

PRIM: Towards Practical In-Image Multilingual Machine Translation

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Abstract

In-Image Machine Translation (IIMT) aims to translate images containing texts from one language to another. Current research of end-to-end IIMT mainly conducts on synthetic data, with simple background, single font, fixed text position, and bilingual translation, which can not fully reflect real world, causing a significant gap between the research and practical conditions. To facilitate research of IIMT in real-world scenarios, we explore Practical In-Image Multilingual Machine Translation (IIMMT). In order to convince the lack of publicly available data, we annotate the PRIM dataset, which contains real-world captured one-line text images with complex background, various fonts, diverse text positions, and supports multilingual translation directions. We propose an end-to-end model VisTrans to handle the challenge of practical conditions in PRIM, which processes visual text and background information in the image separately, ensuring the capability of multilingual translation while improving the visual quality. Experimental results indicate the VisTrans achieves a better translation quality and visual effect compared to other models. The code and dataset are available at: <https://github.com/BITHLP/PRIM>.

1 Introduction

In-Image Machine Translation (IIMT) aims to transform images containing texts from one language to another (Mansimov et al., 2020; Tian et al., 2023, 2025; Lan et al., 2024; Qian et al., 2024). The challenge of IIMT lies in that both the input and output are images, detaching from the text modality, which is a significant distinction from other Neural Machine Translation (NMT) tasks incorporating image modality (Zhu et al., 2023; Liang et al., 2024; Ma et al., 2024; Li et al., 2025a; Zhang et al., 2025b; Fang and Feng, 2022; Chen et al.,

Name	Source	Features			
		ML.	RB.	Fonts.	Pos.
E2E-IIIMT (2020)	Synth.	✗	✗	✗	✗
SegPixel (2023)	Synth.	✗	✗	✓	✗
TranslatotronV (2024)	Synth.	✗	✗	✗	✓
UMTIT (2024)	Synth.	✗	✗	✗	✓
DebackX (2025)	Synth.	✗	✓	✓	✓
PRIM (Ours)	Real.	✓	✓	✓	✓

Previous Research

Tomorrow he will attempt to train with the team.

Morgen wird er versuchen, mit der Mannschaft zu trainieren.

SegPixel (2023)

Synthetic; Not Fully Reflect Real World

und die gefahr besteht darin, dass sie eine pandemie hervorrufen können.

and the danger is that they can cause roughly what's a pandemic.

TranslatotronV (2024)

Our Research

Tragbares großes Fassungsvermögen, trinken Sie einen Tag lang Wasser.

Grande capacité portable, buvez de l'eau pendant une journée,

Portable large capacity, drink for a day of water,

Practical; Captured from Real World

Figure 1: Comparison between PRIM to publicly available IIMT datasets. The sources of datasets are divided into synthetic (Synth.) and real world (Real.), and “ML.”, “RB.”, “Fonts” and “Pos.” specifies whether the dataset including multilingual translation, real-world backgrounds, various fonts and different text positions. Previous research primarily conducts on synthetic data with simple background, single font, fixed text position, and bilingual translation. Our research utilizes real-world captured images with complex background, various fonts, diverse text positions, and multilingual translation, which is more aligned to real conditions.

2025), as they still center around text, with the input or output remaining text-based.

The translated target images of IIMT help people understand texts in visual modality directly, holding significant application value in translation software. A commonly used approach for IIMT is the cascade model: It begins with using an Optical Character Recognition (OCR) model to recognize text in the source image, followed by employing an NMT model for translation. Finally, the text region in the source image is removed and rendered

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with translated target text. The drawbacks of the cascade model mainly lie in: (1) The cascade OCR-NMT procedure has the risk of error propagation and negatively affected translation quality. (2) The removing and rendering process damages the integrity of background in the image, resulting in the suboptimal visual quality of the output image.

To address the issues in the existing cascade model, recent research has focused on the end-to-end IIMT model (Mansimov et al., 2020; Tian et al., 2023; Lan et al., 2024). As shown in Figure 1, previous research mainly focuses on images with simple backgrounds, single font style, fixed text position, and bilingual translation.

However, real-world images may contain complex backgrounds, various font styles, diverse text positions, and a wide range of translation directions, which leads to certain limitations in previous research. To overcome these limitations, we explore Practical In-Image Multilingual Machine Translation (IIMMT), which emphasizes two key aspects: real-world captured images and multilingual translation. We annotate a dataset PRIM to convince the lack of publicly available real-world data, which contains real-world captured source images with one-line text and manually annotated target images. The images of PRIM include real-world backgrounds, various font styles, diverse text positions, and supporting 5 translation directions.

To tackle the challenge of practical conditions in the PRIM dataset, we design an end-to-end model **VisualTranslator** (VisTrans), which handles the visual text and background information in the image separately, with a two-stage training and multi-task learning strategy. The separate processing of visual text and background ensures that the model retains the multilingual translation capability while maintaining the integrity of the background, thereby helps mitigate error propagation and improves visual quality.

The main contributions of this paper are as follows:

- In order to closely resemble practical conditions, we explore Practical In-Image Multilingual Machine Translation (IIMMT). The challenge of the task lies in the lack of publicly available dataset, and the model needs to handle complex real-world images with multilingual translation directions.
- To mitigate the lack of real-world dataset, we present the first annotated dataset PRIM,

which contains real-world captured images with multilingual translation directions.

- We propose a novel model VisTrans, the first end-to-end model designed for practical conditions. By handling the visual text and background information of the images separately, our model is able to generate multilingual target images with integrity backgrounds.

2 Related Work

In-Image Machine Translation. The end-to-end IIMT research mainly focuses on simple scenarios with synthetic datasets. Mansimov et al. (2020) and Tian et al. (2023) conduct on a dataset containing one-line black texts within a white background. Lan et al. (2024) further extend the dataset, including multiple lines of black text with random rotating in a solid-colored background.

Another type of research in IIMT does not focus on end-to-end models but instead utilizes existing pre-trained models to construct a more effective cascade model. Qian et al. (2024) propose AnyTrans, an advanced pipeline that applies Qwen (Bai et al., 2023) instead of the NMT model, AnyText (Tuo et al., 2024) alternating Removing and Rendering procedures. Although AnyTrans utilizes large pre-trained models, it is still constrained by the cascade process, which poses a risk of error propagation. It is also limited by the capability of the text editing model AnyText, making it hard to generate target images containing lengthy text.

Text-Image Translation. Text-Image Translation (TIT) aims to translate the text in the image into the target text. Research on TIT can be categorized into two main types: translating sentences within images (Lan et al., 2023; Zhu et al., 2023; Ma et al., 2024; Li et al., 2025a), and translating paragraph texts in images with layout information (Liang et al., 2024; Zhang et al., 2025b; Liang et al., 2025b,a; Zhang et al., 2025a).

Two-pass Model. The two-pass model is initially used for end-to-end Speech-to-Speech Translation (S2ST) task (Jia et al., 2022a; Inaguma et al., 2023), that the model firstly generate the target text with the source speech (1-pass), and the hidden representation of the target text is then used to generate the target spectrogram or the discrete code (2-pass). Fang et al. (2024) investigate the vocabulary mismatch issue between the two decoders in the two-pass model, which makes it challenging to utilize

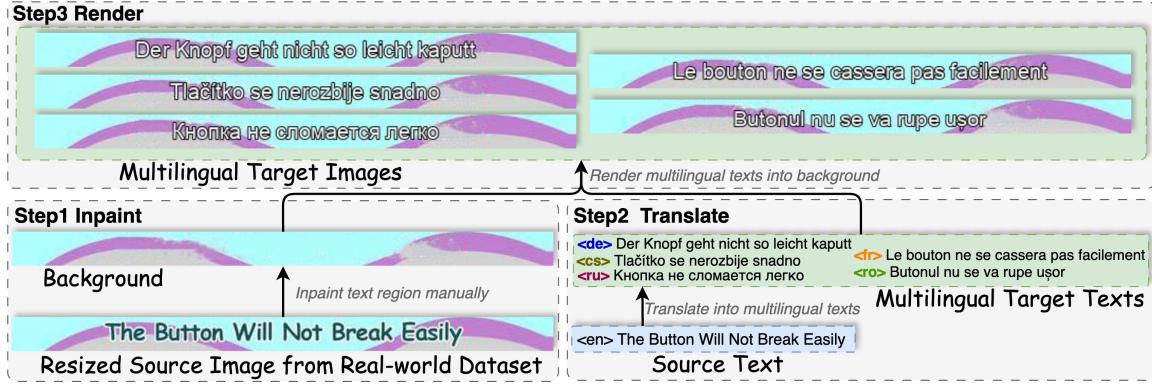


Figure 2: Annotation procedure of PRIM. The first step is inpainting the text region of the source image manually, obtaining the background. The second step is translating the source text into multilingual target texts. The third step is rendering the multilingual target texts into the background to get multilingual target images.

existing Speech-to-Text Translation (S2TT) and Text-to-Speech (TTS) models, and propose a CTC (Graves et al., 2006) based vocabulary adaptor, and Yao et al. (2024) explore translation robustness under different vocabulary sizes.

3 Data Construction

PRIM. To address the lack of publicly available real-world IIMMT benchmark, we annotate a test set containing real-world source images with one-line texts and annotated target images, namely **Practical In-Image Multilingual Machine Translation** (PRIM). The construction procedure is shown in Figure 2. To better align with real-world scenarios, PRIM follows the design paradigm commonly adopted in S2ST (Fang et al., 2023, 2024; Zhang et al., 2024b), such as CVSS (Jia et al., 2022b), which uses real-world human speech as source input and synthetic target speech.

Recognizing the importance of realism on the source side, we adopt the same approach in PRIM, using real-world source images with annotated target images. We take images collected from the real world by Ma et al. (2024) and Li et al. (2025a) as source images, where both datasets are originally designed for TIT task. Ma et al. (2024) capture images from video subtitles, and the English texts in the images are represented with different fonts, sizes, and positions. Li et al. (2025a) crawl textual images from websites and most of which are e-commerce platform advertising boards. Unlike the video subtitle scenarios, where the source text may be accessible through metadata, advertising boards typically do not provide such textual information. This scenario further emphasizes the necessity of the IIMT task, which aims to directly translate the

input image into a target-language image without relying on the availability of source texts.

We crop the text regions of images in the above datasets with a size of $\text{Height} \times \text{Width} = 32 \times 512$ from the dataset and primarily select images with non-solid color backgrounds. After source images are fully collected, the text areas are inpainting manually by the raster graphics editor software, obtaining the corresponding background of each source image. Although PRIM only contains one-line text images captured from real world and does not fully reflect the real-world conditions, collecting and annotating such data remains highly challenging (Lan et al., 2024). Compared with existing public datasets, PRIM offers a closer approximation to real-world conditions.

We adopt a multilingual translation setting, focusing on one-to-many translation, which includes the following 5 translation directions, English-Russian (En-Ru), English-French (En-Fr), English-Romanian (En-Ro), English-German (En-De), and English-Czech (En-Cs). The source texts are translated to multilingual target texts by GPT-4¹ and Google Translate, which are two commonly used methods to annotate translation texts (Li et al., 2025a; Liang et al., 2024). The multilingual translated texts are then rendered into the background, to build the target images. By manually annotating target images, automatic evaluation metrics such as FID can be used to assess the visual quality by comparing the target images with the generated images (Tuo et al., 2024).

We perform inspections on PRIM, including the translation quality and integrity of image, and more

¹gpt-4-turbo with prompt “Translate the following sentence from English to {target_language}: {source_text}”

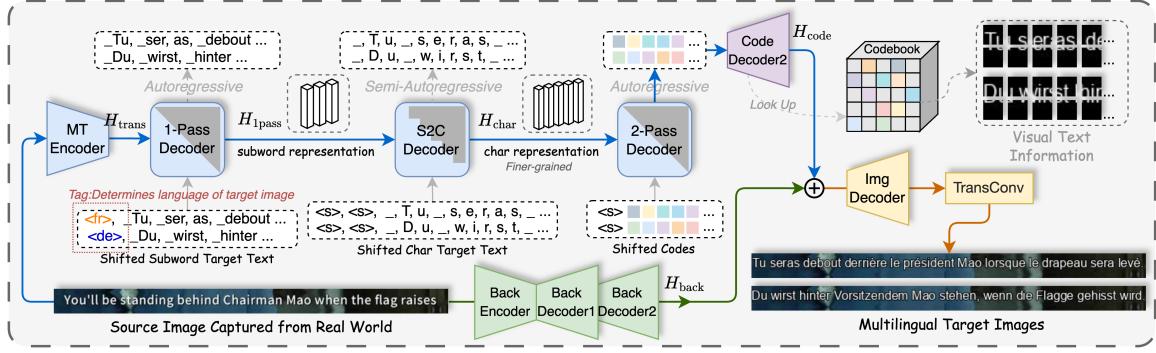


Figure 3: Architecture of VisTrans. The trapezoid represents Vision Transformer (ViT) (Dosovitskiy et al., 2021), while the rectangle represents Transformer Decoder (Vaswani et al., 2017). More specifically, the rectangle with an upper triangular mask indicates an autoregressive decoder, whereas a staircase-like mask represents a semi-autoregressive decoder.

details and evaluation results of PRIM are introduced in Appendix A.

Training Set. Collecting and annotating large-scale IIMMT datasets from reality for training models is challenging, as the IIMMT dataset requires both source images and target images with parallel texts. Such a challenge also appears in the training of early OCR models, and one solution is to synthesize a large number of images using various fonts and backgrounds to simulate real-world scenarios (Jaderberg et al., 2014). Following the above method, we use TRDG toolkit² to render source texts with various styles, and the target images are rendered target texts using Arial font with different font sizes by PIL library. The texts are sourced from the MTed dataset (Duh, 2018), and the backgrounds of the source and target images are extracted from frames of the corresponding video based on the timestamps of the text. Since image generation tasks typically use fixed input and output dimensions (Esser et al., 2021; Rombach et al., 2022; Zhang et al., 2024a), we extract the bottom part of the aforementioned frames with a size of Height \times Width = 32 \times 512.

The generated images are filtered to ensure that the source and target texts are fully rendered into the images. More details of the training set are introduced in Appendix B.

Explanation of images with single-line texts. The images in our dataset contain single-line text with various font styles, sizes and positions, since the single-line text represents a fundamental and frequently encountered case in practical applica-

tions. Prior research on TIT, such as PEIT (Zhu et al., 2023) and METIMT (Ma et al., 2024), typically uses single-line source images as input. In particular, the constructed ECOIT dataset contains a large collection of single-line text images captured from an e-commerce platform, indicating that such images are present at scale in real-world scenarios.

4 Method

We design the VisTrans model which is shown in Figure 3. We first introduce the overall architecture and inference process of the model, where the output target image is generated given an input source image. Then, we describe the training methodology of the model.

4.1 Architecture

The source image $I_{\text{src}} \in \mathbb{R}^{H \times W \times C}$ is used as input for two sub-modules. Firstly, it is encoded by a set of Vision Transformer (ViT) (Dosovitskiy et al., 2021), BackEncoder, BackDecoder1, and BackDecoder2, obtaining the output representation $H_{\text{back}} \in \mathbb{R}^{\frac{HW}{P^2} \times D}$, where P and D are the patch size and dimension of the ViT. Secondly, it is encoded into representation $H_{\text{trans}} \in \mathbb{R}^{\frac{HW}{P^2} \times D}$ by another ViT, MT Encoder.

The 1-Pass Decoder is used to generate the target get translation text, and its hidden representation $H_{1\text{pass}} \in \mathbb{R}^{L_s \times D}$ where L_s and D are the lengths of subword target text and dimension of the 1-Pass Decoder, serving as input for the subsequent module. Specifically, the 1-Pass Decoder takes the embeddings of the shifted target text, which is prefixed with a language tag (e.g., “<de>” for German, “<fr>” for French), along with H_{trans} as input, and

²<https://github.com/Belval/TextRecognitionDataGenerator>

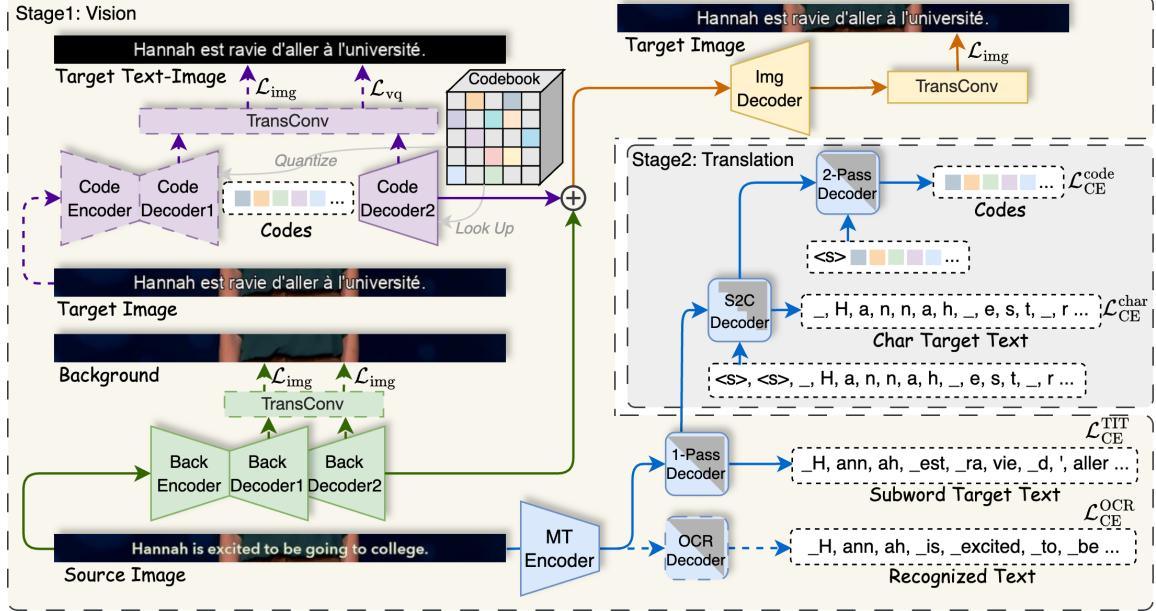


Figure 4: The two stages training of VisTrans. The modules and arrows with dashed lines represent auxiliary modules and tasks introduced during training, which will not be used during model inference.

then autoregressively generates the target language text and the hidden representation $H_{1\text{pass}}$.

The hidden representation $H_{1\text{pass}}$ is used as input of a Subword-to-Char (S2C) Decoder, which aims to transform the subword-level representation $H_{1\text{pass}}$ into the char-level representation $H_{\text{char}} \in \mathbb{R}^{L_c \times D}$ where L_c is the length of char target text. The S2C Decoder is implemented with a Semi-Autoregressive (SAT) decoder (Wang et al., 2018), which generates a group of K tokens at each step, rather than producing a single token like an autoregressive (AT) decoder. Compared with the AT decoder, the SAT decoder has a certain performance degradation while achieving higher decoding efficiency. The architectural difference between SAT and AT decoders lies in the design of the attention mask. AT typically employs a strict causal mask which visually appears as an upper triangle, whereas SAT utilizes a relaxed causal mask which visually appears as a staircase.

The char-level representation H_{char} is used to generate the code sequence with the 2-Pass Decoder autoregressively, and each code in the sequence is looked up with a codebook, converted to a vector sequence H_{code} , which is added with the output of BackDecoder2 H_{back} , to generate the target image with ImgDecoder and Transposed Convolution.

The reason for using the S2C Decoder to convert subword-level representation into char-level repre-

sentation is to align with the representations in the codebook. The designed codebook stores the visual text information of the target image, where each code corresponds to a small patch (e.g., 16×16) of the image. Therefore, a single code is usually insufficient to fully capture the visual characteristics of the region corresponding to a subword. In other words, the granularity of subword representation is too large compared to code representation, which requires transforming the subword into a finer-grained representation, to reduce the granularity gap between it and the code representation.

4.2 Training

We employ a multi-task learning strategy along with auxiliary modules to train our model, and the training process includes two stages, as illustrated in Figure 4. The solid-lined modules are required during inference, while the dashed-lined modules are auxiliary components used only for training. The auxiliary modules aim to generate background, text-image (images containing visual texts with an empty background), and recognized text, which are not required during inference. The following is an introduction to the three loss functions used in the training process.

The image reconstruction loss with perceptual loss (Zhang et al., 2018) is used to train the image generation task, described as:

$$\mathcal{L}_{\text{img}}(y, \hat{y}) = \|y - \hat{y}\|^2 + \lambda_p \mathcal{L}_{\text{Perceptual}}(y, \hat{y}), \quad (1)$$

where y is the generated image of the model and \hat{y} is the ground truth image. λ_p is loss weight, and it is set to 0.1 in our experiments.

The vector quantization (vq) loss is used to train the codebook, formally as:

$$\mathcal{L}_{\text{vq}}(y, \hat{y}) = \|y - \hat{y}\|^2 + \lambda_p \mathcal{L}_{\text{Perceptual}}(y, \hat{y}) + \|\text{sg}[z_q] - E(x)\|_2^2, \quad (2)$$

where y is the generated image of the model and \hat{y} is the ground truth image. $\|\text{sg}[z_q] - E(x)\|_2^2$ is the commitment loss with stop-gradient operation $\text{sg}[\cdot]$, and z_q is the vector obtained by quantization using the codebook, while $E(x)$ is the encoded feature of image x , which serves as the input to the quantization layer. λ_p is loss weight, and it is set to 0.1 in our experiments.

The cross-entropy loss \mathcal{L}_{CE} is used to train the sequence generation task, such as the generation of the target text and code sequence, and the cross entropy loss is applied label smoothing with 0.1.

Stage 1: Vision. In this stage, the model is trained in two parallel branches simultaneously. The first branch is primarily designed to learn the visual text information in the target image. The target image is used as input of the CodeEncoder and CodeDecoder1, obtaining the representation $E(x)$, which serves as the input of a codebook.

Specifically, the codebook q contains V learnable vectors $\{e_1, e_2, \dots, e_V\}$, and each encoded feature x_i is quantized by the nearest vector in q , obtaining z_i . Formally as:

$$z_i = q(E(x_i)) = \arg \min_{e_k \in q} \|E(x_i) - e_k\|_2. \quad (3)$$

With the quantization of the codebook, the target image is converted into a code sequence and the corresponding vector sequence. The vector sequence is further fed into the CodeDecoder2 to obtain the representation H_{code} .

To align the learnable vectors in the codebook with the visual text in the image, transposed convolutions are applied to generate output images $I_{\text{code}1}$ and $I_{\text{code}2}$ based on the hidden representations of CodeDecoder1 and CodeDecoder2, which are used to train the reconstruction of the target text-image $I_{\text{tgt-text}}$. The loss function of the first branch is described as follows:

$$\mathcal{L}_{\text{b1}} = \mathcal{L}_{\text{img}}(I_{\text{code}1}, I_{\text{tgt-text}}) + \mathcal{L}_{\text{vq}}(I_{\text{code}2}, I_{\text{tgt-text}}). \quad (4)$$

The second branch is mainly used to learn the background information in the source image. The hidden representation of the background H_{back} is obtained by encoding the source image using a set of BackEncoder, BackDecoder1, and BackDecoder2. Similar to the first branch, the hidden representations of BackDecoder1 and BackDecoder2 are used to generate the output images $I_{\text{back}1}$ and $I_{\text{back}2}$ with transposed convolutions, aiming to reconstruct the background I_{back} .

In addition, the second branch also learns the information required for the training in the subsequent translation stage, an MT Encoder and a 1-Pass Decoder are used to generate the multilingual target texts (TIT task), with the OCR Decoder to recognize the texts in source images for auxiliary. The two tasks are trained with cross-entropy loss, denoted as $\mathcal{L}_{\text{CE}}^{\text{TIT}}$ and $\mathcal{L}_{\text{CE}}^{\text{OCR}}$. The loss function of the second branch is described as follows:

$$\begin{aligned} \mathcal{L}_{\text{b2}} = & \mathcal{L}_{\text{img}}(I_{\text{back}1}, I_{\text{back}}) + \mathcal{L}_{\text{img}}(I_{\text{back}2}, I_{\text{back}}) \\ & + \mathcal{L}_{\text{CE}}^{\text{TIT}} + \mathcal{L}_{\text{CE}}^{\text{OCR}}. \end{aligned} \quad (5)$$

The final output representations of two branches, H_{code} and H_{back} are added, to generate the image I_{img} by the ImgDecoder and Transposed Convolution, aiming to reconstruct the target image I_{tgt} . The total loss function of stage 1 is the sum of all the loss functions mentioned above, expressed as:

$$\mathcal{L}_{\text{stage1}} = \mathcal{L}_{\text{b1}} + \mathcal{L}_{\text{b2}} + \mathcal{L}_{\text{img}}(I_{\text{img}}, I_{\text{tgt}}). \quad (6)$$

Stage 2: Translation. The training in stage 1 is divided into two branches, which obtain the visual text information of the target image by the quantization of the codebook, and the background information of the source image. The final output image can be generated with the addition of the two types of information. The background information can be obtained directly from the source image, but the code sequence corresponding to the visual text information cannot be directly obtained.

Therefore, the training objective of stage 2 is to generate the code sequence for the target image based on the representations from the pre-trained MT Encoder and 1-Pass Decoder in stage 1. Specifically, the hidden representation of the 1-Pass Decoder and the embedding of the shifted char target text is inputted into the S2C Decoder, transforming the subword-level representation of target text into the char-level representation. The char-level

Systems	BLEU \uparrow / COMET \uparrow						FID \downarrow
	En-De	En-Fr	En-Cs	En-Ru	En-Ro	Avg.	Avg.
Golden	74.2 / 89.6	73.7 / 86.9	73.3 / 89.7	47.1 / 84.4	65.1 / 75.3	66.7 / 85.2	0.00
<i>pre-trained cascade models</i>							
EasyOCR-NLLB-Render	24.7 / 58.4	27.0 / 60.4	24.0 / 67.8	14.1 / 60.8	25.2 / 66.0	23.0 / 62.7	100.2
QwenVL-Render	19.8 / 56.7	23.3 / 56.9	14.5 / 61.2	11.3 / 56.8	16.7 / 60.4	17.1 / 58.4	102.2
AnyTrans	0.1 / 29.8	0.1 / 30.6	0.0 / 30.9	0.1 / 32.4	0.0 / 31.1	0.1 / 31.0	204.1
<i>cascade models</i>							
PARSeq-mTransformer-Render	9.5 / 41.7	13.8 / 46.9	7.7 / 43.9	5.5 / 48.1	12.8 / 53.5	9.9 / 46.8	103.8
PEIT-Render	<u>10.4</u> / 45.1	<u>14.0</u> / 48.1	7.9 / 46.2	5.3 / 47.7	14.2 / 52.9	<u>10.4</u> / 48.0	101.4
<i>end-to-end models</i>							
TranslatotronV	1.7 / 34.3	1.9 / 30.2	1.1 / 30.5	0.9 / 32.0	1.3 / 33.9	1.4 / 32.2	<u>69.1</u>
VisTrans (ours)	12.6 / <u>44.4</u>	17.0 / 49.4	5.9 / 41.8	7.2 / 49.4	<u>13.9</u> / 50.2	11.3 / <u>47.0</u>	28.8

Table 1: Experimental results of different systems. Metrics include translation quality (BLEU, COMET) and visual effect (FID), and “Avg.” represents the average across all translation directions. \uparrow or \downarrow indicates higher or lower values are better. The **best** and second-best performance are in bold and underline, respectively.

representation, along with the embedding of the shifted code sequence, is further used in the 2-Pass Decoder to generate the code sequence. Both tasks are trained using cross-entropy loss, denoted as $\mathcal{L}_{\text{CE}}^{\text{char}}, \mathcal{L}_{\text{CE}}^{\text{code}}$. The complete loss function of stage 2 is the sum of them, expressed as:

$$\mathcal{L}_{\text{stage2}} = \mathcal{L}_{\text{CE}}^{\text{char}} + \mathcal{L}_{\text{CE}}^{\text{code}}. \quad (7)$$

5 Experiments

5.1 Metrics

The evaluation of IIMT requires to recognize the texts in the output images (Tian et al., 2023, 2025; Lan et al., 2024; Qian et al., 2024), and we use EasyOCR³, a widely used OCR toolkit that supports multilingual text recognition, to recognize the generated images of each system. Based on the OCR recognition results and the reference texts, we calculate BLEU (Papineni et al., 2002) and COMET (Rei et al., 2020) to assess the translation quality. The BLEU is calculated with SacreBLEU⁴, and COMET is calculated with Unbabel-COMET⁵ by wmt22-comet-da model.

To evaluate the visual effect of the output images automatically and objectively, we calculate the Fréchet Inception Distance (FID) between the generated images and the reference images. The FID correlates well with human judgment of visual quality, and it is a widely used metric in image generation tasks (Esser et al., 2021; Rombach et al.,

2022; Peebles and Xie, 2023; Tuo et al., 2024). We employ pytorch-fid⁶ to calculate the FID.

5.2 Experimental Settings

We use PRIM mentioned in Section 3 to evaluate the systems, including pre-trained cascade models, cascade models, and end-to-end models. The following is a brief introduction to each system.

Golden. Since evaluating IIMMT models requires recognizing the texts in the output images with the OCR model, which could introduce errors, negatively impacting the evaluation of translation quality. We use the same OCR model to evaluate the golden reference target images in the test set, and these results represent the theoretical upper bound for all system.

EasyOCR-NLLB-Render. A cascade system includes pre-trained EasyOCR, NLLB-3.3B (NLLB Team et al., 2022), and text render. The text render first requires removing the texts in the source images, and we replace each text area detected by EasyOCR with the mean color of the region. Then the translated texts are rendered in Arial font. Unless otherwise specified, this render method is also used in other cascade models, which ensures the integrity of the images as much as possible.

QwenVL-Render. A cascade system includes Qwen2.5VL-7B (Bai et al., 2025) with prompt “*Translate the text in the image to {target_language}, and only output the translated text*”, and text render.

³<https://github.com/JaidedAI/EasyOCR>

⁴<https://github.com/mjpost/sacrebleu>

⁵<https://github.com/Unbabel/COMET>

⁶<https://github.com/mseitzer/pytorch-fid>

Input Images	Systems	Output Images
	Cascade	große Fassungsvermögen- Wasser für
	VisTrans	Glückliche Kapazität, für einen Tag Wasser trinken ,
	Cascade	Idéal pour les déplacements;
	VisTrans	Idéal pour voyager,

Table 2: Comparison of cascade model (EasyOCR-NLLB-Render) and our end-to-end VisTrans. The issues of the cascade system output images lie in that the background of the images is damaged, negatively affecting the visual quality; and the texts are not fully rendered, decreasing the translation quality.

AnyTrans. An advanced cascade model (Qian et al., 2024) with pre-trained PPOCR, Qwen1.5-7B, and AnyText. More explanation of AnyTrans is introduced in Appendix F.

PARSeq-mTransformer-Render. A cascade model contains SOTA OCR model PARSeq (Bautista and Atienza, 2022), a commonly used multilingual machine translation model mTransformer (Johnson et al., 2017), and text render.

PEIT-Render. A cascade model contains the SOTA TIT model PEIT (Zhu et al., 2023), and text render.

TranslatotronV. An end-to-end IIMT model (Lan et al., 2024) with the architecture of ViT-VQGAN (Yu et al., 2022) and multi-task learning.

VisTrans. Our end-to-end IIMT model is introduced in Section 4. Detailed implementation is introduced in Appendix D.

5.3 Main Results

The experimental results are shown in Table 1.

Translation Quality. The EasyOCR-NLLB-Render achieves the best performance, which benefits from the strong translation performance of NLLB. Except for pre-trained models, our VisTrans and PEIT-Render achieve better performance compared with other baselines.

Visual Effect. Although a more complex rendering method is applied for the cascade models (replacing text regions with average pixels instead of directly removing), the visual quality still remains poor. The end-to-end models achieve better visual quality due to the incorporation of image generation modules. Compared to TranslatotronV, our VisTrans processes visual text and background information separately, leading to improved visual performance.

6 Analysis

6.1 Ablation Study: Does S2C Decoder contribute to translation quality?

The core idea of VisTrans is to handle the background and visual text separately, making all components except the S2C Decoder essential. To investigate the different performance with the S2C Decoder, we conduct an ablation study, by replacing it with other type of decoder. The experimental results are shown in Table 3.

S2C Decoder	Avg. BLEU \uparrow	Speedup \uparrow
None	5.27	1.00 \times
CTC	6.06	0.96 \times
AT	11.87	0.74 \times
SAT (K=2)	11.32	0.88 \times
SAT (K=4)	8.97	0.92 \times
SAT (K=6)	7.16	0.93 \times

Table 3: Average BLEU and Speedup on different S2C Decoder.

Different types of S2C Decoder have an impact on translation quality. Specifically, by removing the S2C Decoder (None), the translation quality decreases significantly. The S2C Decoder with CTC is trained by upsampling the hidden representation from the 1-Pass Decoder, leading to an improvement compared to none S2C Decoder. The best translation quality is achieved using AT for the S2C Decoder, but the autoregressive decoding results in slower inference speed. As K increases, SAT yields faster inference but lower translation quality. We adopt $K = 2$ in the SAT S2C Decoder to balance quality and speed.

6.2 Case Study: Why not render texts into images directly?

Cascade models with text render have certain advantages: they leverage well-established text-based

translation models, and the techniques for rendering texts into images are mature, ensuring clear and readable fonts.

However, as illustrated in Table 2, the cascade model (EasyOCR-NLLB-Render) causes noticeable damage to the output images, which is also reflected in the FID metric in Table 1. Moreover, when render the translated text into the image, the text length is constrained by the image size, preventing complete rendering and leading to a decline in translation quality. Therefore, the error propagation in cascade models is not limited to the OCR-NMT process, and there still exists the issue of incomplete text rendering in the target image, which is another form of error propagation. Since different font sizes are used for rendering the target images of the training set, our VisTrans can automatically adjust the font size in the output image, ensuring text completeness. More output images of our VisTrans are shown in Appendix E.

6.3 Robustness Study: Does VisTrans fit for images containing multi-line texts?

To evaluate the ability of the VisTrans model translating multi-line text images, we conduct experiments on the IIMT30k dataset (Tian et al., 2025), which consists of synthetic images, but features complex backgrounds, diverse font styles, and a mix of single-line and multi-line texts (e.g., sentences split across two lines).

Systems	De-En		En-De	
	Valid	Test	Valid	Test
DebackX	10.8	8.6	9.5	6.9
VisTrans (ours)	14.7	12.3	16.5	12.2

Table 4: BLEU score on IIMT30k dataset.

Experimental results in Table 4 demonstrate that VisTrans is capable of handling images containing multi-line text, indicating that the model can generalize to more complex text layouts when appropriately trained.

7 Conclusion

In this paper, we address the limitations of IIMT in real-world scenarios by exploring Practical In-Image Multilingual Machine Translation (IIMMT), and first annotate a dataset PRIM containing real-world images with multilingual translation directions. To tackle the challenge of practical conditions in the PRIM dataset, we propose an end-to-

end model VisTrans, which handles the visual text and background information separately. Experimental results show that our model retrains the multilingual translation capability while maintaining the integrity of the background, obtaining a better translation quality and visual effect compared to other models.

Limitations

While we explore IIMMT by annotating PRIM dataset, and propose an end-to-end model VisTrans, this paper has certain limitations.

Our VisTrans is trained on large amount of training data, and is adopted a two-stage training with multi-task learning strategy, leading to the high computational resource costs and hardware requirements. The images are quantized by a codebook, obtaining the code sequence. We only conduct experiments with the most basic codebook and decoder, lacking the investigation on the use of more advanced quantization techniques or decoders that better support long-sequence modeling.

Ethics Statement

We manually annotate PRIM dataset containing real-world images, and the data has been carefully selected to avoid any form of offensive or biased content. We take ethical considerations seriously and ensure that the data used in this study are conducted in a responsible and ethical manner.

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A Details of PRIM

Our PRIM includes 5 translation directions (En-Ru, En-Fr, En-Ro, En-De, En-Cs), and each direction contains 340 images. Each source image corresponds to 2 reference translation images, which texts are rendered based on translations obtained from GPT4 and Google Translate respectively. In the experiments, BLEU is evaluated using 2 references, while the computation of COMET and FID is averaging the results from both references.

Data quality of benchmark is a critical issue (Li et al., 2025b; Lu et al., 2025; Zeng et al., 2025), therefore we additionally perform evaluation on the PRIM benchmark. Following Yu et al. (2025), the translation quality is evaluated by reference-free wmt22-cometkiwi-da⁷. The evaluation scores for

⁷<https://huggingface.co/Unbabel/wmt22-cometkiwi-da>

the PRIM dataset across different translation directions, and the human-annotated MTed dev and test sets are used as comparison are shown in Table 5. Evaluation results show that the translation quality of the PRIM dataset matches the level of human annotation.

PRIM only includes source images, target images, source texts, and target texts for evaluation. As shown in Figure 5, the real-world source images demonstrate significant diversity in visual characteristics such as various fonts, diverse text positions.

B Details of Training Set

The parallel texts used to construct the training set are sourced from the MTed dataset (Duh, 2018), which contains transcription texts from Ted talk videos along with multilingual translation results.

Due to texts in MTed dataset are merged, resulting in excessive length unsuitable for rendering into images, we do not directly use the text from the dataset. Instead, we extract the unmerged texts, along with the corresponding video-related information and transcript timestamps from the original XML documents⁸. The source and target language texts are filtered based on timestamps, retaining only parallel texts that can be aligned.

We construct a validation set along with the training set, which is used to evaluate the performance of the model during training. The statistical data for each translation direction is shown in Table 6.

Moreover, due to the length differences between source and target language texts with same meaning, the space occupied in the images are also varies. Therefore, the target images adjusts the font size according to the text length. Compared to existing publicly available training data, our dataset offers the most diverse styles and translation directions.

Figure 6 shows samples of the training set, including source images, backgrounds, target images, target text-images, source texts, and target text, which enable the two-stage training of our VisTrans model.

C Formal Representation of Mask for SAT

In AT, attention is strictly unidirectional, while the SAT allows bidirectional attention among tokens

⁸The XML documents are obtained from <https://wit3.fbk.eu/>.

within the same group. The relaxed causal mask $M \in \mathbb{R}^{n \times n}$ for the sequence length n and group size K can be formalized as follows:

$$M[i][j] = \begin{cases} 1, & \text{if } j < (\lceil \frac{i-1}{K} \rceil + 1) \times K \\ 0, & \text{other} \end{cases} \quad (8)$$

D Implementation of VisTrans

Our VisTrans is trained by Huggingface Accelerate framework⁹ (Gugger et al., 2022) with fp16 mixed precision on 4 TITAN RTX GPUs. The implementation of Vision Transformer in VisTrans is referred to timm¹⁰, and the codebook is implemented based on vector-quantize-pytorch¹¹. The texts are tokenized by Sentencepiece¹². The perceptual loss is implemented by PerceptualSimilarity¹³. Both of two training stages use AdamW optimizer (Loshchilov and Hutter, 2019) with inverse square root learning rate schedule.

The hyperparameters of VisTrans are shown in Table 7, and we choose these parameters based on the performance of model on the validation set.

E More Outputs of VisTrans

More outputs of our VisTrans for different translation directions are shown in Figure 7.

F Explanation of the AnyTrans

We implement the AnyTrans by PPOCR¹⁴, Qwen1.5-7B (Bai et al., 2023) and AnyText (Tuo et al., 2024). The PPOCR firstly detects the text regions and recognizes source texts. Then, the source texts are translated by Qwen1.5-7B with system prompt “*You are a multilingual translation assistant, and only need to output the translated text.*”, and each source text is add the prompt “*Translate the following text from English to {target_language}: {source_text}*”.

Since AnyText does not support text editing of images with size 32×512 , therefore we resize the images of the test set into 64×512 . The AnyText requires the original image, the image with text regions removed and the texts prompt as inputs.

⁹<https://github.com/huggingface/accelerate>

¹⁰<https://github.com/huggingface/pytorch-image-models>

¹¹<https://github.com/lucidrains/vector-quantize-pytorch>

¹²<https://github.com/google/sentencepiece>

¹³<https://github.com/richzhang/PerceptualSimilarity>

¹⁴<https://github.com/PaddlePaddle/PaddleOCR>

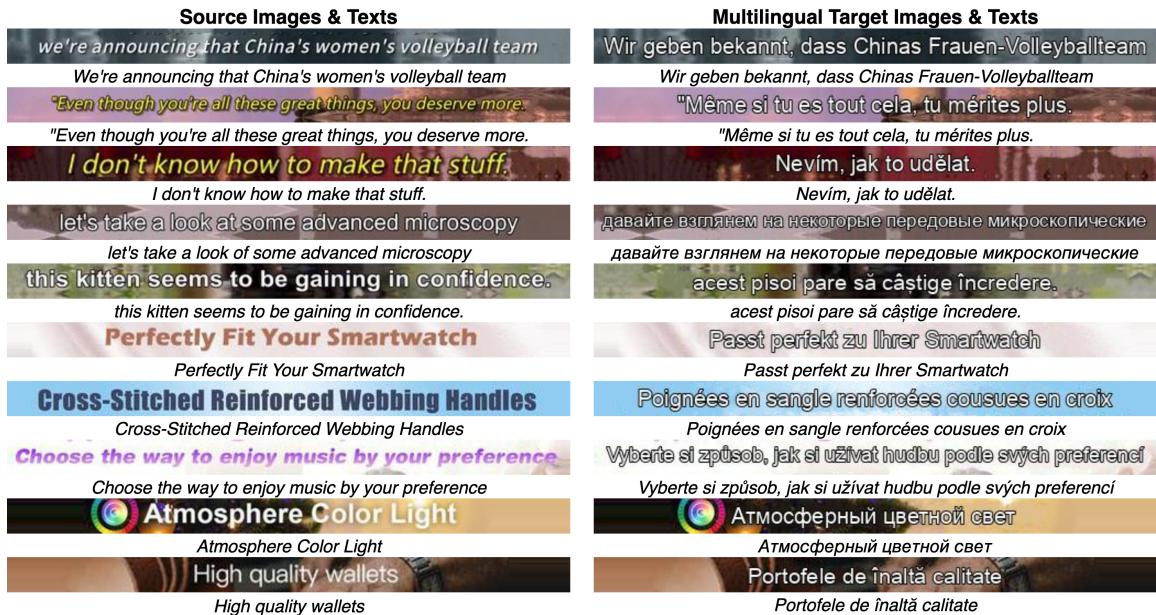


Figure 5: Samples from PRIM, which includes source images, source texts, multilingual target images, and multilingual target texts. The source images are captured from real world, with real-world backgrounds, various fonts, diverse text positions, and 5 translation directions.



Figure 6: Samples from our training set. Due to the auxiliary training tasks in the training process, the training set includes not only source images, source texts, multilingual target images, multilingual target texts, but also backgrounds and multilingual target text-images.

	PRIM-Google	PRIM-GPT4	MTed dev (human)	MTed test (human)
En-De	0.8271	0.8246	0.8075	0.8102
En-Fr	0.8386	0.8359	0.8269	0.8188
En-Cs	0.8388	0.8397	0.8122	0.8102
En-Ru	0.8310	0.8308	0.7901	0.7859
En-Ro	0.8392	0.8459	0.8280	0.8250

Table 5: Comparison of translation quality between the PRIM dataset and human-annotated datasets, indicating that the translation quality of the PRIM dataset matches the level of human annotation.



Figure 7: Multilingual output images of VisTrans on PRIM. Our model maintains the integrity of the image background while ensuring multilingual translation performance.

Direction	# Training	# Validation
En-Ru	1,629,790	3,404
En-Fr	1,594,303	3,434
En-Ro	1,507,993	3,544
En-De	1,418,009	3,424
En-Cs	848,894	3,555

Table 6: Statistic of training set.

The text regions in the image are removed based on the regions detected by PPOCR, with regions expanded by a certain proportion.

However, we find that AnyText cannot generate good text editing results in our test set, due to the lengthy text in the images, which occupy a large amount of space. Although AnyTrans exhibits strong performance, it is limited by the performance of AnyText, and it is not well-suited for our test set. We present some outputs from the AnyTrans in Figure 8.



Figure 8: Outputs from AnyTrans (Qian et al., 2024). The prompt is the translation result of recognized text by PPOCR, based on Qwen-1.5 7B. We find that AnyTrans is not well-suited for our test set, which is limited by the text editing capability of lengthy text in the image.

	patch_size	16
BackEncoder	d_model	512
BackDecoder1	d_ff	2,048
BackDecoder2	heads	8
	1	6
	patch_size	16
CodeEncoder	d_model	512
CodeDecoder1	d_ff	2,048
CodeDecoder2	heads	8
	1	6
Codebook	dim	32
	size	8,192
	patch_size	16
	d_model	512
ImgDecoder	d_ff	2,048
	heads	8
	1	6
	patch_size	8
	d_model	512
MTEncoder	d_ff	2,048
	heads	8
	1	6
	d_model	512
OCR Decoder	d_ff	2,048
1-Pass Decoder	heads	8
	1	6
	vocabulary	35,000
	d_model	512
	d_ff	2,048
S2C Decoder	heads	8
	1	3
	K	2
	vocabulary	176
	d_model	512
Code Decoder	d_ff	2,048
	heads	8
	1	6

Table 7: Hyperparameters of VisTrans.