques tailored specifically to the KGE setting.

A.2 Calibration Baselines Evaluated in Our Experiments

We summarize the post-hoc probability calibration baselines considered in this work:

- **Platt Scaling (PS)** (Platt et al., 1999) is a parametric calibration method that transforms the non-probabilistic outputs of a binary classifier into calibrated confidence scores.
- **Histogram Binning (HB)** (Zadrozny and Elkan, 2001) is a simple non-parametric approach that partitions predictions into mutually exclusive bins, assigning each bin a calibrated score.
- **Isotonic Regression (IR)** (Zadrozny and Elkan, 2002) generalizes HB by jointly optimizing both bin boundaries and predictions through a monotonic regression function.
- **Bayesian Binning into Quantiles (BBQ)** (Naeini et al., 2015) extends HB by applying Bayesian model averaging over multiple binning models.
- **Matrix Scaling (MS) and Vector Scaling (VS)** (Guo et al., 2017) are multi-class extensions of PS, using matrix and vector transformations, respectively.
- **Temperature Scaling (TS)** (Guo et al., 2017) is the simplest extension of PS, employing a single scalar temperature parameter $T > 0$ shared across all predictions.
- **Meta-Cal** (Ma and Blaschko, 2021) combines a bipartite-ranking model with selective classifica-

tion to construct a more flexible calibration mapping.

• Parametrized Temperature Scaling (PTS)

(Tomani et al., 2022) generalizes TS by computing prediction-specific temperatures, parameterized by a neural network.

In this study, we restrict our attention to *post-hoc probability calibration* methods, which adjust model outputs without altering the underlying KGE training process. This ensures that the original ranking of entities is preserved. Training-modifying approaches such as regularization (Ahn et al., 2019), ensembles (Lakshminarayanan et al., 2017), MC-dropout (Gal and Ghahramani, 2016), and mixup (Thulasidasan et al., 2019) fall outside our scope, as they fundamentally alter the embedding training procedure.

We also exclude **Beta Calibration** (Kull et al., 2017) due to its prohibitive computational cost. For example, even on the smallest dataset (WN18RR), it required over 60 hours to complete, making it infeasible for our large-scale experiments. Finally, we emphasize that this work focuses strictly on *probability calibration*. Expit transformation alternatives such as replacing the Softmax function with Sigmoid or NIC (Wang et al., 2021) are conceptually distinct and therefore not considered here.

B Effect of Different Calibration Methods Across Datasets

In this section, we systematically evaluate nine widely used post-hoc calibration methods on the entity prediction task across four benchmark datasets. The goal is to assess whether these calibration techniques can improve probabilistic reliability while preserving the ranking quality essential for knowledge graph completion.

We report results using standard link prediction metrics. Specifically, lower *Mean Rank (MR)* indicates better performance, while higher values of *Mean Reciprocal Rank (MRR)*, *HITS@1*, *HITS@3*, and *HITS@10* correspond to better ranking quality.

As shown in Table 5–8, several calibration methods, including HB, IR, BBQ, MS, and Meta-Cal, substantially degrade entity ranking performance. This suggests that these approaches disrupt the original link prediction scores after calibration and are therefore unsuitable for KGE-based entity prediction.

Table 4: Overview of calibration methods employed in prior KGE calibration studies. Each method is marked as parametric or non-parametric, along with the corresponding references.

| Calibration Method | Parametric | Used in Works |
|--|------------|---|
| Isotonic Regression (Zadrozny and Elkan, 2002) | No | (Tabacof and Costabello, 2020), (Wang et al., 2021), (Zhu et al., 2022) |
| Histogram Binning (Zadrozny and Elkan, 2001) | No | (Zhu et al., 2022) |
| Beta Calibration (Kull et al., 2017) | Yes | (Zhu et al., 2022) |
| Platt Scaling (Platt et al., 1999) | Yes | (Tabacof and Costabello, 2020), (Wang et al., 2021), (Zhu et al., 2022) |
| Matrix Scaling (Guo et al., 2017) | Yes | (Safavi et al., 2020) |
| Vector Scaling (Guo et al., 2017) | Yes | (Safavi et al., 2020) |
| Temperature Scaling (Guo et al., 2017) | Yes | (Zhu et al., 2022) |

C Detailed Description of the Jump Selection Strategy (JSS)

In the main paper (Section 4.1), we introduced the **Jump Selection Strategy** (JSS) as a principled method to reduce the size of calibration training data while preserving the essential informativeness of the retained samples. Here, we provide a more detailed exposition of the motivation, intuition, and theoretical considerations behind JSS.

C.1 Challenge of Large Class Spaces.

A core difficulty in calibrating KGE models lies in the extremely large candidate space. Each query may involve thousands of possible entities, resulting in probability distributions dominated by a long tail of near-zero values. Using all candidates for calibration training is both computationally prohibitive and information-redundant: the majority of entries contribute little to overall informativeness. Thus, an effective selection mechanism is needed to retain only the most informative instance per query.

C.2 Principle of Informativeness.

The informativeness of a candidate is defined as its ability to characterize the transition from highly informative predictions to less informative ones. Empirically, when candidate probabilities are ranked, the distribution exhibits a steep drop from a small number of dominant candidates to a long tail of negligible ones. The most informative instance lies at this transition point, where the contrast between candidates is strongest. Selecting this instance ensures that calibration focuses on the sample carrying the greatest informativeness.

C.3 Reordering Step.

To detect this transition consistently, we first reorder each query’s probability vector into descending order. This guarantees a monotonic sequence from most informative to least informative candi-

dates, making the transition explicit. Although this step perturbs the raw candidate alignment, it does not alter downstream objectives: (i) Link prediction is ranking-based, not order-sensitive. Thus, perturbing candidate order within a query does not affect evaluation metrics such as MRR or HITS@K. (ii) As demonstrated in Multi-Binning Scaling (Section 4.2), for query i , all of the M elements in the probability vector \mathbf{P}_i are transformed using the same temperature parameter T_w^2 . MBS is applied uniformly across the entire vector \mathbf{P}_i , regardless of its internal order. Therefore, the calibrated output preserves the original ranking. Reordering is therefore a benign preprocessing step that enables consistent identification of the most informative instance.

C.4 Illustrative Toy Example.

To make the procedure concrete, consider the following probability matrix with three queries (rows) and three candidates (columns):

$$\mathbf{P} = \begin{bmatrix} 0.1 & 0.2 & 0.3 \\ 0.4 & 0.6 & 0.2 \\ 0.5 & 0.1 & 0.4 \end{bmatrix}. \quad (9)$$

After reordering each row in descending order, we obtain

$$\tilde{\mathbf{P}} = \begin{bmatrix} 0.3 & 0.2 & 0.1 \\ 0.6 & 0.4 & 0.2 \\ 0.5 & 0.4 & 0.1 \end{bmatrix}. \quad (10)$$

We then compute KL-based Jump Measures between adjacent columns of $\tilde{\mathbf{P}}$, which yields

$$J = [0.0039, 0.0541], \quad (11)$$

indicating that the maximum jump occurs at the second column ($J^* = 1$ in zero-based indexing).

Table 5: Effect of different calibration methods on the performance of the TransE model across various datasets. \uparrow indicates an improvement, while \downarrow indicates a decline compared to the original uncalibrated results.

| Method | MR | MRR | HITS@1 | HITS@3 | HITS@10 |
|------------------|--------------------|--------------------|--------------------|--------------------|--------------------|
| WN18 | | | | | |
| Uncal | 263 | 0.772 | 0.706 | 0.807 | 0.920 |
| PS | 260 \uparrow | 0.772 | 0.706 | 0.807 | 0.920 |
| HB | 15299 \downarrow | 0.225 \downarrow | 0.212 \downarrow | 0.236 \downarrow | 0.240 \downarrow |
| IR | 14590 \downarrow | 0.251 \downarrow | 0.232 \downarrow | 0.267 \downarrow | 0.279 \downarrow |
| BBQ | 15178 \downarrow | 0.218 \downarrow | 0.200 \downarrow | 0.233 \downarrow | 0.244 \downarrow |
| VS | 258 \uparrow | 0.772 | 0.706 | 0.807 | 0.920 |
| MS | 16483 \downarrow | 0.013 \downarrow | 0.005 \downarrow | 0.013 \downarrow | 0.029 \downarrow |
| TS | 260 \uparrow | 0.772 | 0.706 | 0.807 | 0.920 |
| Meta-Cal | 1784 \downarrow | 0.718 \downarrow | 0.657 \downarrow | 0.749 \downarrow | 0.856 \downarrow |
| PTS | 2116 \downarrow | 0.751 \downarrow | 0.706 | 0.775 \downarrow | 0.849 \downarrow |
| KGEC | 263 | 0.772 | 0.706 | 0.807 | 0.920 |
| WN18RR | | | | | |
| Uncal | 3437 | 0.223 | 0.014 | 0.401 | 0.528 |
| PS | 3437 | 0.223 | 0.014 | 0.401 | 0.528 |
| HB | 19455 \downarrow | 0.071 \downarrow | 0.053 \uparrow | 0.087 \downarrow | 0.099 \downarrow |
| IR | 18143 \downarrow | 0.102 \downarrow | 0.080 \uparrow | 0.119 \downarrow | 0.139 \downarrow |
| BBQ | 18196 \downarrow | 0.071 \downarrow | 0.050 \uparrow | 0.085 \downarrow | 0.105 \downarrow |
| VS | 3421 \uparrow | 0.224 \uparrow | 0.014 | 0.401 | 0.529 \uparrow |
| MS | 18178 \downarrow | 0.009 \downarrow | 0.003 \downarrow | 0.008 \downarrow | 0.020 \downarrow |
| TS | 3437 | 0.223 | 0.014 | 0.401 | 0.528 |
| Meta-Cal | 3437 | 0.223 | 0.014 | 0.401 | 0.528 |
| PTS | 3437 | 0.223 | 0.014 | 0.401 | 0.528 |
| KGEC | 3437 | 0.223 | 0.014 | 0.401 | 0.528 |
| FB15K | | | | | |
| Uncal | 40 | 0.731 | 0.646 | 0.793 | 0.865 |
| PS | 40 | 0.731 | 0.646 | 0.793 | 0.865 |
| HB | 2275 \downarrow | 0.570 \downarrow | 0.510 \downarrow | 0.614 \downarrow | 0.670 \downarrow |
| IR | 982 \downarrow | 0.615 \downarrow | 0.530 \downarrow | 0.675 \downarrow | 0.761 \downarrow |
| BBQ | 1275 \downarrow | 0.589 \downarrow | 0.509 \downarrow | 0.646 \downarrow | 0.726 \downarrow |
| VS | 41 \downarrow | 0.730 \downarrow | 0.646 | 0.791 \downarrow | 0.862 \downarrow |
| MS | 3687 \downarrow | 0.038 \downarrow | 0.024 \downarrow | 0.039 \downarrow | 0.061 \downarrow |
| TS | 40 | 0.731 | 0.646 | 0.793 | 0.865 |
| Meta-Cal | 1149 \downarrow | 0.677 \downarrow | 0.604 \downarrow | 0.735 \downarrow | 0.787 \downarrow |
| PTS | 40 | 0.731 | 0.646 | 0.793 | 0.865 |
| KGEC | 40 | 0.731 | 0.646 | 0.793 | 0.865 |
| FB15K-237 | | | | | |
| Uncal | 173 | 0.330 | 0.231 | 0.368 | 0.527 |
| PS | 173 | 0.330 | 0.231 | 0.368 | 0.527 |
| HB | 3497 \downarrow | 0.289 \downarrow | 0.224 \downarrow | 0.321 \downarrow | 0.416 \downarrow |
| IR | 2141 \downarrow | 0.309 \downarrow | 0.234 \uparrow | 0.343 \downarrow | 0.455 \downarrow |
| BBQ | 2335 \downarrow | 0.280 \downarrow | 0.209 \downarrow | 0.310 \downarrow | 0.422 \downarrow |
| VS | 173 | 0.330 | 0.231 | 0.368 | 0.527 |
| MS | 3704 \downarrow | 0.033 \downarrow | 0.014 \downarrow | 0.032 \downarrow | 0.070 \downarrow |
| TS | 173 | 0.330 | 0.231 | 0.368 | 0.527 |
| Meta-Cal | 1231 \downarrow | 0.308 \downarrow | 0.218 \downarrow | 0.344 \downarrow | 0.490 \downarrow |
| PTS | 173 | 0.330 | 0.231 | 0.368 | 0.527 |
| KGEC | 173 | 0.330 | 0.231 | 0.368 | 0.527 |

Thus, the second column of $\tilde{\mathbf{P}}$ is selected as the most informative instance per query:

$$\mathbf{p}^* = \begin{bmatrix} 0.2 \\ 0.4 \\ 0.4 \end{bmatrix}. \quad (12)$$

For each query (row), suppose the temperatures selected by MBS based on the binned values in \mathbf{p}^* are

$$\mathbf{T} = \begin{bmatrix} 0.7 \\ 1.5 \\ 1.0 \end{bmatrix}. \quad (13)$$

Table 6: Effect of different calibration methods on the performance of the ComplEx model across various datasets. \uparrow indicates an improvement, while \downarrow indicates a decline compared to the original uncalibrated results.

| Method | MR | MRR | HITS@1 | HITS@3 | HITS@10 |
|------------------|--------------------|--------------------|--------------------|--------------------|--------------------|
| WN18 | | | | | |
| Uncal | 311 | 0.893 | 0.854 | 0.925 | 0.953 |
| PS | 311 | 0.893 | 0.854 | 0.925 | 0.953 |
| HB | 14328 \downarrow | 0.274 \downarrow | 0.262 \downarrow | 0.285 \downarrow | 0.289 \downarrow |
| IR | 14094 \downarrow | 0.290 \downarrow | 0.280 \downarrow | 0.298 \downarrow | 0.304 \downarrow |
| BBQ | 13657 \downarrow | 0.236 \downarrow | 0.194 \downarrow | 0.271 \downarrow | 0.306 \downarrow |
| VS | 305 \uparrow | 0.893 | 0.854 | 0.925 | 0.953 |
| MS | 16825 \downarrow | 0.011 \downarrow | 0.004 \downarrow | 0.012 \downarrow | 0.022 \downarrow |
| TS | 311 | 0.893 | 0.854 | 0.925 | 0.953 |
| Meta-Cal | 1260 \downarrow | 0.851 \downarrow | 0.813 \downarrow | 0.880 \downarrow | 0.908 \downarrow |
| PTS | 311 | 0.893 | 0.854 | 0.925 | 0.953 |
| KGEC | 311 | 0.893 | 0.854 | 0.925 | 0.953 |
| WN18RR | | | | | |
| Uncal | 5469 | 0.469 | 0.428 | 0.486 | 0.552 |
| PS | 5469 | 0.469 | 0.428 | 0.486 | 0.552 |
| HB | 18836 \downarrow | 0.107 \downarrow | 0.100 \downarrow | 0.112 \downarrow | 0.118 \downarrow |
| IR | 18244 \downarrow | 0.103 \downarrow | 0.090 \downarrow | 0.110 \downarrow | 0.124 \downarrow |
| BBQ | 18200 \downarrow | 0.087 \downarrow | 0.076 \downarrow | 0.097 \downarrow | 0.105 \downarrow |
| VS | 5447 \uparrow | 0.469 | 0.428 | 0.486 | 0.552 |
| MS | 18191 \downarrow | 0.009 \downarrow | 0.003 \downarrow | 0.009 \downarrow | 0.020 \downarrow |
| TS | 5469 | 0.469 | 0.428 | 0.486 | 0.552 |
| Meta-Cal | 6416 \downarrow | 0.445 \downarrow | 0.407 \downarrow | 0.459 \downarrow | 0.522 |
| PTS | 5469 | 0.469 | 0.428 | 0.486 | 0.552 |
| KGEC | 5469 | 0.469 | 0.428 | 0.486 | 0.552 |
| FB15K | | | | | |
| Uncal | 45 | 0.770 | 0.703 | 0.816 | 0.885 |
| PS | 45 | 0.770 | 0.703 | 0.816 | 0.885 |
| HB | 1747 \downarrow | 0.610 \downarrow | 0.543 \downarrow | 0.661 \downarrow | 0.724 \downarrow |
| IR | 970 \downarrow | 0.652 \downarrow | 0.579 \downarrow | 0.704 \downarrow | 0.780 \downarrow |
| BBQ | 797 \downarrow | 0.597 \downarrow | 0.509 \downarrow | 0.656 \downarrow | 0.757 \downarrow |
| VS | 43 \uparrow | 0.770 | 0.703 | 0.816 | 0.886 \uparrow |
| MS | 3693 \downarrow | 0.025 \downarrow | 0.010 \downarrow | 0.024 \downarrow | 0.055 \downarrow |
| TS | 45 | 0.770 | 0.703 | 0.816 | 0.885 |
| Meta-Cal | 484 \downarrow | 0.715 \downarrow | 0.651 \downarrow | 0.759 \downarrow | 0.826 \downarrow |
| PTS | 45 | 0.770 | 0.703 | 0.816 | 0.885 |
| KGEC | 45 | 0.770 | 0.703 | 0.816 | 0.885 |
| FB15K-237 | | | | | |
| Uncal | 166 | 0.322 | 0.230 | 0.352 | 0.511 |
| PS | 166 | 0.322 | 0.230 | 0.352 | 0.511 |
| HB | 2882 \downarrow | 0.274 \downarrow | 0.201 \downarrow | 0.305 \downarrow | 0.420 \downarrow |
| IR | 2185 \downarrow | 0.296 \downarrow | 0.220 \uparrow | 0.328 \downarrow | 0.449 \downarrow |
| BBQ | 1661 \downarrow | 0.249 \downarrow | 0.176 \downarrow | 0.273 \downarrow | 0.399 \downarrow |
| VS | 166 | 0.322 | 0.230 | 0.352 | 0.512 \uparrow |
| MS | 3704 \downarrow | 0.033 \downarrow | 0.014 \downarrow | 0.032 \downarrow | 0.070 \downarrow |
| TS | 166 | 0.322 | 0.230 | 0.352 | 0.511 |
| Meta-Cal | 267 \downarrow | 0.310 \downarrow | 0.218 \downarrow | 0.339 \downarrow | 0.498 \downarrow |
| PTS | 166 | 0.322 | 0.230 | 0.352 | 0.511 |
| KGEC | 166 | 0.322 | 0.230 | 0.352 | 0.511 |

Applying temperature scaling yields the calibrated confidence matrix

$$\hat{\mathbf{P}} = \begin{bmatrix} 0.1 & 0.2 & 0.3 \\ 0.7^2 & 0.7^2 & 0.7^2 \\ 0.4 & 0.6 & 0.2 \\ 1.5^2 & 1.5^2 & 1.5^2 \\ 0.5 & 0.1 & 0.4 \\ 1.0^2 & 1.0^2 & 1.0^2 \end{bmatrix} = \begin{bmatrix} 0.20 & 0.40 & 0.60 \\ 0.18 & 0.27 & 0.09 \\ 0.50 & 0.10 & 0.40 \end{bmatrix} \quad (14)$$

As observed, this rescaling preserves the rela-

Table 7: Effect of different calibration methods on the performance of the DistMult model across various datasets. \uparrow indicates an improvement, while \downarrow indicates a decline compared to the original uncalibrated results.

| Method | MR | MRR | HITS@1 | HITS@3 | HITS@10 |
|------------------|--------------------|--------------------|--------------------|--------------------|--------------------|
| WN18 | | | | | |
| Uncal | 227 | 0.685 | 0.529 | 0.829 | 0.933 |
| PS | 227 | 0.685 | 0.529 | 0.829 | 0.933 |
| HB | 14718 \downarrow | 0.240 \downarrow | 0.216 \downarrow | 0.262 \downarrow | 0.271 \downarrow |
| IR | 14271 \downarrow | 0.260 \downarrow | 0.237 \downarrow | 0.279 \downarrow | 0.294 \downarrow |
| BBQ | 13614 \downarrow | 0.201 \downarrow | 0.154 \downarrow | 0.232 \downarrow | 0.293 \downarrow |
| VS | 224 \uparrow | 0.685 | 0.529 | 0.829 | 0.933 |
| MS | 16984 \downarrow | 0.011 \downarrow | 0.004 \downarrow | 0.012 \downarrow | 0.022 \downarrow |
| TS | 227 | 0.685 | 0.529 | 0.829 | 0.933 |
| Meta-Cal | 770 \downarrow | 0.663 \downarrow | 0.508 \downarrow | 0.805 \downarrow | 0.908 \downarrow |
| PTS | 240 \downarrow | 0.685 | 0.529 | 0.829 | 0.932 \downarrow |
| KGEC | 227 | 0.685 | 0.529 | 0.829 | 0.933 |
| WN18RR | | | | | |
| Uncal | 4912 | 0.439 | 0.394 | 0.453 | 0.532 |
| PS | 4909 \uparrow | 0.439 | 0.394 | 0.453 | 0.532 |
| HB | 19006 \downarrow | 0.100 \downarrow | 0.090 \uparrow | 0.108 \downarrow | 0.117 \downarrow |
| IR | 18174 \downarrow | 0.099 \downarrow | 0.083 \uparrow | 0.109 \downarrow | 0.124 \downarrow |
| BBQ | 18192 \downarrow | 0.088 \downarrow | 0.073 \uparrow | 0.100 \downarrow | 0.109 \downarrow |
| VS | 4888 \uparrow | 0.439 | 0.394 | 0.453 | 0.532 |
| MS | 18172 \downarrow | 0.009 \downarrow | 0.003 \downarrow | 0.009 \downarrow | 0.020 \downarrow |
| TS | 4909 \uparrow | 0.439 | 0.394 | 0.453 | 0.532 |
| Meta-Cal | 6157 \downarrow | 0.406 \downarrow | 0.366 \downarrow | 0.419 \downarrow | 0.493 \downarrow |
| PTS | 4909 \uparrow | 0.439 | 0.394 | 0.453 | 0.532 |
| KGEC | 4909 \uparrow | 0.439 | 0.394 | 0.453 | 0.532 |
| FB15K | | | | | |
| Uncal | 41 | 0.768 | 0.701 | 0.813 | 0.884 |
| PS | 41 | 0.768 | 0.701 | 0.813 | 0.884 |
| HB | 1528 \downarrow | 0.630 \downarrow | 0.562 \downarrow | 0.679 \downarrow | 0.748 \downarrow |
| IR | 952 \downarrow | 0.667 \downarrow | 0.599 \downarrow | 0.713 \downarrow | 0.787 \downarrow |
| BBQ | 692 \downarrow | 0.603 \downarrow | 0.512 \downarrow | 0.659 \downarrow | 0.775 \downarrow |
| VS | 39 \uparrow | 0.768 | 0.701 | 0.814 \uparrow | 0.885 \uparrow |
| MS | 3693 \downarrow | 0.025 \downarrow | 0.010 \downarrow | 0.024 \downarrow | 0.055 \downarrow |
| TS | 41 | 0.768 | 0.701 | 0.813 | 0.884 |
| Meta-Cal | 202 \downarrow | 0.746 \downarrow | 0.680 \downarrow | 0.790 \downarrow | 0.861 \downarrow |
| PTS | 41 | 0.768 | 0.701 | 0.813 | 0.884 |
| KGEC | 41 | 0.768 | 0.701 | 0.813 | 0.884 |
| FB15K-237 | | | | | |
| Uncal | 174 | 0.309 | 0.222 | 0.337 | 0.484 |
| PS | 174 | 0.309 | 0.222 | 0.337 | 0.484 |
| HB | 2695 \downarrow | 0.256 \downarrow | 0.184 \downarrow | 0.286 \downarrow | 0.401 \downarrow |
| IR | 2156 \downarrow | 0.280 \downarrow | 0.205 \uparrow | 0.311 \downarrow | 0.427 \downarrow |
| BBQ | 1562 \downarrow | 0.235 \downarrow | 0.163 \downarrow | 0.259 \downarrow | 0.378 \downarrow |
| VS | 172 \uparrow | 0.305 \downarrow | 0.216 \downarrow | 0.333 \downarrow | 0.484 |
| MS | 3704 \downarrow | 0.033 \downarrow | 0.014 \downarrow | 0.032 \downarrow | 0.070 \downarrow |
| TS | 174 | 0.309 | 0.222 | 0.337 | 0.484 |
| Meta-Cal | 259 \downarrow | 0.300 \downarrow | 0.213 \downarrow | 0.327 \downarrow | 0.474 \downarrow |
| PTS | 5659 \downarrow | 0.222 \downarrow | 0.222 | 0.222 \downarrow | 0.223 \downarrow |
| KGEC | 174 | 0.309 | 0.222 | 0.337 | 0.484 |

tive ordering of candidates within each row, and thus ranking-based metrics (e.g., MRR, HITS@K) remain unaffected.

C.5 KL Divergence as Jump Measure.

Given the reordered probability matrix $\tilde{\mathbf{P}}$, we compute the *Jump measure* J_j as the KL divergence between adjacent columns. KL is not used here as a loss function but as a relative difference metric, quantifying how informativeness changes between consecutive ranked positions. A large KL value indicates a sharp change in informativeness, corresponding to the transition point. Unlike its unstable behavior in one-hot settings (where zero entries

Table 8: Effect of different calibration methods on the performance of the RotatE model across various datasets. \uparrow indicates an improvement, while \downarrow indicates a decline compared to the original uncalibrated results.

| Method | MR | MRR | HITS@1 | HITS@3 | HITS@10 |
|------------------|--------------------|--------------------|--------------------|--------------------|--------------------|
| WN18 | | | | | |
| Uncal | 270 | 0.950 | 0.944 | 0.952 | 0.960 |
| PS | 270 | 0.950 | 0.944 | 0.952 | 0.960 |
| HB | 13910 \downarrow | 0.279 \downarrow | 0.263 \downarrow | 0.294 \downarrow | 0.299 \downarrow |
| IR | 13962 \downarrow | 0.297 \downarrow | 0.286 \downarrow | 0.308 \downarrow | 0.313 \downarrow |
| BBQ | 13801 \downarrow | 0.271 \downarrow | 0.253 \downarrow | 0.286 \downarrow | 0.297 \downarrow |
| VS | 270 | 0.950 | 0.944 | 0.952 | 0.960 |
| MS | 16626 \downarrow | 0.013 \downarrow | 0.005 \downarrow | 0.013 \downarrow | 0.027 \downarrow |
| TS | 270 | 0.950 | 0.944 | 0.952 | 0.960 |
| Meta-Cal | 1917 \downarrow | 0.905 \downarrow | 0.904 \downarrow | 0.905 \downarrow | 0.905 \downarrow |
| PTS | 474 \downarrow | 0.949 \downarrow | 0.944 | 0.951 \downarrow | 0.958 \downarrow |
| KGEC | 270 | 0.950 | 0.944 | 0.952 | 0.960 |
| WN18RR | | | | | |
| Uncal | 3421 | 0.476 | 0.429 | 0.496 | 0.570 |
| PS | 3421 | 0.476 | 0.429 | 0.497 \uparrow | 0.570 |
| HB | 18719 \downarrow | 0.114 \downarrow | 0.104 \downarrow | 0.122 \downarrow | 0.127 \downarrow |
| IR | 18047 \downarrow | 0.118 \downarrow | 0.103 \downarrow | 0.128 \downarrow | 0.143 \downarrow |
| BBQ | 18189 \downarrow | 0.086 \downarrow | 0.073 \downarrow | 0.095 \downarrow | 0.105 \downarrow |
| VS | 3422 \downarrow | 0.476 | 0.429 | 0.497 \uparrow | 0.570 |
| MS | 18195 \downarrow | 0.009 \downarrow | 0.003 \downarrow | 0.008 \downarrow | 0.020 \downarrow |
| TS | 3421 | 0.476 | 0.429 | 0.497 \uparrow | 0.570 |
| Meta-Cal | 6168 \downarrow | 0.448 \downarrow | 0.409 \downarrow | 0.464 \downarrow | 0.523 \downarrow |
| PTS | 3776 \downarrow | 0.474 \downarrow | 0.429 | 0.493 \downarrow | 0.564 \downarrow |
| KGEC | 3421 | 0.476 | 0.429 | 0.497 \uparrow | 0.570 |
| FB15K | | | | | |
| Uncal | 41 | 0.791 | 0.739 | 0.825 | 0.881 |
| PS | 41 | 0.791 | 0.739 | 0.825 | 0.881 |
| HB | 1843 \downarrow | 0.642 \downarrow | 0.588 \downarrow | 0.682 \downarrow | 0.731 \downarrow |
| IR | 961 \downarrow | 0.696 \downarrow | 0.635 \downarrow | 0.741 \downarrow | 0.799 \downarrow |
| BBQ | 1027 \downarrow | 0.662 \downarrow | 0.599 \downarrow | 0.709 \downarrow | 0.768 \downarrow |
| VS | 42 \downarrow | 0.791 | 0.739 | 0.825 | 0.880 \downarrow |
| MS | 3693 \downarrow | 0.025 \downarrow | 0.010 \downarrow | 0.024 \downarrow | 0.055 \downarrow |
| TS | 41 | 0.791 | 0.739 | 0.825 | 0.881 |
| Meta-Cal | 457 \downarrow | 0.750 \downarrow | 0.700 \downarrow | 0.783 \downarrow | 0.835 \downarrow |
| PTS | 1122 \downarrow | 0.763 \downarrow | 0.739 | 0.782 \downarrow | 0.801 \downarrow |
| KGEC | 41 | 0.791 | 0.739 | 0.825 | 0.881 |
| FB15K-237 | | | | | |
| Uncal | 178 | 0.336 | 0.239 | 0.374 | 0.530 |
| PS | 178 | 0.336 | 0.239 | 0.374 | 0.530 |
| HB | 3458 \downarrow | 0.285 \downarrow | 0.221 \downarrow | 0.317 \downarrow | 0.412 \downarrow |
| IR | 2131 \downarrow | 0.307 \downarrow | 0.232 \downarrow | 0.340 \downarrow | 0.455 \downarrow |
| BBQ | 2292 \downarrow | 0.275 \downarrow | 0.204 \downarrow | 0.305 \downarrow | 0.415 \downarrow |
| VS | 179 \downarrow | 0.336 | 0.239 | 0.374 | 0.530 |
| MS | 3704 \downarrow | 0.033 \downarrow | 0.014 \downarrow | 0.032 \downarrow | 0.070 \downarrow |
| TS | 178 | 0.336 | 0.239 | 0.374 | 0.530 |
| Meta-Cal | 246 \downarrow | 0.328 \downarrow | 0.232 \downarrow | 0.365 \downarrow | 0.522 \downarrow |
| PTS | 179 \downarrow | 0.336 | 0.239 | 0.374 | 0.530 |
| KGEC | 178 | 0.336 | 0.239 | 0.374 | 0.530 |

occur), KL is well-defined here because all compared vectors are soft probability distributions with non-zero entries.

Formally, the column index J^* that maximizes J_j is selected, and the corresponding column vector $\mathbf{p}^* \in \mathbb{R}^n$ is retained as the most informative sample per query.

C.6 Information Loss Quantification via Shannon Entropy

To analyze the effect of JSS on information preservation, we quantify the potential information loss incurred when reducing a probability matrix $\mathbf{P} \in \mathbb{R}^{N \times M}$ to a single informative column vector $\mathbf{p}^* \in$

\mathbb{R}^N . We measure information content using Shannon entropy.

Let $\mathbf{P} \in \mathbb{R}^{N \times M}$ be a real-valued matrix with N rows and M columns. To quantify the amount of information contained in \mathbf{P} , we apply Shannon entropy to the empirical distribution of its elements. Suppose the entries are discretized into a finite alphabet \mathcal{X} (e.g., via binning or quantization). Then the entropy of the matrix \mathbf{P} is defined as:

$$H(\mathbf{P}) = - \sum_{x \in \mathcal{X}} p_{\mathbf{P}}(x) \log p_{\mathbf{P}}(x), \quad (15)$$

where $p_{\mathbf{P}}(x)$ denotes the empirical probability mass function over the elements of \mathbf{P} .

Similarly, consider selecting a single column vector $\mathbf{v} \in \mathbb{R}^N$ from \mathbf{P} , i.e., $\mathbf{v} = \mathbf{P}_{:,j}$ for some $j \in \{1, \dots, M\}$, its entropy is:

$$H(\mathbf{v}) = - \sum_{x \in \mathcal{X}} p_{\mathbf{v}}(x) \log p_{\mathbf{v}}(x), \quad (16)$$

The loss in information due to column selection is thus:

$$\Delta H = H(\mathbf{P}) - H(\mathbf{v}). \quad (17)$$

We discuss three representative cases:

Case 1: Independent and Identically Distributed (i.i.d.) Columns. If each column of \mathbf{P} is drawn independently from the same distribution (i.i.d.), the matrix entropy decomposes additively:

$$H(\mathbf{P}) = \sum_{j=1}^M H(\mathbf{v}_j) = M \cdot H(\mathbf{v}), \quad (18)$$

where $H(\mathbf{v}_j) = H(\mathbf{v})$ for all j . Therefore, the information loss becomes:

$$\Delta H = (M - 1) \cdot H(\mathbf{v}), \quad (19)$$

indicating that \mathbf{P} stores M times more information than any single column under the i.i.d. assumption.

Case 2: Correlated Columns. If the columns are not independent, entropy is subadditive due to redundancy:

$$H(\mathbf{P}) < \sum_{j=1}^M H(\mathbf{v}_j), \quad (20)$$

and the total information is reduced by mutual dependencies. Formally,

$$H(\mathbf{P}) = \sum_{j=1}^M H(\mathbf{v}_j) - \text{Redundancy}, \quad (21)$$

where *Redundancy* quantifies mutual information shared between columns.

Case 3: Identical Columns. In the extreme case where all columns are identical,

$$H(\mathbf{P}) = H(\mathbf{v}), \quad \Delta H = 0, \quad (22)$$

meaning no information is lost by reducing \mathbf{P} to one column.

Discussion. These cases illustrate that although selecting a single column inevitably reduces entropy in the i.i.d. case, real KGE outputs exhibit strong redundancy across candidate entities. JSS exploits this redundancy by identifying the column with the largest information jump, thereby retaining the most informative subset of probabilities while dramatically reducing computational cost.

C.7 Outcome and Comparison.

JSS reduces the training size by a factor of m (the number of candidates per query), transforming the full probability matrix $\mathbf{P} \in \mathbb{R}^{n \times m}$ into a single informative column vector $\mathbf{p}^* \in \mathbb{R}^n$. This compression preserves the informativeness required for calibration while eliminating redundancy. Unlike naive random sampling, which risks discarding boundary instances with high informativeness, JSS consistently identifies the most valuable instance. Empirical results and theoretical analysis confirm that JSS improves both efficiency and reliability in calibration training.

D Limitations of KL Divergence in High-Cardinality Calibration

Kullback–Leibler (KL) divergence is one of the most widely used loss functions in deep learning and probability calibration. However, when applied to high-cardinality tasks such as entity prediction in KGE models, KL divergence exhibits critical limitations that undermine its effectiveness. Each query in KGE involves tens of thousands of candidate entities, yielding probability distributions with extremely sparse support and long tails of near-zero values. In such regimes, KL divergence is prone to gradient vanishing and gradient explosion, leading to instability during optimization.

Failure modes. Two issues are particularly problematic: (i) when the true label probability q_i is nonzero but the predicted probability $p_i \rightarrow 0$, the KL term becomes negligible, suppressing the

contribution of informative but low-probability instances; (ii) when $p_i > 0$ but $q_i = 0$, the divergence becomes infinite, yielding unstable or divergent gradients. Both behaviors compromise the robustness of calibration in large-scale KGE settings.

Formal definition. Let p and q be two discrete probability distributions over a finite set \mathcal{X} . The KL divergence from q to p is defined as:

$$D_{\text{KL}}(p \parallel q) = \sum_{x \in \mathcal{X}} p(x) \log \frac{p(x)}{q(x)}. \quad (23)$$

While this expression is well-defined when both $p(x) > 0$ and $q(x) > 0$, edge cases involving zero probabilities require special attention. Below, we analyze two important cases.

Case 1: $p(x) = 0$

If $p(x) = 0$, the corresponding term is:

$$0 \cdot \log \frac{0}{q(x)}. \quad (24)$$

Although $\log 0$ is undefined, this product is conventionally set to 0, justified by the limit:

$$\lim_{u \rightarrow 0^+} u \log \frac{u}{q(x)} = 0. \quad (25)$$

Hence, for both analytical and numerical purposes:

$$p(x) \log \frac{p(x)}{q(x)} = 0 \quad \text{when } p(x) = 0. \quad (26)$$

Case 2: $q(x) = 0$ and $p(x) > 0$

If $p(x) > 0$ but $q(x) = 0$, the ratio inside the logarithm diverges:

$$\log \frac{p(x)}{q(x)} = +\infty, \quad (27)$$

and thus the corresponding term is:

$$\begin{aligned} D_{\text{KL}}(p \parallel q) &= +\infty \quad \text{if } \exists x \in \mathcal{X} \\ &\quad \text{such that } p(x) > 0 \\ &\quad \text{and } q(x) = 0. \end{aligned} \quad (28)$$

Summary

Each term $p(x) \log \frac{p(x)}{q(x)}$ in the KL divergence admits the following interpretation:

- If $p(x) = 0$, the contribution is defined as 0 (by convention via limiting argument).

Table 9: Statistics of the used KGE datasets.

| dataset | #Entity | #Relation | #Training | #Validation | #Testing |
|-----------|---------|-----------|-----------|-------------|----------|
| WN18 | 40,943 | 18 | 141,442 | 5,000 | 5,000 |
| WN18RR | 40,943 | 11 | 86,835 | 3,034 | 3,134 |
| FB15K | 14,951 | 1,345 | 483,142 | 50,000 | 59,071 |
| FB15K-237 | 14,541 | 237 | 272,115 | 17,535 | 20,466 |

- If $p(x) > 0$ and $q(x) = 0$, the contribution is $+\infty$, making the divergence infinite.

Thus, KL divergence is finite if and only if the support of p is a subset of the support of q :

$$D_{\text{KL}}(p \parallel q) = \begin{cases} \sum_x p(x) \log \frac{p(x)}{q(x)}, & \text{if } \text{supp}(p) \\ & \subseteq \text{supp}(q), \\ +\infty, & \text{otherwise.} \end{cases} \quad (29)$$

Implication for KGE calibration. This support mismatch arises frequently in knowledge graph entity prediction, where sparse distributions and zero-valued targets dominate. In practice, it yields vanishing gradients for informative low-probability entities and exploding gradients when mismatched supports occur. These issues render KL divergence unstable and unreliable as a calibration loss, motivating our adoption of the Wasserstein distance in Section 4.3, which remains finite and geometrically meaningful even under sparse distributions.

E Dataset Statistics

Table 9 summarizes the key statistics of the benchmark KGE datasets used in our experiments. All four datasets are widely adopted in the link prediction literature, with FB15K (Bordes et al., 2013) and WN18 (Bordes et al., 2013) serving as the original benchmarks. However, both contain a substantial number of inverse or redundant relations, which can cause information leakage across training, validation, and testing splits, leading to overly optimistic results. To address this issue, FB15K-237 was introduced by Toutanova and Chen (2015) as a cleaned version of FB15K, obtained by removing near-duplicate and inverse relations so that test triples cannot be trivially inferred from training data. Similarly, WN18RR (Dettmers et al., 2018) was constructed from WN18 by excluding inverse relations, thereby providing a more challenging and realistic evaluation benchmark. Each dataset is publicly available and comes pre-partitioned into training, validation, and testing splits, which we use without modification.

These datasets differ substantially in both scale and relational complexity. For example, FB15K

Table 10: Score functions of popular KGE models. Here, $\|\cdot\|$ denotes the L_1 norm, $\langle \cdot \rangle$ denotes the generalized dot product, \mathbf{t}^* is the complex conjugate of \mathbf{t} , $\text{Re}(\cdot)$ extracts the real part of a complex number, and \circ denotes the Hadamard (element-wise) product.

| KGE Model | Score Function |
|----------------------------------|---|
| TransE (Bordes et al., 2013) | $-\ \mathbf{h} + \mathbf{r} - \mathbf{t}\ $ |
| DistMult (Yang et al., 2015) | $\langle \mathbf{r}, \mathbf{h}, \mathbf{t} \rangle$ |
| ComplEx (Trouillon et al., 2016) | $\text{Re}(\langle \mathbf{r}, \mathbf{h}, \mathbf{t}^* \rangle)$ |
| RotatE (Sun et al., 2019) | $-\ \mathbf{h} \circ \mathbf{r} - \mathbf{t}\ $ |

contains over 1,300 relation types, while FB15K-237 reduces this number to 237 to mitigate redundancy. WN18 and WN18RR share the same set of entities (40,943) but differ in their relation sets, with WN18RR offering a more robust evaluation by removing symmetric and inverse patterns. Together, these datasets span diverse characteristics of real-world knowledge graphs, covering both lexical (WordNet-based) and factual (Freebase-based) domains. Notably, the large entity space in FB15K and FB15K-237 introduces a long-tailed distribution of candidate entities, which poses significant challenges for probability calibration: most classes receive extremely low predicted probabilities, amplifying the issues of sparsity and miscalibration that our proposed method is designed to address.

F Score Functions of Popular KGE Models

We summarize the score functions of several widely used KGE models in Table 10. These definitions provide the basis for the experiments discussed in the Section 5. Beyond link prediction, KGE models have also been successfully applied to a broad range of tasks, such as entity alignment (Sun et al., 2018), canonicalization (Yang and Curry, 2024; Yang et al., 2025), and question answering (Bordes et al., 2014), highlighting their versatility and impact across diverse knowledge-intensive applications.

G Detailed Experimental Results on Efficiency Study for RQ2

To complement the aggregated efficiency results in Table 3 in Section 5.3, we present a fine-grained breakdown of calibration costs across different datasets and KGE models in Table 11. Specifically, the table reports both the training time (in seconds) and peak memory usage (in MBs) required to calibrate entity prediction under CPU-only en-

vironments, ensuring a fair comparison across all methods.

This detailed analysis provides two important insights. First, it reveals the scalability challenges of certain methods: for example, Platt Scaling (PS) and Parametrized Temperature Scaling (PTS) incur prohibitive computational overhead on larger datasets such as FB15K, making them impractical for large-scale applications. In contrast, lightweight approaches such as Vector Scaling (VS), Temperature Scaling (TS), and our proposed KGE method exhibit consistently low resource consumption. Second, the memory profiles highlight significant disparities: PTS can require over 8 GB of memory on FB15K, whereas KGE achieves state-of-the-art calibration accuracy with average memory usage of only ~ 22 MB.

Overall, Table 11 demonstrates that KGE not only achieves superior calibration performance but also remains the most resource-efficient approach across all benchmarks. These results further support the conclusions in Section 5.3, where we argued that efficiency is essential for deploying calibration in knowledge-intensive systems.

H Detailed Experimental Results on Ablation Study for RQ3

In this section, we provide the complete experimental results for our ablation study.

Table 12 reports the detailed performance of each component in KGE across individual datasets and KGE models, covering all evaluation metrics (ECE, ACE, NLL, training time, and memory usage). These results complement the averaged findings presented in Section 5.4 by illustrating the effect of each component in a fine-grained manner.

Effectiveness of JSS vs. Random Sampling. Beyond the above comparisons, we further analyze the effectiveness of JSS against a Random Sampling baseline to directly validate its contribution. JSS consistently retains the most informative sample per query, thereby guiding the calibration process more effectively. In contrast, Random Sampling often discards informative instances and introduces instability in large class spaces, leading to degraded calibration. As shown in Figure 4, JSS achieves markedly better calibration across all metrics (ECE: 0.388 vs. 0.467, ACE: 0.348 vs. 0.495, NLL: 3.396 vs. 5.725). These results highlight that JSS simultaneously enhances efficiency and preserves calibration quality, whereas Random

Table 11: Training time in seconds and memory usage in MBs taken to calibrate entity prediction using different calibration methods. Best and second-ranked results are in bold and underlined, respectively. For a fair comparison, these results are obtained using CPU only.

| Time | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
|------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|--------------|
| | WN18 | WN18RR | FB15K | FB15K-237 | |
| PS | 50551.471 | 32130.612 | 66566.552 | 22756.968 | 44484.280 | 27740.023 | 66631.859 | 20060.975 | 48902.412 | 31739.057 | 58074.230 | 21682.032 | 46162.422 | 30198.810 | 65506.688 | 20522.725 | 40856.945 |
| VS | 2.857 | 1.893 | 25.357 | 3.493 | 2.661 | 1.620 | 16.228 | 3.218 | 4.114 | 1.914 | 20.779 | 3.456 | 2.656 | 1.706 | 25.995 | 3.277 | <u>2.577</u> |
| TS | 5.235 | 3.207 | 20.037 | 6.475 | 5.063 | 3.121 | 18.825 | 6.276 | 5.180 | 3.204 | 19.734 | 6.412 | 5.456 | 3.171 | 20.046 | 6.345 | 8.649 |
| PTS | 3452.440 | 2123.849 | 16769.166 | 5856.000 | 3432.436 | 2122.273 | 16510.019 | 5764.345 | 3450.331 | 2120.555 | 16898.528 | 5868.468 | 3425.148 | 2113.001 | 16802.984 | 5853.287 | 7035.177 |
| KGEC | 2.727 | 1.776 | 10.873 | 3.602 | 2.698 | 1.727 | 10.560 | 3.624 | 2.741 | 1.696 | 10.645 | 3.705 | 2.662 | 1.658 | 10.758 | 4.003 | 4.716 |

| Memory | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
|--------|----------|----------|-----------|-----------|----------|----------|-----------|-----------|----------|----------|-----------|-----------|----------|----------|-----------|-----------|---------------|
| | WN18 | WN18RR | FB15K | FB15K-237 | |
| PS | 1564.336 | 950.762 | 5706.102 | 1948.508 | 1566.598 | 950.270 | 5706.832 | 1948.664 | 1565.820 | 949.633 | 5705.828 | 1947.574 | 1566.477 | 950.793 | 5706.875 | 1948.371 | 2542.715 |
| VS | 84.477 | 84.383 | 86.098 | 84.348 | 82.059 | 83.152 | 86.918 | 80.770 | 83.609 | 83.883 | 80.883 | 81.320 | 80.570 | 83.145 | 86.152 | 80.941 | <u>83.294</u> |
| TS | 1562.625 | 948.453 | 5703.750 | 1947.629 | 1562.984 | 949.285 | 5703.047 | 1945.566 | 1562.340 | 948.504 | 5704.801 | 1945.828 | 1562.914 | 948.566 | 5703.359 | 1944.730 | 2540.274 |
| PTS | 6655.574 | 7017.359 | 11154.340 | 9554.723 | 6804.816 | 7022.313 | 10185.500 | 9629.871 | 6957.012 | 6969.055 | 10180.105 | 9407.988 | 7047.270 | 7047.051 | 10521.520 | 8659.395 | 8410.493 |
| KGEC | 30.484 | 28.289 | 7.570 | 15.273 | 26.652 | 32.176 | 9.535 | 15.285 | 34.316 | 32.047 | 10.531 | 13.492 | 34.320 | 32.191 | 7.551 | 16.930 | 21.665 |

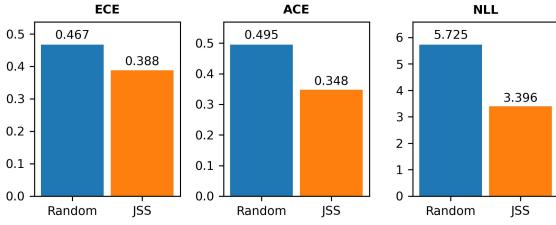


Figure 4: Overall comparison between Random sample and JSS in KGEC, showing average performance across all datasets and KGE models. Lower values of ECE, ACE, and NLL indicate better performance.

Sampling fails to achieve this balance.

In addition, Table 13 presents a focused comparison between JSS and a Random Sampling baseline across four representative KGE models and multiple datasets. Results are reported on the three calibration metrics (ECE, ACE, and NLL), where lower values indicate better performance. This table provides the full results underlying the summary trends shown in Figure 4, further demonstrating the effectiveness and stability of JSS over Random Sampling.

I Sensitivity Analysis

To assess the robustness and stability of our proposed KGEC method, we conduct a comprehensive sensitivity analysis by varying three critical hyperparameters: the number of bins, the initial temperature, and the learning rate. We evaluate the impact of each parameter on three calibration metrics, i.e., ECE, ACE, and NLL, across all KGE models and datasets. Results are summarized in Tables 14, 15, and 16.

Effect of the Number of Bins. We vary the number of bins from 1 to 20. Table 14 shows that using only one bin (equivalent to vanilla temperature scaling) results in poor performance across all metrics, highlighting its limited flexibility. As the

number of bins increases, KGEC becomes more expressive and better calibrated. The best average performance is observed at 19 bins (ECE = 0.352, ACE = 0.343, NLL = 3.361), though results are stable within the 10–20 bin range. This confirms the importance of multi-binning for modeling diverse score distributions, while also indicating that KGEC is robust to bin selection within a reasonable interval.

Effect of Initial Temperature. We examine initial temperature values ranging from 0 to 2.0. As shown in Table 15, extreme initializations (e.g., 0.0 or 2.0) lead to degraded performance due to optimization instability. An initial temperature of 1.0 yields the best results (ECE = 0.388, ACE = 0.348, NLL = 3.396), aligning with standard practice in temperature scaling (Guo et al., 2017). The results indicate that KGEC is relatively insensitive to this hyperparameter, as long as it is initialized within a moderate range.

Effect of Learning Rate. Table 16 presents results under learning rates ranging from 0.001 to 0.1. We find that too small learning rates (e.g., 0.001) may underfit the calibration model, while overly large values (e.g., 0.1) can cause instability and degraded performance. The learning rate of 0.01 achieves the best overall calibration (ECE = 0.388, ACE = 0.348, NLL = 3.396), striking a balance between convergence speed and stability.

Summary. Across all experiments, KGEC demonstrates strong robustness to hyperparameter variations. The best performance is consistently achieved with moderate hyperparameter values: a bin count between 10 and 20, an initial temperature near 1.0, and a learning rate around 0.01. These findings suggest that KGEC is both stable and practical, requiring minimal hyperparameter tuning for optimal performance across diverse KGE models and datasets.

Table 12: Effect of each component in KGE on the performance and efficiency of various KGE models across multiple datasets. For all the five metrics, the lower the better.

| ECE | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
|-------------------|---------|---------|---------|-----------|---------|---------|---------|-----------|----------|---------|---------|-----------|---------|--------|---------|-----------|---------|
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| KGEC-loss-MBS-JSS | 0.642 | 0.195 | 0.637 | 0.213 | 0.852 | 0.423 | 0.691 | 0.228 | 0.528 | 0.389 | 0.689 | 0.220 | 0.805 | 0.383 | 0.671 | 0.222 | 0.487 |
| KGEC-loss-MBS | 0.634 | 0.196 | 0.637 | 0.213 | 0.852 | 0.423 | 0.691 | 0.228 | 0.528 | 0.389 | 0.688 | 0.220 | 0.821 | 0.383 | 0.672 | 0.222 | 0.487 |
| KGEC-loss | 0.611 | 0.196 | 0.408 | 0.199 | 0.824 | 0.377 | 0.689 | 0.161 | 0.501 | 0.388 | 0.683 | 0.165 | 0.813 | 0.327 | 0.642 | 0.215 | 0.450 |
| KGEC | 0.171 | 0.280 | 0.459 | 0.150 | 0.833 | 0.418 | 0.678 | 0.189 | 0.446 | 0.383 | 0.683 | 0.178 | 0.467 | 0.307 | 0.466 | 0.094 | 0.388 |
| ACE | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| KGEC-loss-MBS-JSS | 0.517 | 0.285 | 0.636 | 0.168 | 0.852 | 0.423 | 0.691 | 0.227 | 0.527 | 0.389 | 0.688 | 0.220 | 0.405 | 0.383 | 0.636 | 0.220 | 0.454 |
| KGEC-loss-MBS | 0.516 | 0.285 | 0.630 | 0.168 | 0.852 | 0.423 | 0.690 | 0.227 | 0.527 | 0.389 | 0.688 | 0.220 | 0.402 | 0.383 | 0.636 | 0.220 | 0.454 |
| KGEC-loss | 0.510 | 0.283 | 7.651 | 0.943 | 0.823 | 0.350 | 0.670 | 0.161 | 0.501 | 0.388 | 0.666 | 0.163 | 0.401 | 0.278 | 3.092 | 0.308 | 1.074 |
| KGEC | 0.131 | 0.277 | 0.293 | 0.082 | 0.833 | 0.418 | 0.465 | 0.207 | 0.457 | 0.383 | 0.516 | 0.199 | 0.467 | 0.306 | 0.466 | 0.063 | 0.348 |
| NLL | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| KGEC-loss-MBS-JSS | 2.827 | 6.544 | 3.270 | 5.177 | 6.830 | 7.777 | 5.329 | 7.294 | 7.384 | 7.820 | 5.294 | 7.485 | 1.313 | 6.107 | 3.465 | 5.531 | 5.590 |
| KGEC-loss-MBS | 2.834 | 6.544 | 3.310 | 5.189 | 6.831 | 7.778 | 5.311 | 7.300 | 7.384 | 7.812 | 5.265 | 7.479 | 1.304 | 6.107 | 3.470 | 5.521 | 5.590 |
| KGEC-loss | 2.834 | 6.330 | 0.687 | 4.093 | 4.856 | 7.636 | 6.732 | 3.811 | 5.407 | 7.772 | 6.444 | 3.950 | 1.309 | 6.327 | 5.014 | 6.156 | 4.960 |
| KGEC | 2.462 | 5.965 | 2.536 | 2.889 | 4.350 | 6.965 | 1.357 | 2.911 | 2.843 | 7.119 | 1.319 | 3.106 | 1.036 | 4.698 | 2.033 | 2.743 | 3.396 |
| Training Time / s | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| KGEC-loss-MBS-JSS | 39.769 | 24.194 | 139.544 | 54.700 | 40.996 | 23.856 | 148.151 | 50.186 | 39.602 | 24.557 | 147.145 | 52.021 | 30.659 | 24.270 | 153.269 | 52.023 | 65.871 |
| KGEC-loss-MBS | 2.894 | 1.638 | 11.442 | 3.598 | 2.714 | 1.611 | 10.166 | 3.546 | 2.661 | 1.645 | 10.147 | 3.603 | 2.825 | 1.608 | 10.760 | 3.695 | 4.659 |
| KGEC-loss | 2.785 | 1.676 | 10.305 | 3.598 | 2.915 | 1.650 | 10.246 | 3.597 | 2.660 | 1.644 | 10.490 | 3.527 | 2.671 | 1.605 | 10.747 | 3.578 | 4.606 |
| KGEC | 2.727 | 1.776 | 10.873 | 3.602 | 2.698 | 1.727 | 10.560 | 3.624 | 2.741 | 1.696 | 10.645 | 3.705 | 2.662 | 1.658 | 10.758 | 4.003 | 4.716 |
| Memory Usage / MB | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| KGEC-loss-MBS-JSS | 161.801 | 126.141 | 58.465 | 50.965 | 170.859 | 111.168 | 41.953 | 65.574 | 174.496 | 124.086 | 56.414 | 56.473 | 160.766 | 94.270 | 45.000 | 63.301 | 97.608 |
| KGEC-loss-MBS | 29.027 | 27.121 | 6.871 | 17.969 | 31.258 | 26.676 | 7.535 | 10.391 | 25.426 | 27.184 | 8.750 | 14.277 | 32.906 | 30.742 | 6.422 | 17.961 | 20.032 |
| KGEC-loss | 29.414 | 27.145 | 6.898 | 18.016 | 25.645 | 26.879 | 8.145 | 10.375 | 32.254 | 26.613 | 8.695 | 14.320 | 32.754 | 30.965 | 10.172 | 17.316 | 20.350 |
| KGEC | 30.484 | 28.289 | 7.570 | 15.273 | 26.652 | 32.176 | 9.535 | 15.285 | 34.316 | 32.047 | 10.531 | 13.492 | 34.320 | 32.191 | 7.551 | 16.930 | 21.665 |

Table 13: Ablation study on the effectiveness of the JSS component in KGEC. We compare KGEC with JSS against a Random baseline across four KGE models (TransE, ComplEx, DistMult, RotatE) on multiple datasets. Results are reported using ECE, ACE, and NLL, where lower values indicate better performance.

| ECE | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
|--------|--------|--------|-------|-----------|---------|--------|-------|-----------|----------|--------|-------|-----------|--------|--------|-------|-----------|---------|
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| Random | 0.474 | 0.199 | 0.644 | 0.199 | 0.851 | 0.423 | 0.697 | 0.228 | 0.527 | 0.390 | 0.697 | 0.221 | 0.579 | 0.398 | 0.714 | 0.225 | 0.467 |
| JSS | 0.171 | 0.280 | 0.459 | 0.150 | 0.833 | 0.418 | 0.678 | 0.189 | 0.446 | 0.383 | 0.683 | 0.178 | 0.467 | 0.307 | 0.466 | 0.094 | 0.388 |
| ACE | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| Random | 0.486 | 0.292 | 0.936 | 0.259 | 0.851 | 0.423 | 0.697 | 0.228 | 0.527 | 0.390 | 0.697 | 0.220 | 0.579 | 0.398 | 0.714 | 0.225 | 0.495 |
| JSS | 0.131 | 0.277 | 0.293 | 0.082 | 0.833 | 0.418 | 0.465 | 0.207 | 0.457 | 0.383 | 0.516 | 0.199 | 0.467 | 0.306 | 0.466 | 0.063 | 0.348 |
| NLL | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| Random | 3.028 | 6.518 | 2.575 | 3.355 | 6.497 | 7.761 | 6.043 | 7.577 | 7.222 | 8.007 | 6.338 | 7.735 | 1.721 | 6.516 | 4.880 | 5.825 | 5.725 |
| JSS | 2.462 | 5.965 | 2.536 | 2.889 | 4.350 | 6.965 | 1.357 | 2.911 | 2.843 | 7.119 | 1.319 | 3.106 | 1.036 | 4.698 | 2.033 | 2.743 | 3.396 |

Figure 5: Case 1 from the WN18RR dataset using the TransE model.

| Ranked candidate entities | Uncalibrated scores | Calibrated probabilities |
|--------------------------------------|---------------------|--------------------------|
| 'North_Atlantic_Treaty_O rganization | 1.9763 | 0.3756 |
| Netherlands | 1.6756 | 0.2781 |
| European_Union | 0.9763 | 0.1382 |
| Benelux | 0.9763 | 0.1382 |
| Apeldoorn | -0.4998 | 0.0316 |
| Leiden | -0.5236 | 0.0308 |
| Friesian_Islands | -0.5844 | 0.0290 |
| Friesland | -0.6578 | 0.0270 |
| Netherlander | -0.6780 | 0.0264 |
| British_Commonwealth | -0.7083 | 0.0256 |

Figure 6: Case 2 from the WN18RR dataset using the TransE model.

J Case Study

To illustrate the practical benefits of KGEC calibration, we present two representative case studies from the WN18RR dataset using the TransE model, as shown in Figure 5 and Figure 6. These

examples highlight how calibrated probabilities offer more interpretable and informative confidence scores compared to raw, uncalibrated scores.

Case 1: (Greece, _member_of_domain_region, ?) The ground-truth answer for this query is *sibyl*, which is ranked third among the candidate entities based on the model’s raw scores. However, the uncalibrated scores do not reflect a meaningful confidence distribution, with the top-ranked entity *Greece* receiving a score of -0.1873 and the correct answer *sibyl* receiving -0.5992 , a difference that is difficult to interpret probabilistically.

After applying KGEC calibration, the corresponding estimates become more interpretable:

- *Greece*: 0.0302
- *Holy See*: 0.0272
- *sibyl* (true answer): 0.0200

These calibrated estimates clearly reflect the uncertainty inherent in the model’s prediction. Although the correct answer is not ranked first, its estimate is close to that of the top candidates, suggesting it is still a plausible prediction. This shows that KGEC can better express confidence levels, especially in cases with closely competing candidates.

Case 2: (North_Atlantic_Treaty_Organization, _member_meronym, ?) In this case, the true answer is *Netherlands*, which is correctly ranked second. The raw score of the correct answer (1.6756) is only slightly lower than that of the top-ranked entity *North Atlantic Treaty Organization* (1.9763), but the significance of this difference is unclear without proper calibration.

With KGEC, the calibrated estimates provide a more informative picture:

- *North Atlantic Treaty Organization*: 0.3756
- *Netherlands* (true answer): 0.2781
- *European Union*: 0.1382

Here, although the true answer is not ranked first, its calibrated estimate is still relatively high, reflecting the model’s uncertainty and partially shared semantics among top candidates. This enables downstream applications to interpret and potentially leverage multiple candidates rather than over-committing to the top-1 prediction.

Insights. These case studies demonstrate that:

- KGEC enhances the interpretability of model outputs by transforming unnormalized scores into well-calibrated estimates.

- It allows more accurate reflection of confidence levels, particularly in ambiguous or competitive ranking situations.
- Even when the top-1 prediction is incorrect, KGEC highlights alternative candidates with meaningful confidence, which is valuable for applications such as knowledge graph reasoning, question answering, and downstream ensemble methods.

Overall, these cases exemplify the effectiveness of KGEC in improving the trustworthiness and usability of KGE models.

Table 14: Effect of different number of bins in KGE on the performance of various KGE models across multiple datasets. For all the three metrics, the lower the better.

| ECE | TransE | | | ComplEx | | | DistMult | | | RotatE | | | Average |
|--------|--------|--------|-------|-----------|-------|--------|----------|-----------|-------|--------|-------|-----------|---------|
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| Bin=1 | 0.702 | 0.196 | 0.586 | 0.198 | 0.851 | 0.422 | 0.642 | 0.227 | 0.527 | 0.389 | 0.687 | 0.221 | 0.904 |
| Bin=2 | 0.305 | 0.316 | 0.581 | 0.184 | 0.850 | 0.422 | 0.677 | 0.190 | 0.521 | 0.387 | 0.683 | 0.219 | 0.476 |
| Bin=3 | 0.214 | 0.238 | 0.498 | 0.183 | 0.848 | 0.422 | 0.677 | 0.190 | 0.515 | 0.385 | 0.683 | 0.180 | 0.467 |
| Bin=4 | 0.245 | 0.249 | 0.491 | 0.180 | 0.848 | 0.421 | 0.677 | 0.190 | 0.447 | 0.385 | 0.682 | 0.179 | 0.486 |
| Bin=5 | 0.235 | 0.262 | 0.479 | 0.182 | 0.848 | 0.420 | 0.677 | 0.189 | 0.447 | 0.385 | 0.682 | 0.179 | 0.470 |
| Bin=6 | 0.211 | 0.260 | 0.514 | 0.170 | 0.848 | 0.419 | 0.677 | 0.189 | 0.447 | 0.384 | 0.682 | 0.179 | 0.487 |
| Bin=7 | 0.159 | 0.273 | 0.457 | 0.147 | 0.848 | 0.418 | 0.678 | 0.189 | 0.447 | 0.384 | 0.682 | 0.179 | 0.451 |
| Bin=8 | 0.194 | 0.269 | 0.460 | 0.161 | 0.848 | 0.418 | 0.678 | 0.189 | 0.446 | 0.384 | 0.682 | 0.179 | 0.464 |
| Bin=9 | 0.181 | 0.276 | 0.444 | 0.160 | 0.841 | 0.418 | 0.678 | 0.189 | 0.446 | 0.384 | 0.683 | 0.178 | 0.464 |
| Bin=10 | 0.171 | 0.280 | 0.459 | 0.150 | 0.833 | 0.418 | 0.678 | 0.189 | 0.446 | 0.383 | 0.683 | 0.178 | 0.467 |
| Bin=11 | 0.164 | 0.283 | 0.416 | 0.137 | 0.833 | 0.418 | 0.678 | 0.189 | 0.446 | 0.383 | 0.683 | 0.178 | 0.476 |
| Bin=12 | 0.163 | 0.281 | 0.388 | 0.162 | 0.833 | 0.418 | 0.678 | 0.189 | 0.446 | 0.383 | 0.683 | 0.178 | 0.475 |
| Bin=13 | 0.148 | 0.287 | 0.370 | 0.123 | 0.835 | 0.418 | 0.678 | 0.189 | 0.446 | 0.383 | 0.683 | 0.178 | 0.471 |
| Bin=14 | 0.125 | 0.293 | 0.376 | 0.140 | 0.835 | 0.417 | 0.677 | 0.189 | 0.446 | 0.382 | 0.683 | 0.178 | 0.472 |
| Bin=15 | 0.102 | 0.294 | 0.336 | 0.129 | 0.824 | 0.417 | 0.678 | 0.189 | 0.446 | 0.381 | 0.682 | 0.178 | 0.475 |
| Bin=16 | 0.154 | 0.296 | 0.349 | 0.061 | 0.769 | 0.416 | 0.677 | 0.189 | 0.446 | 0.379 | 0.682 | 0.178 | 0.472 |
| Bin=17 | 0.120 | 0.296 | 0.313 | 0.064 | 0.764 | 0.415 | 0.585 | 0.189 | 0.446 | 0.377 | 0.682 | 0.178 | 0.478 |
| Bin=18 | 0.115 | 0.293 | 0.256 | 0.085 | 0.749 | 0.415 | 0.589 | 0.189 | 0.446 | 0.377 | 0.640 | 0.178 | 0.472 |
| Bin=19 | 0.113 | 0.293 | 0.256 | 0.084 | 0.749 | 0.415 | 0.579 | 0.189 | 0.446 | 0.377 | 0.603 | 0.178 | 0.482 |
| Bin=20 | 0.135 | 0.298 | 0.261 | 0.073 | 0.753 | 0.416 | 0.580 | 0.189 | 0.445 | 0.376 | 0.577 | 0.178 | 0.478 |
| ACE | TransE | | | ComplEx | | | DistMult | | | RotatE | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| Bin=1 | 0.598 | 0.285 | 0.565 | 0.158 | 0.851 | 0.422 | 0.633 | 0.227 | 0.527 | 0.389 | 0.686 | 0.221 | 0.385 |
| Bin=2 | 0.318 | 0.323 | 0.406 | 0.128 | 0.849 | 0.422 | 0.494 | 0.217 | 0.519 | 0.387 | 0.538 | 0.217 | 0.476 |
| Bin=3 | 0.232 | 0.243 | 0.378 | 0.104 | 0.848 | 0.422 | 0.491 | 0.217 | 0.511 | 0.385 | 0.533 | 0.217 | 0.467 |
| Bin=4 | 0.171 | 0.253 | 0.328 | 0.097 | 0.848 | 0.421 | 0.488 | 0.213 | 0.460 | 0.385 | 0.530 | 0.213 | 0.449 |
| Bin=5 | 0.155 | 0.264 | 0.307 | 0.099 | 0.848 | 0.420 | 0.484 | 0.211 | 0.460 | 0.385 | 0.529 | 0.210 | 0.458 |
| Bin=6 | 0.125 | 0.262 | 0.261 | 0.083 | 0.848 | 0.419 | 0.481 | 0.210 | 0.460 | 0.384 | 0.527 | 0.204 | 0.457 |
| Bin=7 | 0.135 | 0.271 | 0.277 | 0.061 | 0.848 | 0.418 | 0.478 | 0.209 | 0.460 | 0.384 | 0.526 | 0.204 | 0.451 |
| Bin=8 | 0.129 | 0.267 | 0.264 | 0.080 | 0.848 | 0.418 | 0.475 | 0.208 | 0.457 | 0.384 | 0.522 | 0.203 | 0.464 |
| Bin=9 | 0.142 | 0.274 | 0.270 | 0.085 | 0.841 | 0.418 | 0.471 | 0.208 | 0.457 | 0.384 | 0.521 | 0.200 | 0.463 |
| Bin=10 | 0.131 | 0.277 | 0.293 | 0.082 | 0.833 | 0.418 | 0.465 | 0.207 | 0.457 | 0.383 | 0.516 | 0.199 | 0.467 |
| Bin=11 | 0.111 | 0.280 | 0.278 | 0.076 | 0.833 | 0.418 | 0.460 | 0.207 | 0.457 | 0.383 | 0.513 | 0.199 | 0.461 |
| Bin=12 | 0.107 | 0.278 | 0.259 | 0.100 | 0.833 | 0.418 | 0.456 | 0.207 | 0.457 | 0.383 | 0.508 | 0.199 | 0.475 |
| Bin=13 | 0.128 | 0.284 | 0.240 | 0.077 | 0.834 | 0.418 | 0.450 | 0.206 | 0.457 | 0.383 | 0.503 | 0.197 | 0.471 |
| Bin=14 | 0.113 | 0.291 | 0.238 | 0.088 | 0.834 | 0.417 | 0.446 | 0.205 | 0.455 | 0.382 | 0.497 | 0.196 | 0.471 |
| Bin=15 | 0.107 | 0.292 | 0.239 | 0.086 | 0.823 | 0.417 | 0.441 | 0.204 | 0.455 | 0.381 | 0.492 | 0.195 | 0.475 |
| Bin=16 | 0.111 | 0.294 | 0.234 | 0.063 | 0.767 | 0.416 | 0.436 | 0.204 | 0.455 | 0.379 | 0.486 | 0.194 | 0.472 |
| Bin=17 | 0.100 | 0.296 | 0.237 | 0.064 | 0.762 | 0.415 | 0.550 | 0.204 | 0.453 | 0.377 | 0.481 | 0.193 | 0.478 |
| Bin=18 | 0.119 | 0.293 | 0.248 | 0.083 | 0.746 | 0.415 | 0.576 | 0.204 | 0.453 | 0.377 | 0.466 | 0.192 | 0.471 |
| Bin=19 | 0.115 | 0.293 | 0.247 | 0.090 | 0.746 | 0.415 | 0.534 | 0.203 | 0.453 | 0.377 | 0.482 | 0.192 | 0.482 |
| Bin=20 | 0.107 | 0.298 | 0.249 | 0.073 | 0.750 | 0.416 | 0.557 | 0.203 | 0.450 | 0.376 | 0.553 | 0.192 | 0.478 |
| NLL | TransE | | | ComplEx | | | DistMult | | | RotatE | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| Bin=1 | 2.544 | 6.543 | 3.910 | 4.774 | 6.524 | 7.496 | 3.589 | 7.208 | 6.944 | 7.947 | 5.152 | 8.395 | 1.165 |
| Bin=2 | 2.865 | 6.212 | 3.076 | 3.365 | 5.963 | 7.513 | 1.350 | 2.908 | 5.477 | 7.578 | 1.314 | 6.650 | 1.281 |
| Bin=3 | 2.712 | 6.265 | 2.986 | 3.290 | 5.633 | 7.513 | 1.350 | 2.908 | 4.913 | 7.338 | 1.315 | 3.101 | 1.184 |
| Bin=4 | 2.605 | 6.185 | 2.845 | 3.191 | 5.633 | 7.299 | 1.351 | 2.909 | 2.843 | 7.338 | 1.315 | 3.101 | 1.100 |
| Bin=5 | 2.537 | 6.109 | 2.766 | 3.061 | 5.633 | 7.202 | 1.351 | 2.909 | 2.843 | 7.338 | 1.315 | 3.102 | 1.088 |
| Bin=6 | 2.523 | 6.085 | 2.642 | 3.062 | 5.633 | 7.123 | 1.352 | 2.909 | 2.843 | 7.200 | 1.316 | 3.104 | 1.062 |
| Bin=7 | 2.515 | 6.023 | 2.641 | 3.112 | 5.633 | 7.009 | 1.352 | 2.910 | 2.843 | 7.200 | 1.316 | 3.104 | 1.038 |
| Bin=8 | 2.499 | 6.024 | 2.607 | 2.956 | 5.656 | 7.001 | 1.353 | 2.910 | 2.844 | 7.200 | 1.317 | 3.104 | 1.051 |
| Bin=9 | 2.493 | 5.987 | 2.602 | 2.895 | 4.835 | 6.965 | 1.355 | 2.910 | 2.843 | 7.200 | 1.317 | 3.105 | 1.035 |
| Bin=10 | 2.462 | 5.965 | 2.536 | 2.889 | 4.350 | 6.965 | 1.357 | 2.911 | 2.843 | 7.119 | 1.319 | 3.106 | 1.036 |
| Bin=11 | 2.466 | 5.944 | 2.532 | 2.898 | 4.350 | 6.965 | 1.358 | 2.911 | 2.843 | 7.119 | 1.319 | 3.106 | 1.013 |
| Bin=12 | 2.448 | 5.943 | 2.529 | 2.798 | 4.350 | 6.929 | 1.359 | 2.911 | 2.843 | 7.114 | 1.321 | 3.106 | 1.043 |
| Bin=13 | 2.447 | 5.919 | 2.486 | 2.871 | 4.415 | 6.933 | 1.360 | 2.911 | 2.843 | 7.114 | 1.323 | 3.107 | 1.022 |
| Bin=14 | 2.437 | 5.889 | 2.482 | 2.809 | 4.415 | 6.867 | 1.363 | 2.912 | 2.845 | 7.027 | 1.326 | 3.108 | 1.017 |
| Bin=15 | 2.438 | 5.880 | 2.498 | 2.803 | 3.987 | 6.867 | 1.363 | 2.912 | 2.845 | 6.935 | 1.329 | 3.108 | 1.024 |
| Bin=16 | 2.449 | 5.870 | 2.463 | 2.883 | 2.931 | 6.773 | 1.366 | 2.912 | 2.845 | 6.813 | 1.331 | 3.109 | 1.014 |
| Bin=17 | 2.434 | 5.859 | 2.487 | 2.855 | 2.873 | 6.726 | 2.678 | 2.913 | 2.846 | 6.722 | 1.333 | 3.109 | 1.023 |
| Bin=18 | 2.449 | 5.865 | 2.513 | 2.779 | 2.711 | 6.724 | 2.860 | 2.913 | 2.846 | 6.722 | 1.860 | 3.110 | 1.010 |
| Bin=19 | 2.445 | 5.862 | 2.498 | 2.745 | 2.711 | 6.733 | 2.569 | 2.913 | 2.846 | 6.682 | 2.235 | 3.110 | 1.029 |
| Bin=20 | 2.438 | 5.842 | 2.489 | 2.791 | 2.749 | 6.734 | 2.710 | 2.913 | 2.849 | 6.635 | 2.743 | 3.110 | 1.014 |

Table 15: Effect of different initial temperature parameters in KGE on the performance of various KGE models across multiple datasets. For all the three metrics, the lower the better.

| ECE | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
|----------|--------|--------|--------|-----------|---------|--------|-------|-----------|----------|--------|-------|-----------|--------|--------|--------|-----------|---------|
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| init=0 | 0.382 | 0.582 | 0.405 | 0.213 | 0.699 | 0.374 | 0.677 | 0.190 | 0.447 | 0.349 | 0.683 | 0.180 | 0.118 | 0.322 | 0.612 | 0.237 | 0.404 |
| init=0.1 | 0.382 | 0.582 | 0.312 | 0.213 | 0.699 | 0.374 | 0.677 | 0.190 | 0.447 | 0.349 | 0.683 | 0.180 | 0.118 | 0.389 | 0.670 | 0.236 | 0.406 |
| init=0.2 | 0.337 | 0.014 | 0.626 | 0.221 | 0.699 | 0.374 | 0.678 | 0.189 | 0.447 | 0.349 | 0.683 | 0.179 | 0.603 | 0.420 | 0.719 | 0.239 | 0.424 |
| init=0.3 | 0.696 | 0.013 | 0.626 | 0.221 | 0.699 | 0.374 | 0.678 | 0.189 | 0.447 | 0.349 | 0.683 | 0.179 | 0.939 | 0.428 | 0.719 | 0.239 | 0.467 |
| init=0.4 | 0.705 | 0.014 | 0.627 | 0.221 | 0.699 | 0.374 | 0.678 | 0.189 | 0.447 | 0.349 | 0.683 | 0.178 | 0.944 | 0.426 | 0.729 | 0.239 | 0.469 |
| init=0.5 | 0.706 | 0.014 | 0.645 | 0.221 | 0.699 | 0.279 | 0.678 | 0.189 | 0.447 | 0.222 | 0.683 | 0.178 | 0.944 | 0.397 | 0.709 | 0.239 | 0.453 |
| init=0.6 | 0.706 | 0.268 | 0.624 | 0.233 | 0.699 | 0.348 | 0.678 | 0.189 | 0.447 | 0.336 | 0.683 | 0.178 | 0.944 | 0.320 | 0.668 | 0.239 | 0.472 |
| init=0.7 | 0.706 | 0.390 | 0.566 | 0.233 | 0.699 | 0.384 | 0.678 | 0.189 | 0.447 | 0.356 | 0.683 | 0.178 | 0.907 | 0.244 | 0.597 | 0.239 | 0.468 |
| init=0.8 | 0.706 | 0.424 | 0.520 | 0.226 | 0.793 | 0.404 | 0.678 | 0.189 | 0.446 | 0.370 | 0.683 | 0.178 | 0.355 | 0.215 | 0.530 | 0.173 | 0.431 |
| init=0.9 | 0.444 | 0.342 | 0.496 | 0.200 | 0.823 | 0.412 | 0.678 | 0.189 | 0.446 | 0.376 | 0.683 | 0.178 | 0.402 | 0.273 | 0.492 | 0.124 | 0.410 |
| init=1.0 | 0.171 | 0.280 | 0.459 | 0.150 | 0.833 | 0.418 | 0.678 | 0.189 | 0.446 | 0.383 | 0.683 | 0.178 | 0.467 | 0.307 | 0.466 | 0.094 | 0.388 |
| init=1.1 | 0.199 | 0.232 | 0.419 | 0.109 | 0.848 | 0.420 | 0.678 | 0.189 | 0.446 | 0.386 | 0.683 | 0.178 | 0.547 | 0.331 | 0.495 | 0.098 | 0.391 |
| init=1.2 | 0.278 | 0.195 | 0.365 | 0.073 | 0.849 | 0.422 | 0.606 | 0.189 | 0.485 | 0.388 | 0.683 | 0.178 | 0.608 | 0.350 | 0.528 | 0.101 | 0.394 |
| init=1.3 | 0.340 | 0.165 | 0.335 | 0.051 | 0.850 | 0.423 | 0.592 | 0.189 | 0.513 | 0.388 | 0.683 | 0.178 | 0.656 | 0.362 | 0.551 | 0.106 | 0.399 |
| init=1.4 | 0.390 | 0.141 | 0.360 | 0.064 | 0.851 | 0.424 | 0.618 | 0.189 | 0.519 | 0.390 | 0.683 | 0.178 | 0.696 | 0.373 | 0.568 | 0.108 | 0.409 |
| init=1.5 | 0.430 | 0.122 | 0.388 | 0.082 | 0.852 | 0.425 | 0.599 | 0.190 | 0.524 | 0.390 | 0.602 | 0.178 | 0.727 | 0.382 | 0.581 | 0.133 | 0.413 |
| init=1.6 | 0.463 | 0.105 | 0.411 | 0.097 | 0.852 | 0.425 | 0.625 | 0.209 | 0.525 | 0.391 | 0.597 | 0.178 | 0.752 | 0.390 | 0.594 | 0.128 | 0.421 |
| init=1.7 | 0.491 | 0.090 | 0.429 | 0.110 | 0.852 | 0.425 | 0.611 | 0.213 | 0.526 | 0.391 | 0.609 | 0.193 | 0.773 | 0.395 | 0.609 | 0.150 | 0.429 |
| init=1.8 | 0.515 | 0.079 | 0.447 | 0.121 | 0.853 | 0.426 | 0.607 | 0.223 | 0.527 | 0.392 | 0.611 | 0.186 | 0.791 | 0.400 | 0.622 | 0.162 | 0.435 |
| init=1.9 | 0.534 | 0.069 | 0.462 | 0.133 | 0.853 | 0.426 | 0.616 | 0.223 | 0.527 | 0.392 | 0.614 | 0.198 | 0.807 | 0.404 | 0.631 | 0.167 | 0.441 |
| init=2.0 | 0.550 | 0.061 | 0.475 | 0.141 | 0.853 | 0.426 | 0.644 | 0.225 | 0.528 | 0.392 | 0.613 | 0.209 | 0.820 | 0.407 | 0.638 | 0.172 | 0.447 |
| ACE | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| init=0 | 55.708 | 27.896 | 26.189 | 4.896 | 0.679 | 0.163 | 0.515 | 0.226 | 0.471 | 0.240 | 0.547 | 0.228 | 50.620 | 3.966 | 4.828 | 1.306 | 11.155 |
| init=0.1 | 37.388 | 18.451 | 12.026 | 4.896 | 0.679 | 0.163 | 0.515 | 0.226 | 0.471 | 0.240 | 0.547 | 0.228 | 27.979 | 3.158 | 4.275 | 1.278 | 7.032 |
| init=0.2 | 8.518 | 4.825 | 2.672 | 1.805 | 0.688 | 0.160 | 0.467 | 0.210 | 0.458 | 0.238 | 0.517 | 0.201 | 8.266 | 1.911 | 2.159 | 0.995 | 2.131 |
| init=0.3 | 4.237 | 2.449 | 2.671 | 1.805 | 0.688 | 0.160 | 0.466 | 0.208 | 0.458 | 0.238 | 0.517 | 0.200 | 3.453 | 1.006 | 2.154 | 0.995 | 1.357 |
| init=0.4 | 2.585 | 1.508 | 2.646 | 1.814 | 0.688 | 0.160 | 0.465 | 0.208 | 0.457 | 0.238 | 0.516 | 0.200 | 1.404 | 0.483 | 0.288 | 0.995 | 0.916 |
| init=0.5 | 1.535 | 0.994 | 0.311 | 1.795 | 0.688 | 0.265 | 0.465 | 0.207 | 0.457 | 0.208 | 0.516 | 0.200 | 0.726 | 0.195 | 0.298 | 0.995 | 0.616 |
| init=0.6 | 0.947 | 0.721 | 0.249 | 0.392 | 0.688 | 0.347 | 0.465 | 0.207 | 0.457 | 0.335 | 0.516 | 0.200 | 0.314 | 0.119 | 0.327 | 0.994 | 0.455 |
| init=0.7 | 0.573 | 0.542 | 0.242 | 0.290 | 0.689 | 0.384 | 0.465 | 0.207 | 0.457 | 0.355 | 0.516 | 0.199 | 0.105 | 0.152 | 0.362 | 0.994 | 0.408 |
| init=0.8 | 0.307 | 0.422 | 0.257 | 0.209 | 0.792 | 0.404 | 0.465 | 0.207 | 0.457 | 0.369 | 0.516 | 0.199 | 0.230 | 0.213 | 0.402 | 0.113 | 0.348 |
| init=0.9 | 0.144 | 0.339 | 0.275 | 0.141 | 0.822 | 0.412 | 0.465 | 0.207 | 0.457 | 0.376 | 0.516 | 0.199 | 0.366 | 0.273 | 0.427 | 0.070 | 0.343 |
| init=1.0 | 0.131 | 0.277 | 0.293 | 0.082 | 0.833 | 0.418 | 0.465 | 0.207 | 0.457 | 0.383 | 0.516 | 0.199 | 0.467 | 0.306 | 0.466 | 0.063 | 0.348 |
| init=1.1 | 0.200 | 0.230 | 0.309 | 0.050 | 0.847 | 0.420 | 0.465 | 0.207 | 0.457 | 0.386 | 0.516 | 0.199 | 0.547 | 0.331 | 0.495 | 0.064 | 0.358 |
| init=1.2 | 0.278 | 0.195 | 0.331 | 0.042 | 0.848 | 0.422 | 0.582 | 0.207 | 0.478 | 0.388 | 0.516 | 0.199 | 0.608 | 0.350 | 0.528 | 0.088 | 0.379 |
| init=1.3 | 0.340 | 0.167 | 0.359 | 0.048 | 0.850 | 0.423 | 0.493 | 0.207 | 0.509 | 0.388 | 0.516 | 0.199 | 0.656 | 0.362 | 0.551 | 0.094 | 0.385 |
| init=1.4 | 0.390 | 0.145 | 0.385 | 0.059 | 0.851 | 0.424 | 0.607 | 0.207 | 0.516 | 0.390 | 0.517 | 0.199 | 0.696 | 0.373 | 0.568 | 0.095 | 0.401 |
| init=1.5 | 0.430 | 0.126 | 0.409 | 0.074 | 0.851 | 0.425 | 0.563 | 0.197 | 0.523 | 0.390 | 0.501 | 0.199 | 0.727 | 0.382 | 0.581 | 0.122 | 0.406 |
| init=1.6 | 0.463 | 0.110 | 0.429 | 0.094 | 0.852 | 0.425 | 0.618 | 0.209 | 0.525 | 0.391 | 0.509 | 0.199 | 0.752 | 0.390 | 0.594 | 0.116 | 0.417 |
| init=1.7 | 0.491 | 0.096 | 0.445 | 0.109 | 0.852 | 0.425 | 0.593 | 0.211 | 0.526 | 0.391 | 0.597 | 0.199 | 0.773 | 0.395 | 0.609 | 0.142 | 0.429 |
| init=1.8 | 0.515 | 0.086 | 0.462 | 0.121 | 0.853 | 0.426 | 0.584 | 0.222 | 0.527 | 0.392 | 0.600 | 0.197 | 0.791 | 0.400 | 0.622 | 0.158 | 0.435 |
| init=1.9 | 0.534 | 0.076 | 0.474 | 0.133 | 0.853 | 0.426 | 0.604 | 0.222 | 0.527 | 0.392 | 0.606 | 0.200 | 0.807 | 0.404 | 0.631 | 0.163 | 0.441 |
| init=2.0 | 0.550 | 0.068 | 0.485 | 0.141 | 0.853 | 0.426 | 0.644 | 0.224 | 0.528 | 0.392 | 0.604 | 0.203 | 0.820 | 0.407 | 0.638 | 0.169 | 0.447 |
| NLL | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| init=0 | -1.714 | 1.977 | -0.694 | 0.791 | 2.287 | 3.210 | 1.349 | 2.908 | 2.841 | 3.253 | 1.314 | 3.099 | -3.229 | 1.540 | -0.515 | 1.145 | 1.223 |
| init=0.1 | -1.422 | 2.230 | -0.296 | 0.791 | 2.287 | 3.210 | 1.349 | 2.908 | 2.841 | 3.253 | 1.314 | 3.099 | -2.814 | 1.620 | -0.452 | 1.150 | 1.317 |
| init=0.2 | -0.209 | 3.154 | 0.492 | 1.014 | 2.287 | 3.211 | 1.356 | 2.909 | 2.843 | 3.253 | 1.318 | 3.104 | -1.858 | 1.738 | -0.316 | 1.166 | 1.591 |
| init=0.3 | 0.378 | 3.833 | 0.493 | 1.014 | 2.288 | 3.211 | 1.356 | 2.910 | 2.843 | 3.253 | 1.319 | 3.104 | -1.191 | 2.238 | -0.315 | 1.165 | 1.744 |
| init=0.4 | 0.786 | 4.312 | 0.498 | 1.012 | 2.288 | 3.211 | 1.356 | 2.910 | 2.843 | 3.253 | 1.319 | 3.104 | -0.549 | 2.683 | 1.189 | 1.166 | 1.961 |
| init=0.5 | 1.172 | 4.722 | 1.926 | 1.016 | 2.288 | 4.151 | 1.356 | 2.910 | 2.843 | 4.318 | 1.319 | 3.105 | -0.187 | 3.085 | 1.339 | 1.166 | 2.283 |
| init=0.6 | 1.494 | 5.037 | 2.077 | 2.191 | 2.288 | 4.549 | 1.356 | 2.910 | 2.843 | 5.889 | 1.319 | 3.105 | 0.395 | 3.839 | 1.682 | 1.167 | 2.744 |
| init=0.7 | 1.777 | 5.317 | 2.191 | 2.374 | 2.288 | 5.459 | 1.356 | 2.910 | 2.843 | 5.889 | 1.319 | 3.105 | 0.395 | 3.839 | 1.682 | 1.167 | 2.744 |
| init=0.8 | 2.037 | 5.560 | 2.322 | 2.542 | 3.267 | 6.058 | 1.356 | 2.910 | 2.843 | 6.328 | 1.319 | 3.105 | 0.637 | 4.125 | 1.825 | 3.042 | 3.223 |
| init=0.9 | 2.261 | 5.773 | 2.434 | 2.710 | 3.937 | 6.483 | 1.357 | 2.910 | 2.843 | 6.642 | 1.319 | 3.106 | | | | | |

Table 16: Effect of different learning rate in KGE on the performance of various KGE models across multiple datasets. For all the three metrics, the lower the better.

| ECE | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
|----------|--------|--------|-------|-----------|---------|--------|-------|-----------|----------|--------|-------|-----------|--------|--------|-------|-----------|---------|
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| lr=0.001 | 0.184 | 0.229 | 0.469 | 0.098 | 0.852 | 0.423 | 0.644 | 0.228 | 0.528 | 0.389 | 0.659 | 0.220 | 0.492 | 0.381 | 0.498 | 0.191 | 0.405 |
| lr=0.002 | 0.172 | 0.231 | 0.517 | 0.052 | 0.852 | 0.423 | 0.608 | 0.227 | 0.527 | 0.388 | 0.596 | 0.218 | 0.476 | 0.371 | 0.456 | 0.092 | 0.388 |
| lr=0.003 | 0.199 | 0.265 | 0.534 | 0.099 | 0.851 | 0.423 | 0.593 | 0.226 | 0.527 | 0.388 | 0.594 | 0.212 | 0.481 | 0.361 | 0.467 | 0.092 | 0.395 |
| lr=0.004 | 0.203 | 0.276 | 0.535 | 0.138 | 0.851 | 0.422 | 0.595 | 0.222 | 0.526 | 0.387 | 0.605 | 0.191 | 0.478 | 0.353 | 0.480 | 0.098 | 0.398 |
| lr=0.005 | 0.179 | 0.281 | 0.521 | 0.157 | 0.850 | 0.422 | 0.594 | 0.213 | 0.525 | 0.386 | 0.612 | 0.178 | 0.479 | 0.344 | 0.476 | 0.092 | 0.394 |
| lr=0.006 | 0.202 | 0.286 | 0.520 | 0.160 | 0.849 | 0.421 | 0.678 | 0.207 | 0.522 | 0.386 | 0.683 | 0.178 | 0.477 | 0.333 | 0.483 | 0.091 | 0.405 |
| lr=0.007 | 0.201 | 0.291 | 0.497 | 0.166 | 0.849 | 0.421 | 0.678 | 0.189 | 0.517 | 0.385 | 0.683 | 0.178 | 0.472 | 0.323 | 0.462 | 0.110 | 0.401 |
| lr=0.008 | 0.188 | 0.287 | 0.491 | 0.163 | 0.846 | 0.419 | 0.678 | 0.189 | 0.495 | 0.384 | 0.683 | 0.178 | 0.466 | 0.317 | 0.455 | 0.127 | 0.398 |
| lr=0.009 | 0.188 | 0.284 | 0.478 | 0.167 | 0.843 | 0.419 | 0.678 | 0.189 | 0.446 | 0.384 | 0.683 | 0.178 | 0.467 | 0.313 | 0.463 | 0.097 | 0.392 |
| lr=0.010 | 0.171 | 0.280 | 0.459 | 0.150 | 0.833 | 0.418 | 0.678 | 0.189 | 0.446 | 0.383 | 0.683 | 0.178 | 0.467 | 0.307 | 0.466 | 0.094 | 0.388 |
| lr=0.020 | 0.152 | 0.246 | 0.380 | 0.064 | 0.699 | 0.392 | 0.678 | 0.189 | 0.446 | 0.353 | 0.683 | 0.178 | 0.514 | 0.273 | 0.560 | 0.239 | 0.378 |
| lr=0.030 | 0.184 | 0.228 | 0.460 | 0.080 | 0.699 | 0.374 | 0.677 | 0.189 | 0.446 | 0.349 | 0.683 | 0.178 | 0.562 | 0.289 | 0.606 | 0.238 | 0.390 |
| lr=0.040 | 0.244 | 0.211 | 0.507 | 0.114 | 0.699 | 0.374 | 0.678 | 0.189 | 0.446 | 0.349 | 0.683 | 0.178 | 0.598 | 0.290 | 0.638 | 0.097 | 0.393 |
| lr=0.050 | 0.305 | 0.189 | 0.530 | 0.139 | 0.699 | 0.374 | 0.677 | 0.189 | 0.446 | 0.349 | 0.682 | 0.178 | 0.623 | 0.295 | 0.652 | 0.238 | 0.410 |
| lr=0.060 | 0.342 | 0.163 | 0.554 | 0.212 | 0.699 | 0.364 | 0.677 | 0.189 | 0.446 | 0.205 | 0.683 | 0.178 | 0.635 | 0.330 | 0.674 | 0.237 | 0.412 |
| lr=0.070 | 0.393 | 0.153 | 0.569 | 0.164 | 0.699 | 0.374 | 0.677 | 0.190 | 0.526 | 0.349 | 0.683 | 0.178 | 0.656 | 0.330 | 0.679 | 0.239 | 0.429 |
| lr=0.080 | 0.418 | 0.135 | 0.577 | 0.174 | 0.699 | 0.407 | 0.678 | 0.189 | 0.446 | 0.349 | 0.682 | 0.178 | 0.685 | 0.332 | 0.680 | 0.239 | 0.429 |
| lr=0.090 | 0.456 | 0.130 | 0.584 | 0.184 | 0.826 | 0.374 | 0.677 | 0.189 | 0.446 | 0.385 | 0.683 | 0.178 | 0.716 | 0.350 | 0.693 | 0.237 | 0.444 |
| lr=0.100 | 0.494 | 0.108 | 0.590 | 0.193 | 0.699 | 0.374 | 0.677 | 0.189 | 0.527 | 0.349 | 0.683 | 0.178 | 0.742 | 0.331 | 0.696 | 0.239 | 0.442 |
| ACE | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| lr=0.001 | 0.220 | 0.237 | 0.276 | 0.098 | 0.852 | 0.423 | 0.644 | 0.227 | 0.527 | 0.388 | 0.659 | 0.219 | 0.492 | 0.380 | 0.498 | 0.190 | 0.396 |
| lr=0.002 | 0.171 | 0.236 | 0.248 | 0.037 | 0.851 | 0.423 | 0.587 | 0.226 | 0.527 | 0.388 | 0.562 | 0.216 | 0.459 | 0.370 | 0.456 | 0.069 | 0.364 |
| lr=0.003 | 0.119 | 0.263 | 0.247 | 0.049 | 0.851 | 0.423 | 0.513 | 0.225 | 0.526 | 0.388 | 0.547 | 0.205 | 0.457 | 0.361 | 0.445 | 0.069 | 0.356 |
| lr=0.004 | 0.108 | 0.273 | 0.252 | 0.075 | 0.851 | 0.422 | 0.486 | 0.220 | 0.525 | 0.387 | 0.499 | 0.198 | 0.457 | 0.352 | 0.437 | 0.063 | 0.350 |
| lr=0.005 | 0.109 | 0.278 | 0.256 | 0.092 | 0.850 | 0.422 | 0.527 | 0.211 | 0.524 | 0.386 | 0.497 | 0.199 | 0.461 | 0.344 | 0.440 | 0.067 | 0.354 |
| lr=0.006 | 0.107 | 0.283 | 0.264 | 0.095 | 0.849 | 0.421 | 0.465 | 0.208 | 0.521 | 0.386 | 0.516 | 0.199 | 0.463 | 0.333 | 0.435 | 0.065 | 0.351 |
| lr=0.007 | 0.112 | 0.288 | 0.264 | 0.101 | 0.849 | 0.421 | 0.465 | 0.207 | 0.514 | 0.385 | 0.516 | 0.199 | 0.465 | 0.323 | 0.448 | 0.066 | 0.351 |
| lr=0.008 | 0.122 | 0.284 | 0.272 | 0.097 | 0.845 | 0.419 | 0.465 | 0.207 | 0.488 | 0.384 | 0.516 | 0.199 | 0.466 | 0.317 | 0.452 | 0.071 | 0.350 |
| lr=0.009 | 0.127 | 0.281 | 0.284 | 0.100 | 0.842 | 0.419 | 0.465 | 0.207 | 0.457 | 0.384 | 0.516 | 0.199 | 0.467 | 0.313 | 0.463 | 0.062 | 0.349 |
| lr=0.010 | 0.131 | 0.277 | 0.293 | 0.082 | 0.833 | 0.418 | 0.465 | 0.207 | 0.457 | 0.383 | 0.516 | 0.199 | 0.467 | 0.306 | 0.466 | 0.063 | 0.348 |
| lr=0.020 | 0.146 | 0.244 | 0.400 | 0.048 | 0.689 | 0.392 | 0.465 | 0.207 | 0.457 | 0.352 | 0.517 | 0.199 | 0.514 | 0.273 | 0.560 | 0.994 | 0.404 |
| lr=0.030 | 0.163 | 0.227 | 0.471 | 0.075 | 0.689 | 0.160 | 0.484 | 0.207 | 0.457 | 0.238 | 0.517 | 0.199 | 0.562 | 0.289 | 0.606 | 1.010 | 0.397 |
| lr=0.040 | 0.244 | 0.211 | 0.511 | 0.114 | 0.689 | 0.160 | 0.466 | 0.207 | 0.457 | 0.238 | 0.522 | 0.199 | 0.598 | 0.290 | 0.638 | 0.085 | 0.352 |
| lr=0.050 | 0.305 | 0.191 | 0.535 | 0.139 | 0.689 | 0.160 | 0.486 | 0.207 | 0.457 | 0.238 | 0.529 | 0.199 | 0.623 | 0.295 | 0.652 | 1.115 | 0.426 |
| lr=0.060 | 0.342 | 0.167 | 0.554 | 2.220 | 0.689 | 0.364 | 0.493 | 0.207 | 0.457 | 0.189 | 0.519 | 0.199 | 0.635 | 0.330 | 0.674 | 1.067 | 0.569 |
| lr=0.070 | 0.393 | 0.157 | 0.569 | 0.164 | 0.689 | 0.160 | 0.493 | 0.212 | 0.526 | 0.238 | 0.518 | 0.199 | 0.656 | 0.330 | 0.679 | 0.987 | 0.436 |
| lr=0.080 | 0.418 | 0.139 | 0.577 | 0.174 | 0.689 | 0.407 | 0.469 | 0.207 | 0.457 | 0.238 | 0.533 | 0.199 | 0.685 | 0.332 | 0.680 | 0.986 | 0.449 |
| lr=0.090 | 0.456 | 0.136 | 0.584 | 0.184 | 0.826 | 0.160 | 0.503 | 0.208 | 0.457 | 0.383 | 0.517 | 0.200 | 0.716 | 0.350 | 0.693 | 1.142 | 0.470 |
| lr=0.100 | 0.494 | 0.114 | 0.590 | 0.193 | 0.689 | 0.160 | 0.498 | 0.208 | 0.527 | 0.240 | 0.521 | 0.200 | 0.742 | 0.331 | 0.696 | 0.997 | 0.450 |
| NLL | TransE | | | | ComplEx | | | | DistMult | | | | RotatE | | | | Average |
| | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | WN18 | WN18RR | FB15K | FB15K-237 | |
| lr=0.001 | 2.751 | 6.481 | 2.469 | 3.771 | 6.777 | 7.749 | 3.691 | 7.271 | 7.279 | 7.797 | 4.071 | 7.207 | 1.254 | 5.847 | 2.159 | 4.410 | 5.061 |
| lr=0.002 | 2.505 | 6.267 | 2.341 | 3.233 | 6.634 | 7.665 | 3.006 | 6.945 | 7.073 | 7.729 | 2.871 | 6.351 | 1.014 | 5.546 | 1.997 | 2.862 | 4.627 |
| lr=0.003 | 2.471 | 6.029 | 2.309 | 3.034 | 6.514 | 7.599 | 2.511 | 6.618 | 6.818 | 7.646 | 2.763 | 5.263 | 1.008 | 5.357 | 1.961 | 2.860 | 4.423 |
| lr=0.004 | 2.468 | 5.984 | 2.311 | 2.924 | 6.292 | 7.493 | 2.301 | 5.853 | 6.526 | 7.562 | 2.353 | 3.975 | 1.010 | 5.217 | 1.934 | 2.703 | 4.182 |
| lr=0.005 | 2.473 | 5.966 | 2.331 | 2.865 | 6.188 | 7.455 | 2.587 | 4.799 | 6.230 | 7.495 | 2.256 | 3.106 | 1.019 | 5.101 | 1.942 | 2.817 | 4.039 |
| lr=0.006 | 2.464 | 5.947 | 2.353 | 2.853 | 5.874 | 7.356 | 1.357 | 4.372 | 5.670 | 7.383 | 1.319 | 3.106 | 1.024 | 4.965 | 1.927 | 2.793 | 3.798 |
| lr=0.007 | 2.462 | 5.931 | 2.406 | 2.834 | 5.773 | 7.280 | 1.357 | 2.911 | 5.093 | 7.362 | 1.319 | 3.106 | 1.028 | 4.857 | 1.970 | 2.635 | 3.645 |
| lr=0.008 | 2.466 | 5.942 | 2.444 | 2.845 | 5.288 | 7.094 | 1.357 | 2.911 | 4.088 | 7.253 | 1.319 | 3.106 | 1.032 | 4.800 | 1.984 | 2.573 | 3.531 |
| lr=0.009 | 2.465 | 5.951 | 2.473 | 2.831 | 4.963 | 7.113 | 1.357 | 2.911 | 2.843 | 7.203 | 1.319 | 3.106 | 1.033 | 4.757 | 2.026 | 2.711 | 3.441 |
| lr=0.010 | 2.462 | 5.965 | 2.536 | 2.889 | 4.350 | 6.965 | 1.357 | 2.911 | 2.843 | 7.119 | 1.319 | 3.106 | 1.036 | 4.698 | 2.033 | 2.743 | 3.396 |
| lr=0.020 | 2.519 | 6.087 | 3.006 | 3.237 | 2.288 | 5.673 | 1.356 | 2.911 | 2.844 | 5.811 | 1.319 | 3.106 | 1.146 | 4.446 | 2.456 | 1.167 | 3.086 |
| lr=0.030 | 2.579 | 6.160 | 3.362 | 3.546 | 2.288 | 3.211 | 1.351 | 2.910 | 2.844 | 3.254 | 1.320 | 3.106 | 1.274 | 4.564 | 2.756 | 1.167 | 2.856 |
| lr=0.040 | 2.747 | 6.236 | 3.661 | 3.855 | 2.288 | 3.211 | 1.356 | 2.910 | 2.844 | 3.254 | 1.320 | 3.106 | 1.370 | 4.575 | 3.027 | 3.067 | 3.052 |
| lr=0.050 | 2.896 | 6.335 | | | | | | | | | | | | | | | |